

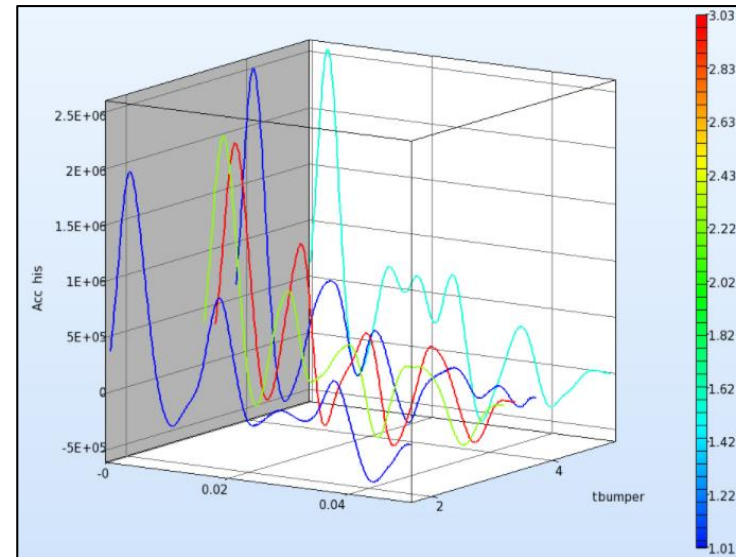
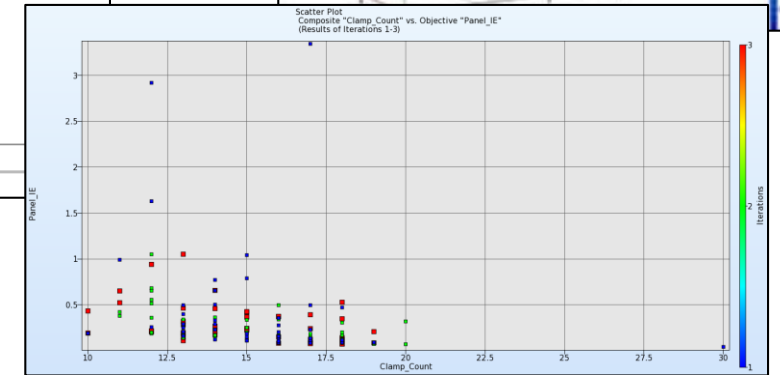
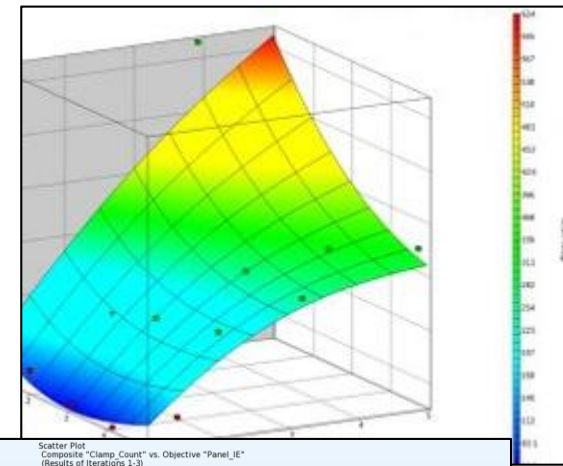
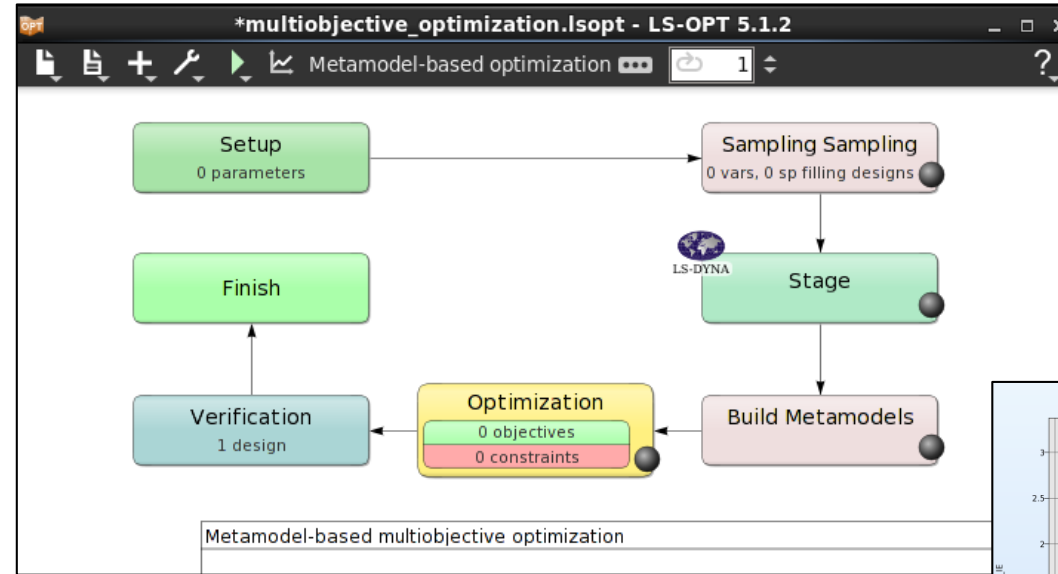
Cycling | Digital Doping with LS-OPT

24th January 2018

Ben Crone

LS-OPT

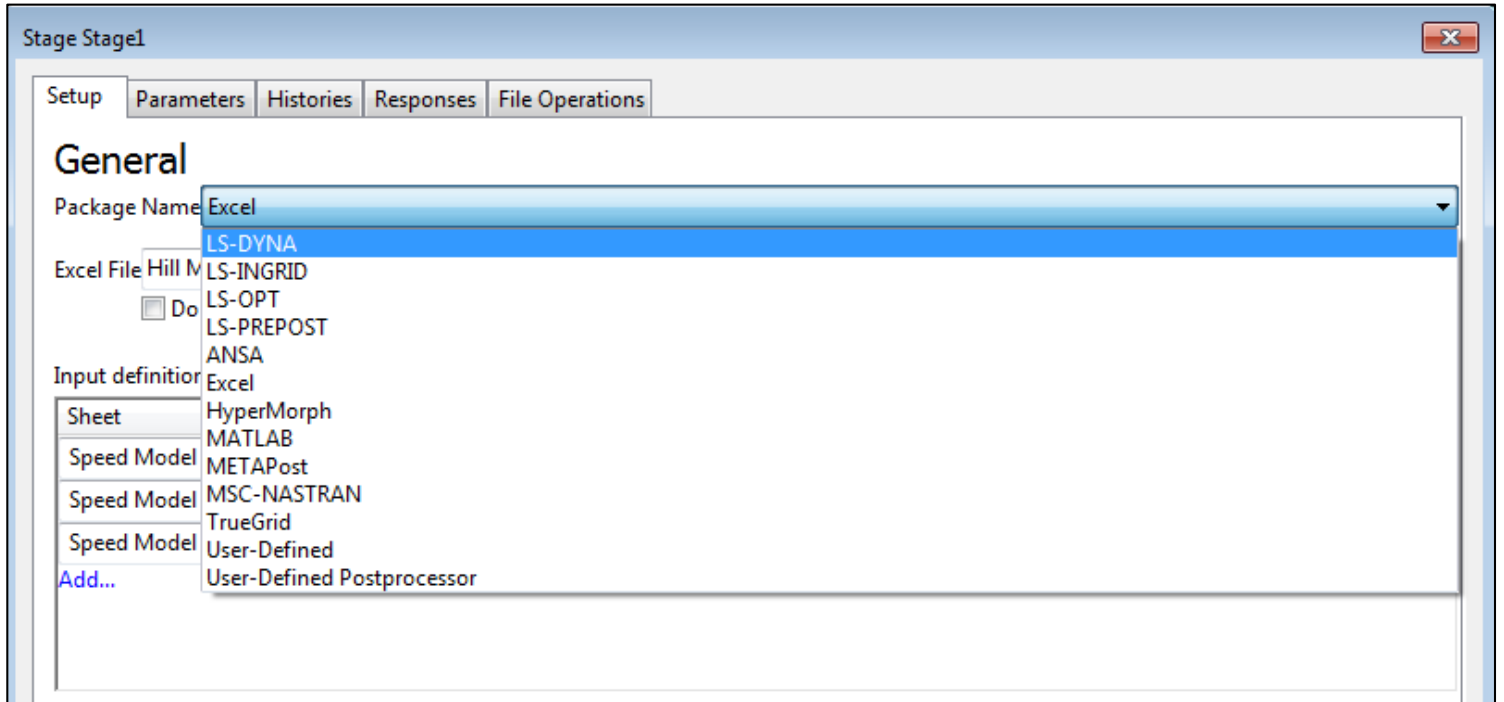
- Optimisation.
- System identification.
- DOE.
- Curve matching.
- Robustness.
- Sensitivity studies.



		Variables				Responses		
		t_hood	t_bumper	Acc_max	Mass	Intru2	Intru1	HIC
Responses	t_hood		0.00	-0.60	0.97	0.96	-0.91	0.83
	t_bumper			-0.80	0.23	0.28	-0.42	-0.55
	Acc_max				-0.77	-0.80	0.88	-0.06
	Mass					1.00	-0.98	0.69
	Intru2						-0.99	0.65
	Intru1							-0.52
	HIC							
		Intrusion						

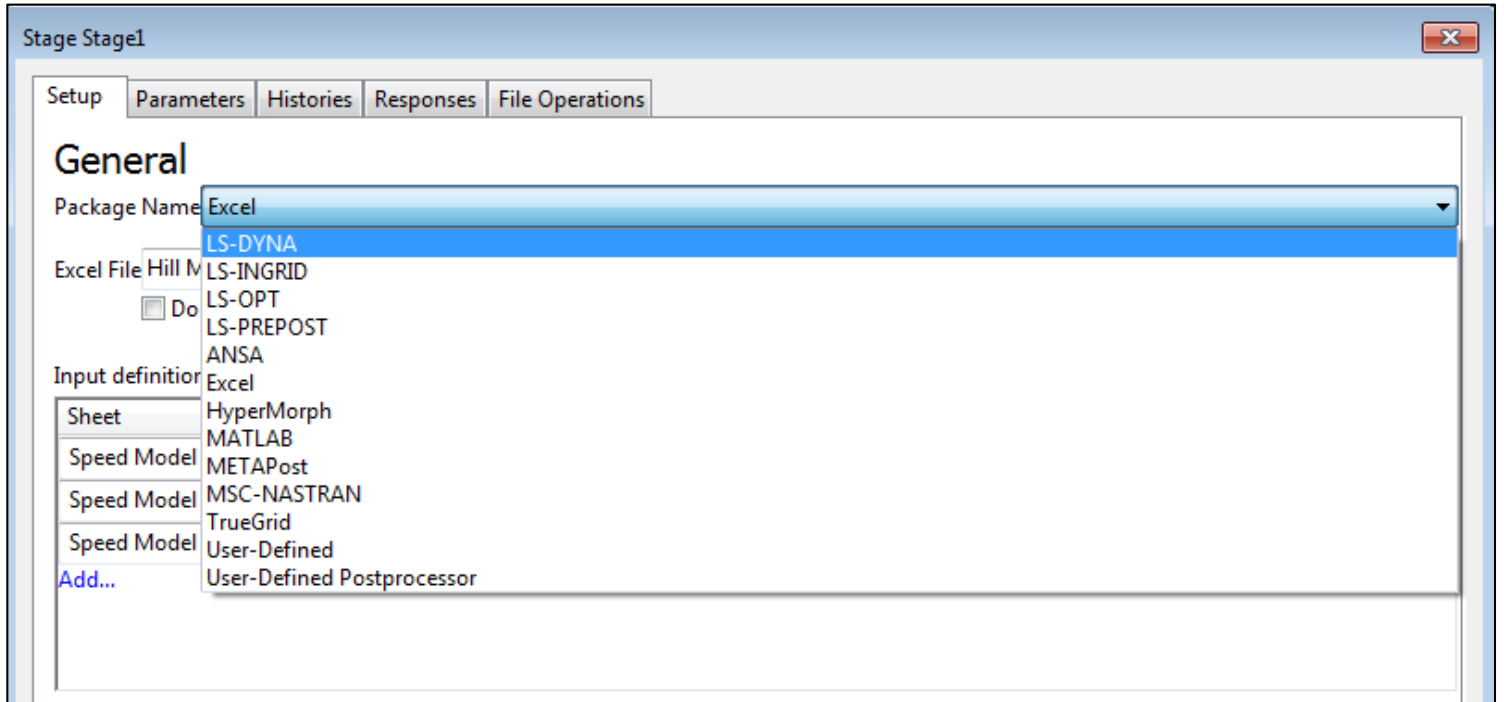
LS-OPT - Solvers

- 11 built in solver options, including:
 - LS-DYNA
 - MS Excel
 - MATLAB
 - NASTRAN
- User defined routines also possible.



LS-OPT - Solvers

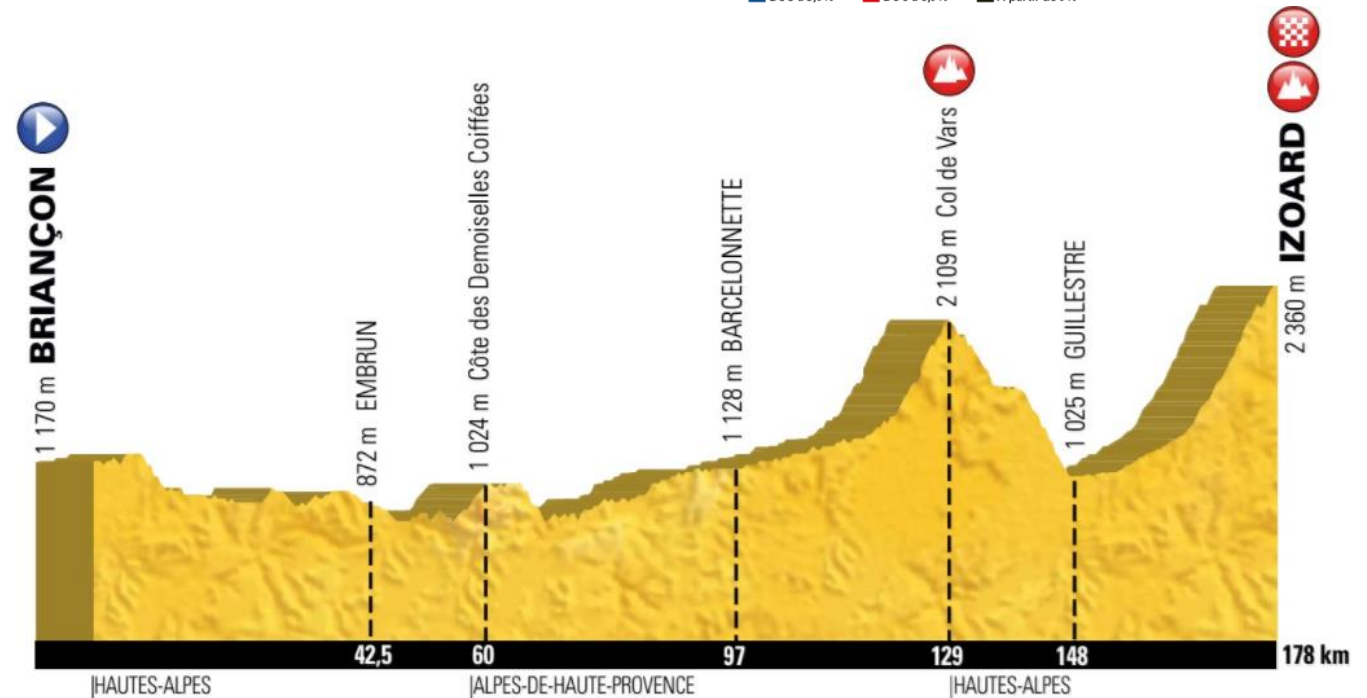
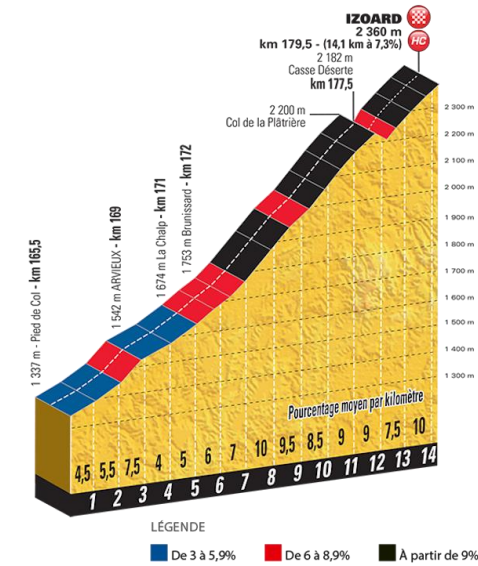
- 11 built in solver options, including:
 - LS-DYNA
 - MS Excel ← ?..
 - MATLAB
 - NASTRAN



- User defined routines also possible.

Etape du Tour

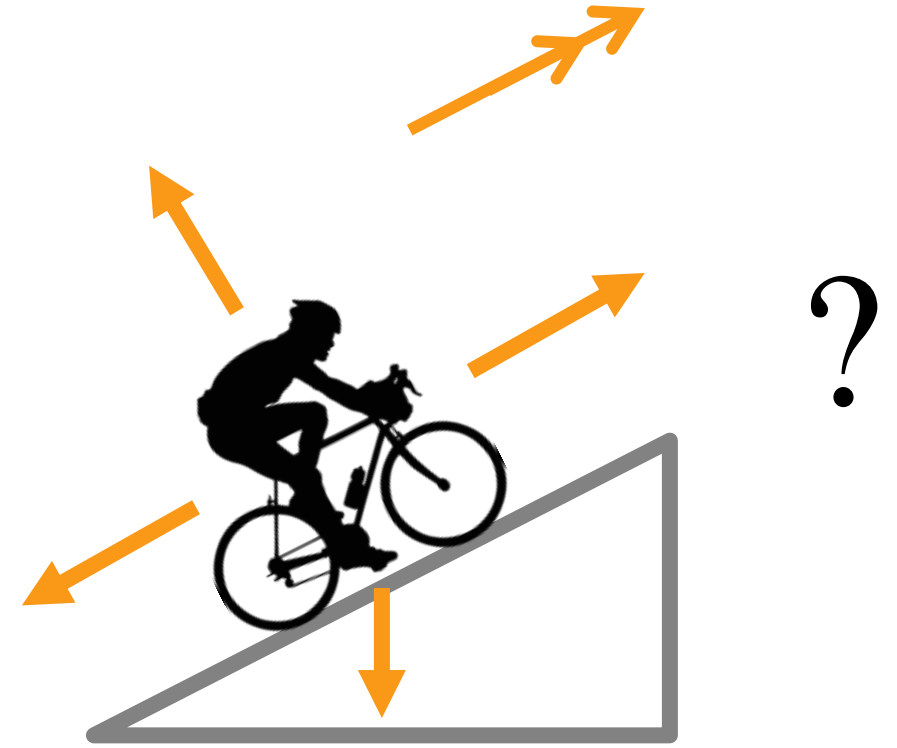
- Organised by Tour de France.
- Official stage opened to amateurs.
- Mountain stage.
- Circa 10,000-15,000 riders.
- 2017 stage:
 - 110 miles.
 - 2 mountains.
 - 3700 m ascent.



ASO

Mathematical Model

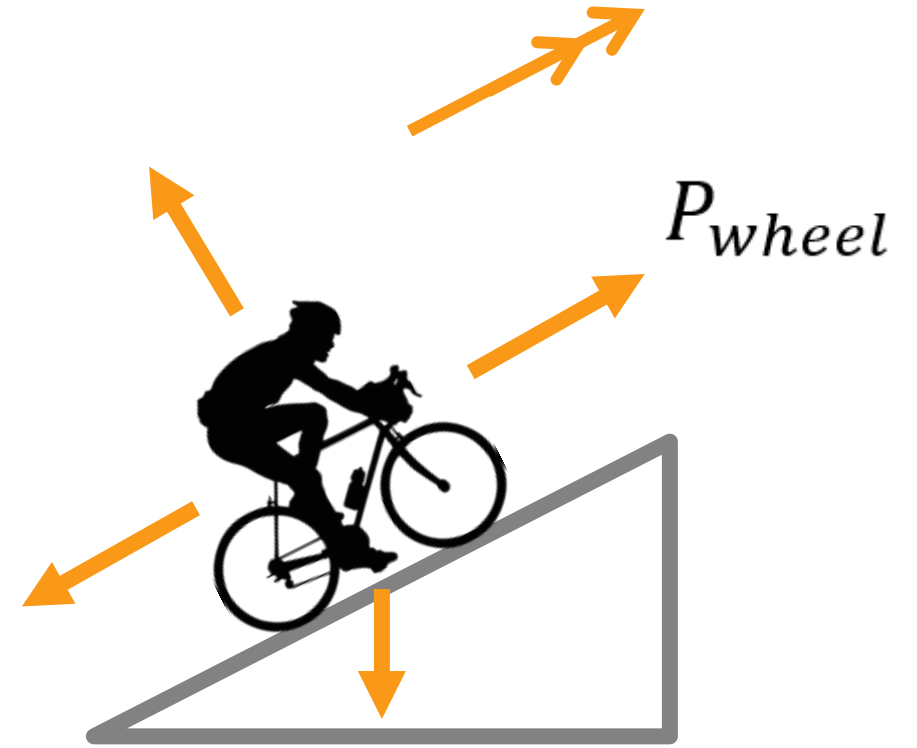
- Energy based calculation using force balance.
- System input less system outputs.



Mathematical Model

- System input:
 - Driving force.
 - Power at pedal as generated by cyclist.
 - Minus drivetrain losses, ~3%.
 - Power at wheel (drive).

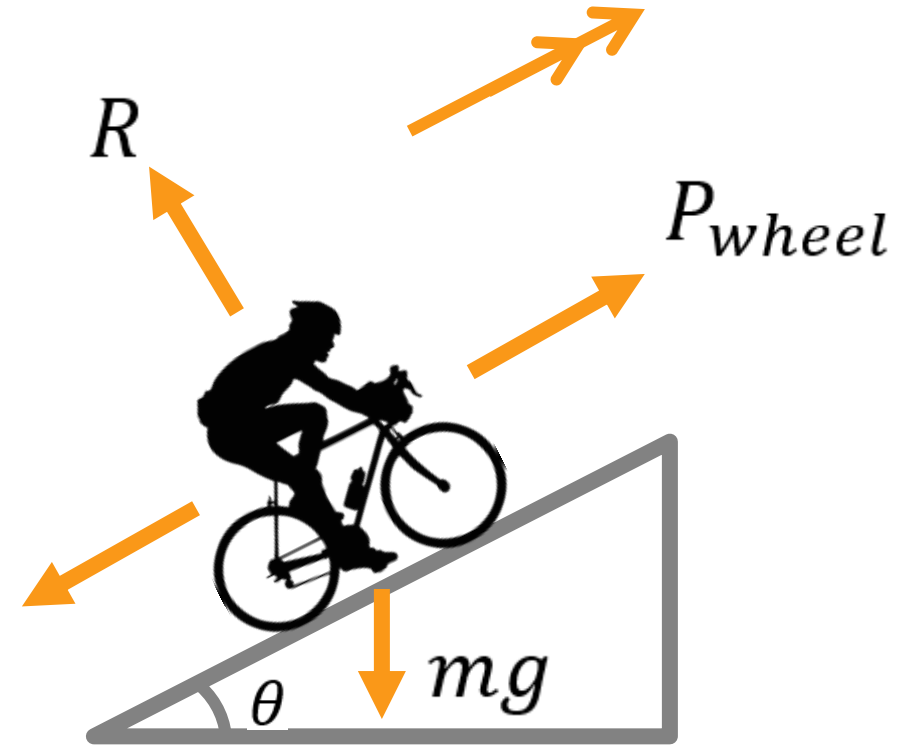
$$P_{wheel} = \eta_{drive} \cdot P_{pedal}$$



Mathematical Model

- System output:
 - Gravity.
 - Work done travelling uphill.

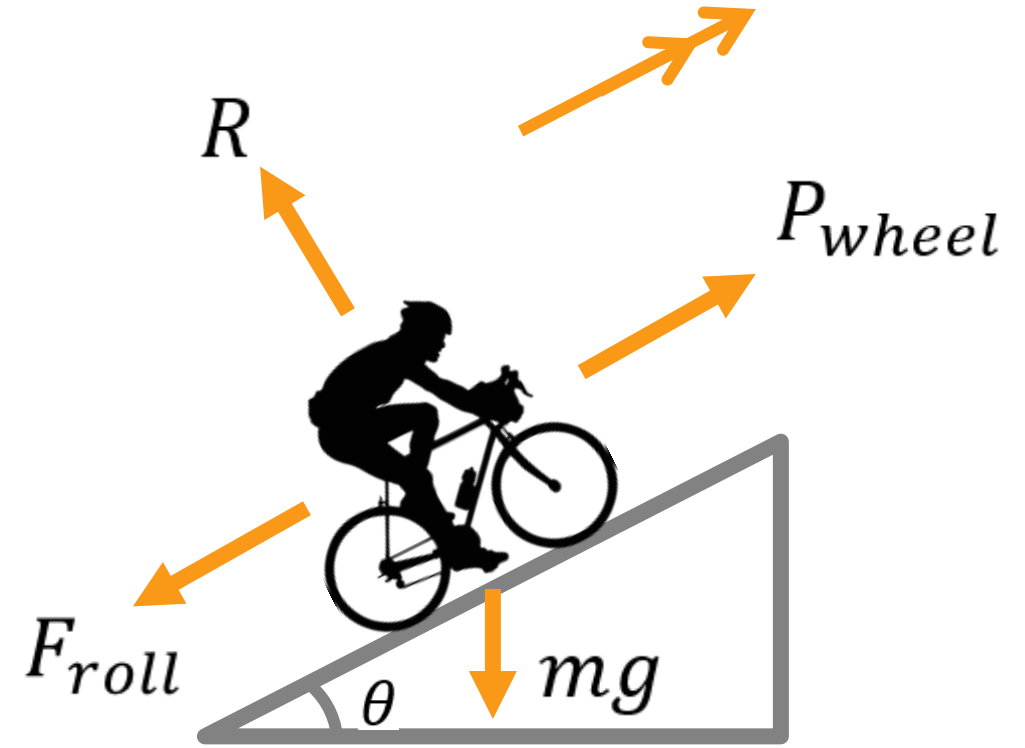
$$F_{grav} = mgsin\theta$$



$$(m = m_{cyclist} + m_{bike})$$

Mathematical Model

- System output:
 - Rolling resistance of tyres.
 - Function of weight and tyre friction.
 - Tyre rolling resistance coefficient approx. 0.005.



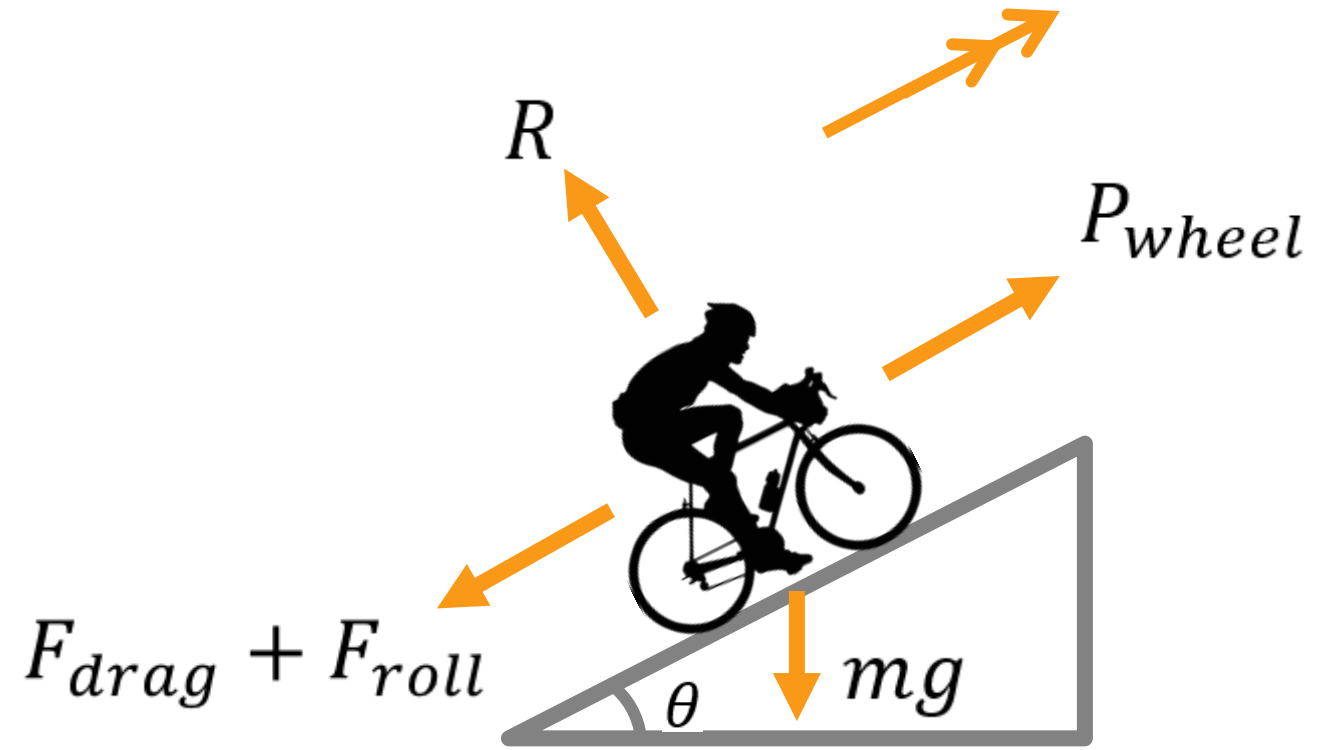
$$F_{roll} = \mu_{tyre} \cdot R = \mu_{tyre} \cdot mg \cos \theta$$

$$(m = m_{cyclist} + m_{bike})$$

Mathematical Model

- System output:
 - Air resistance.
 - Function of frontal area and shape.
 - Increases in proportion to the square of velocity.

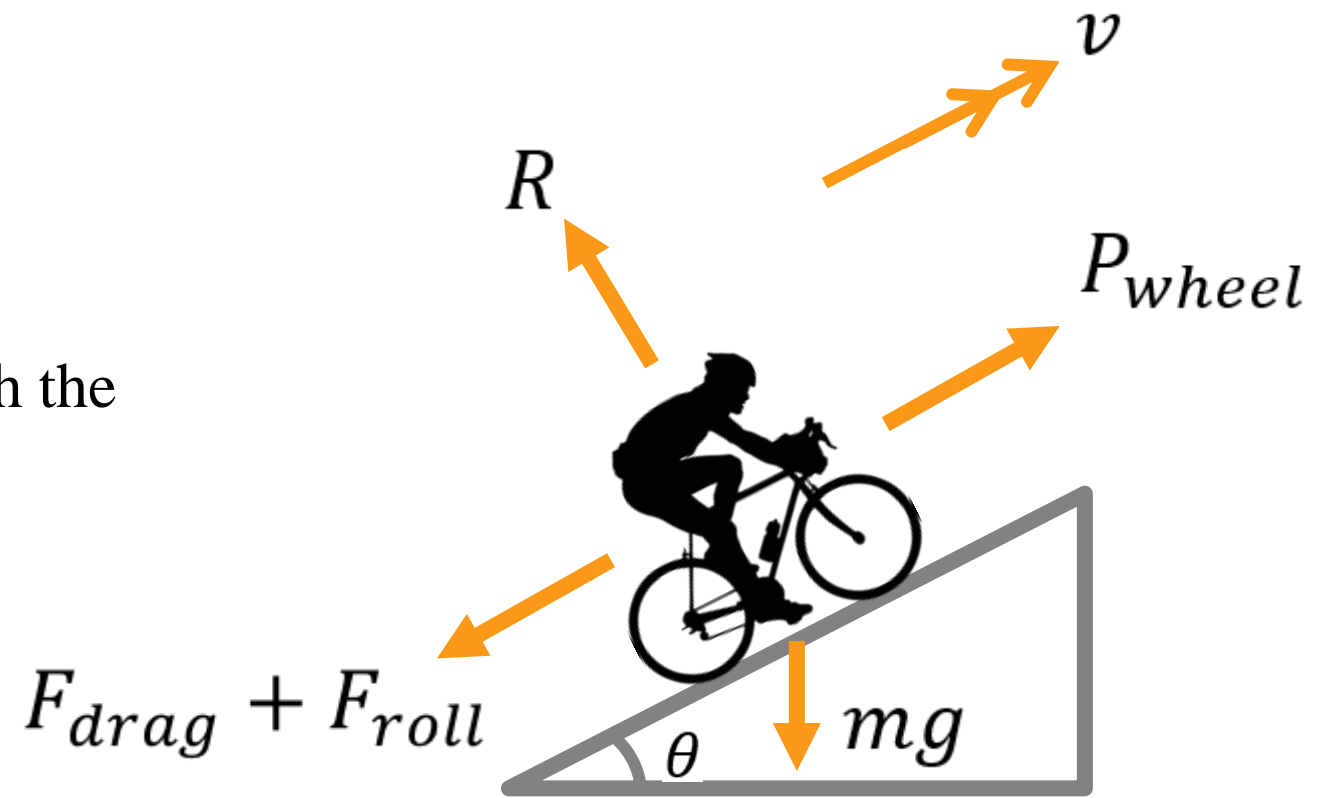
$$F_{drag} = \frac{1}{2} \rho v^2 C_d A$$



ρ Air Density
 v Velocity
 C_d Drag Coefficient
 A Frontal Area

Mathematical Model

- Balancing the driving force/power with the resisting forces:

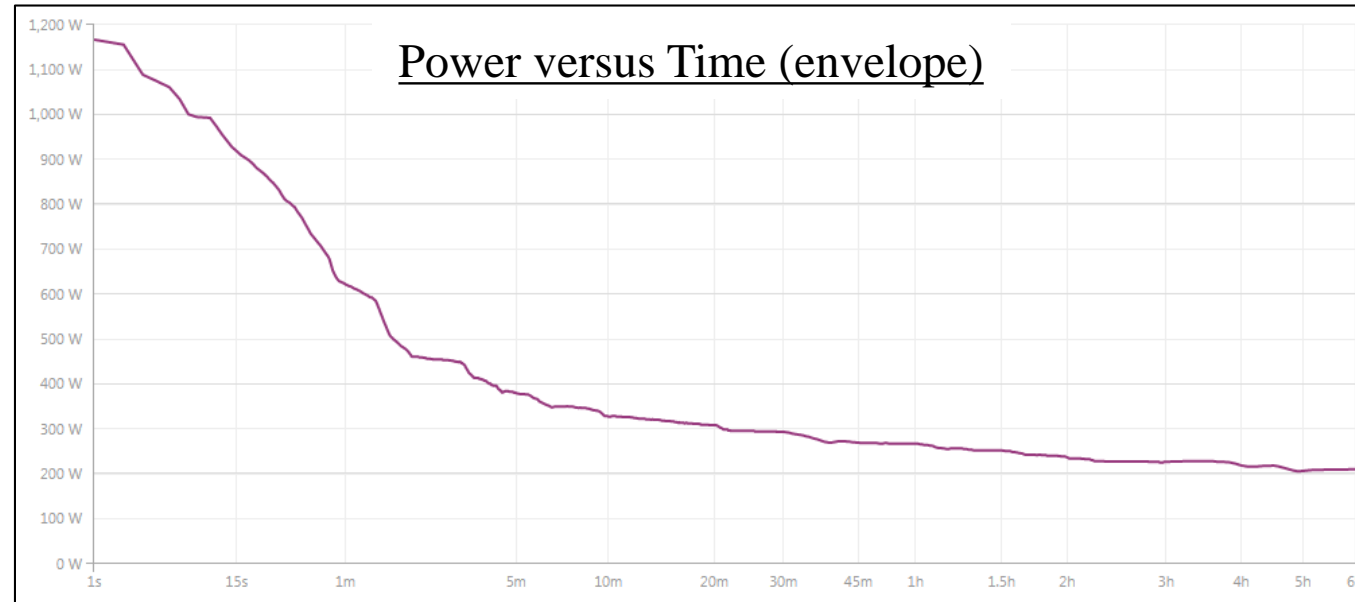


$$P_{wheel} = (F_{roll} + F_{drag} + F_{grav}) \cdot v$$

Cubic equation that can be solved for velocity.

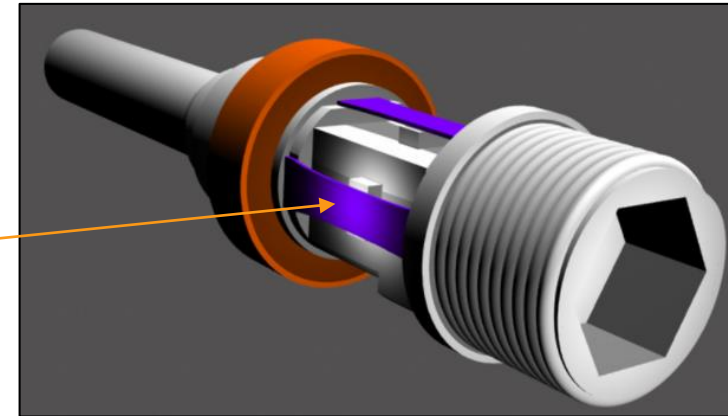
Unknowns... Input Power

- Not commonly known.
- Various methods of measuring exist.
- Pedal based measurements use strain gauges located within pedal spindle.



Garmin

Strain gauge



Swedish Adrenaline










Unknowns... CdA

- Typical values not appropriate.
- Requires extensive testing.
- Controlled conditions.



POC

- Values tuned so that model agreed with test data.
- $C_d = 0.6$.
- $C_dA = 0.3 \text{ m}^2$

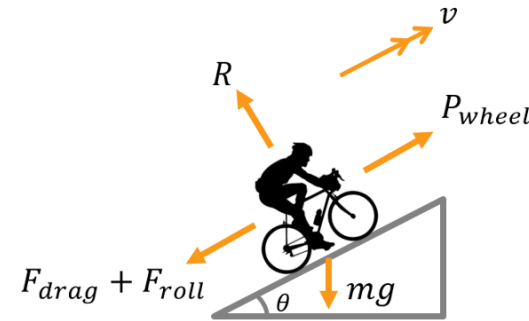
Bluff Body		Drag Coefficient
Sphere	→ 	0.47
Half-sphere	→ 	0.42
Cone	→ 	0.50
Cube	→ 	1.05
Angled Cube	→ 	0.80
Long Cylinder	→ 	0.82
Short Cylinder	→ 	1.15
Streamlined Body	→ 	0.04
Streamlined Half-body	→ 	0.09

Measured Drag Coefficients

Wikipedia

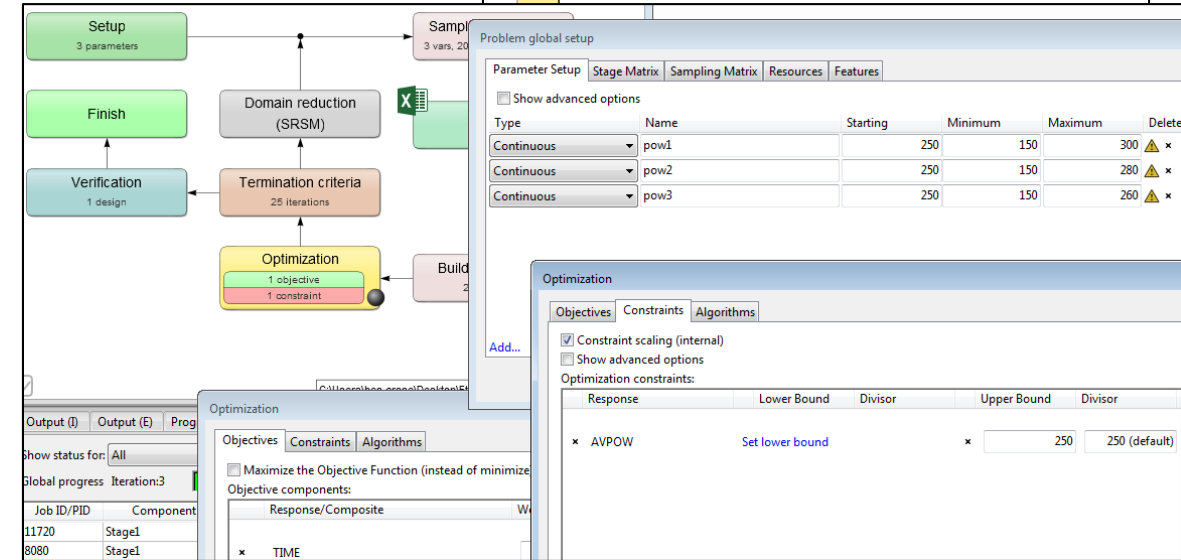
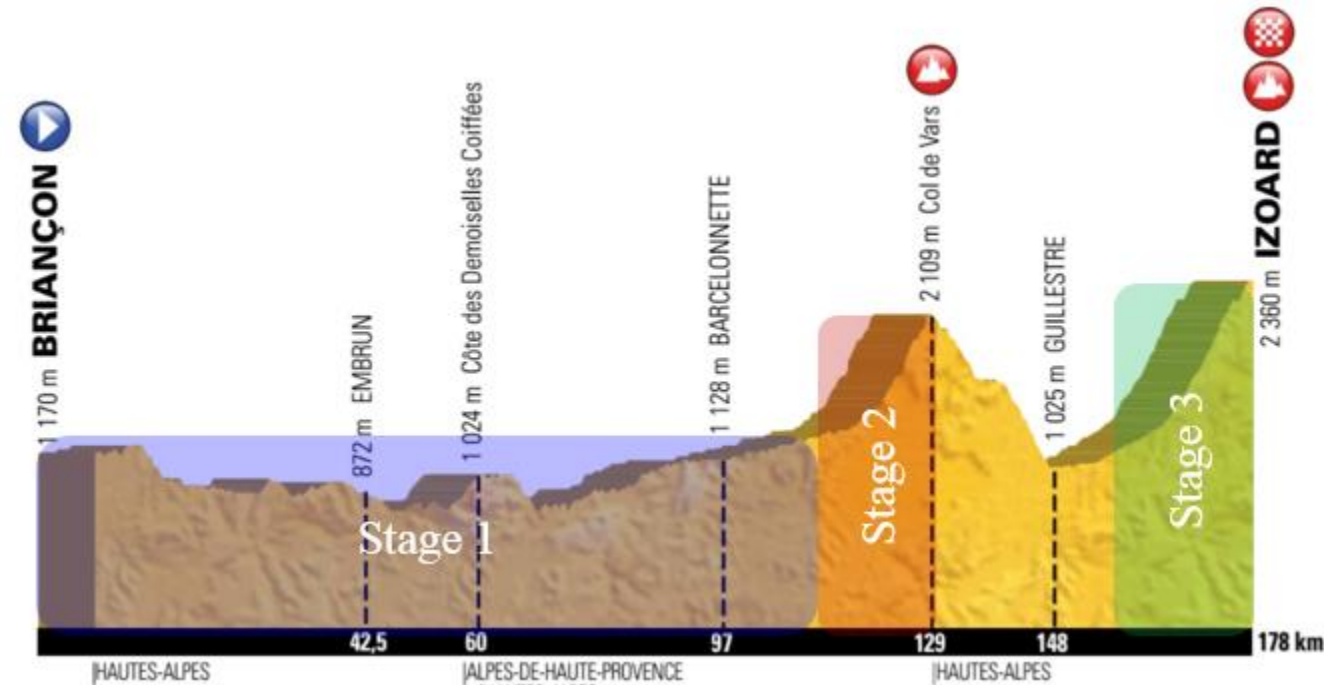
Problem Setup

- Minimise total time to complete route.
- Constrained by average power (250W).
- Course broken into three stages.



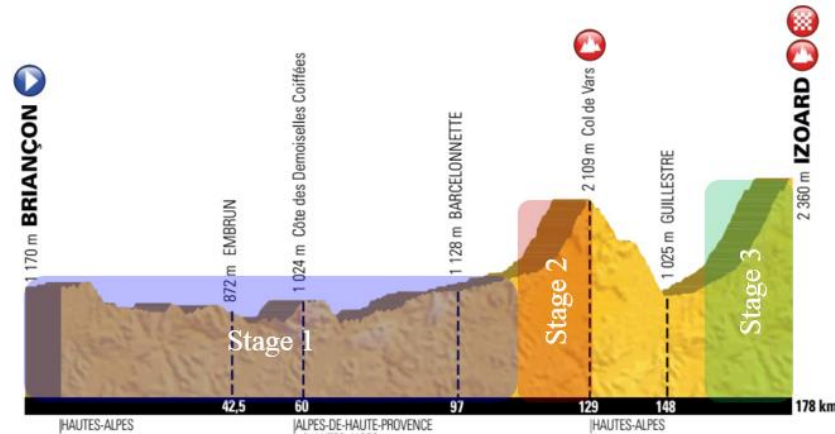
	A	B	C	D	E	F
1						
2						
3						
4						
5						
6						
7						
8						
9						
10						
11						
12						
13						
14						
15						
16						
17						
18						
19						

Stage 1	
Inputs	
Plegs	300 W
Gradient	0%
Distance	400 m
Constants	
Rider Mass	70 kg
Bike Mass	7 kg
Frontal Area	0.5 m ²
Drag Coefficient	0.605
Rolling Resistance	0.005
Density	1.226 kg/m ³
g	9.81 m/s ²
Drive Loss	3%
Working	
Angle	0 rad
P _{wheel}	291 W (D)



Initial Result

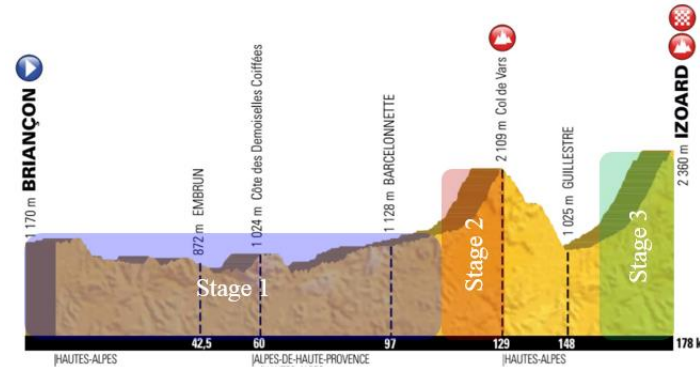
- Not great...
- Model too simplistic.
- Recommended strategy:
 - Gentle on stages 1 & 2.
 - Max effort on final climb.
- **Not practical.**



BikeRadar

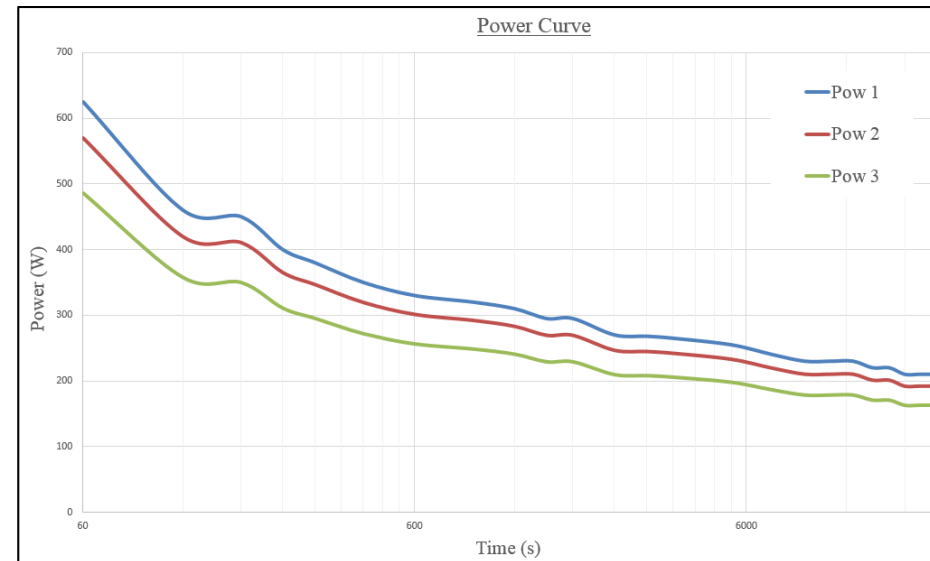
Refined Model

- Utilisation concept introduced.
- Decay factor on latter stages.
- Reduced aero loads for stage 1.



S2 Power	
S1 Util	Factor
0.85	1
1	0.9

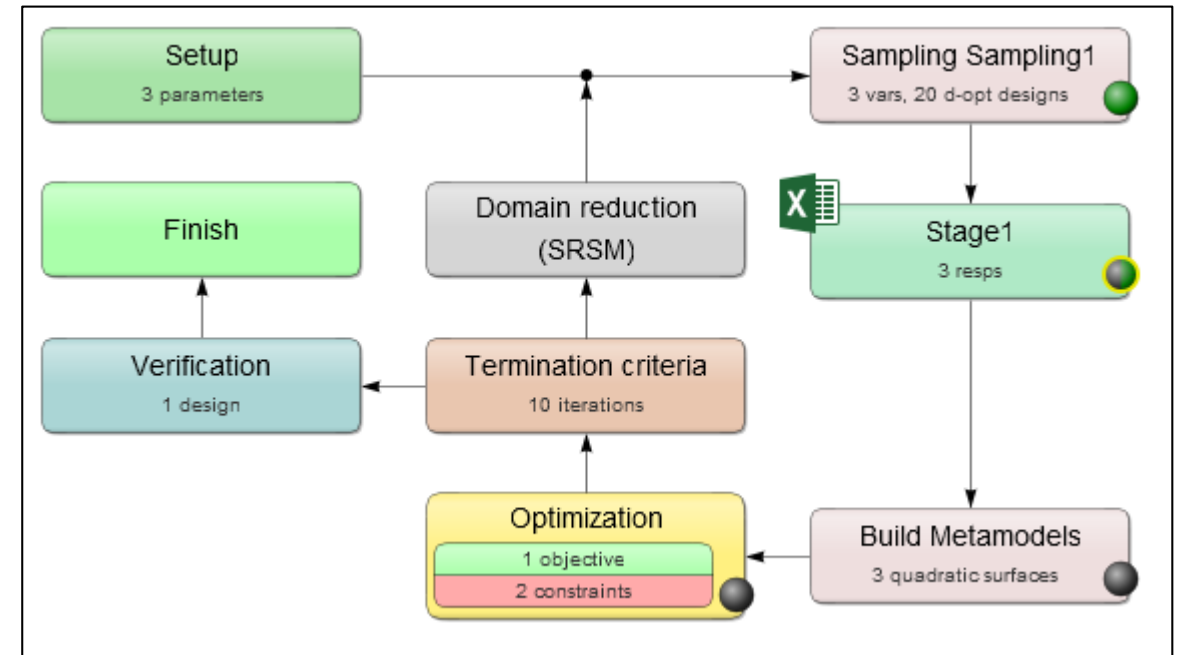
S3 Power	
S2 Util	Factor
0.85	0.9
1	0.8



Dan Pontefract

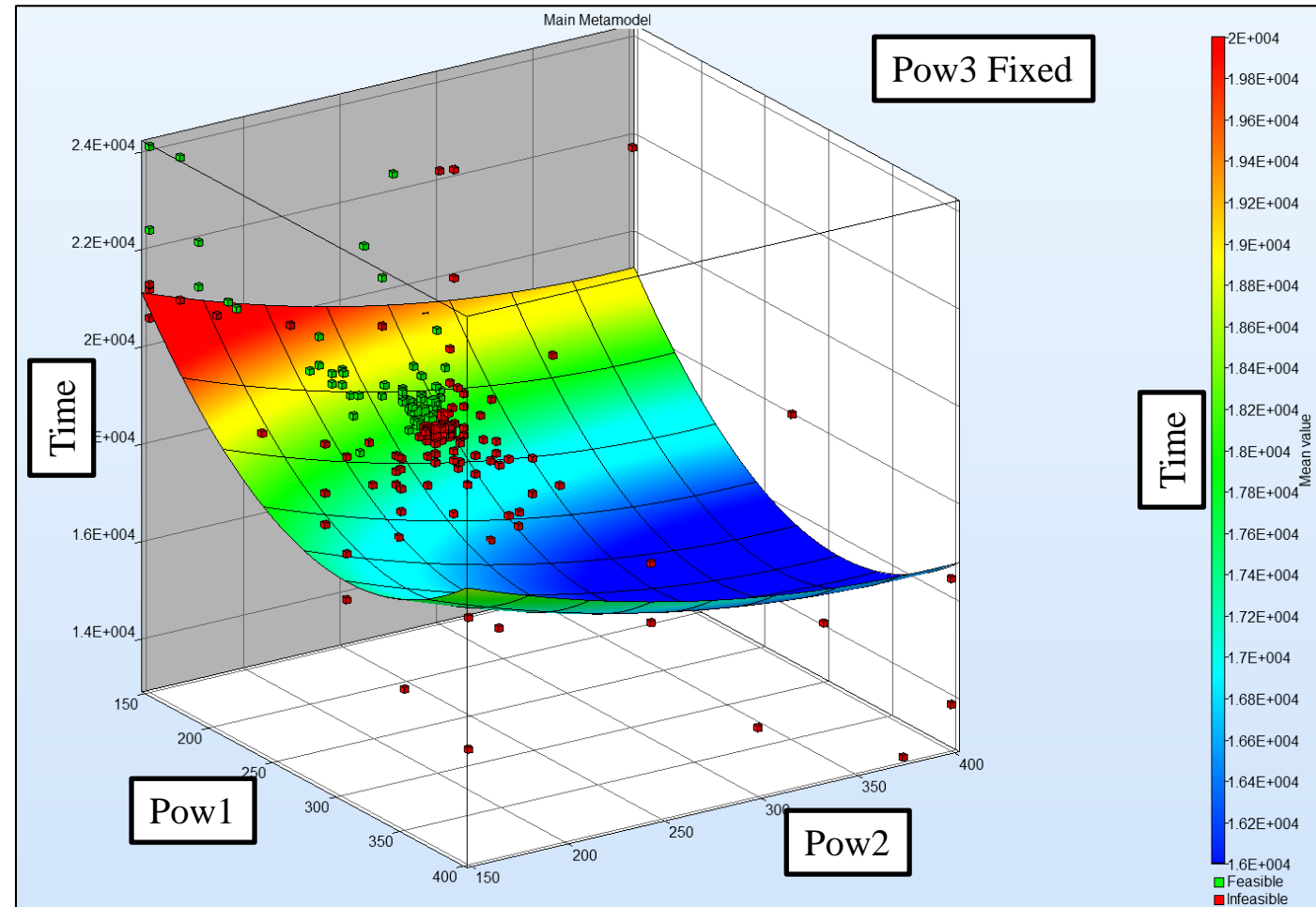
Refined Problem

- Constraints now based on utilisation.
 - Average should not exceed 100%.
 - Max should not exceed 103%.
- Quadratic polynomial meta-model used.
- D-Optimal sampling.
- Domain reduction active.
- 10 iterations.



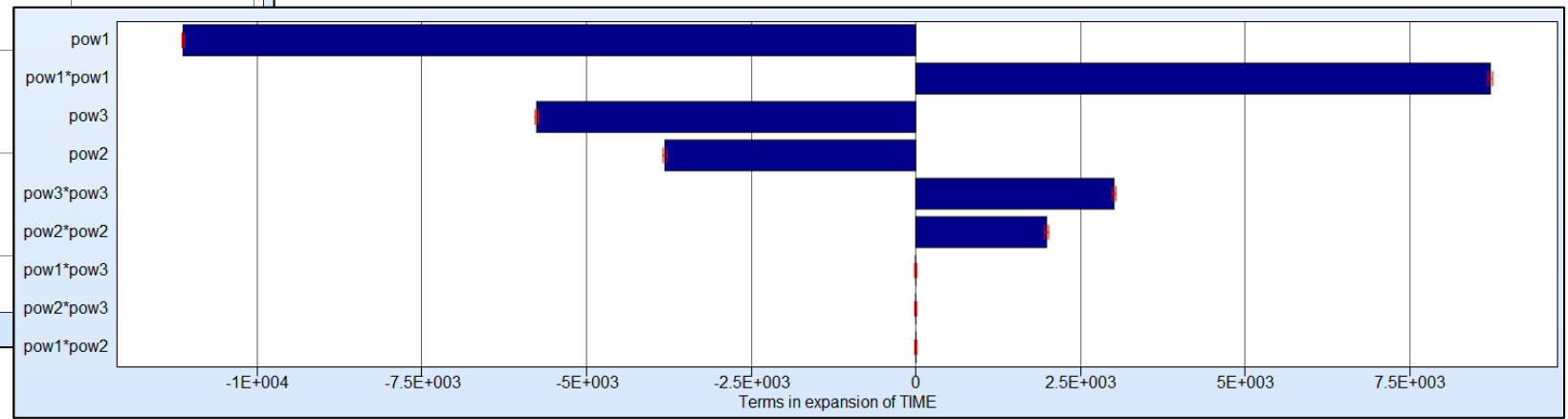
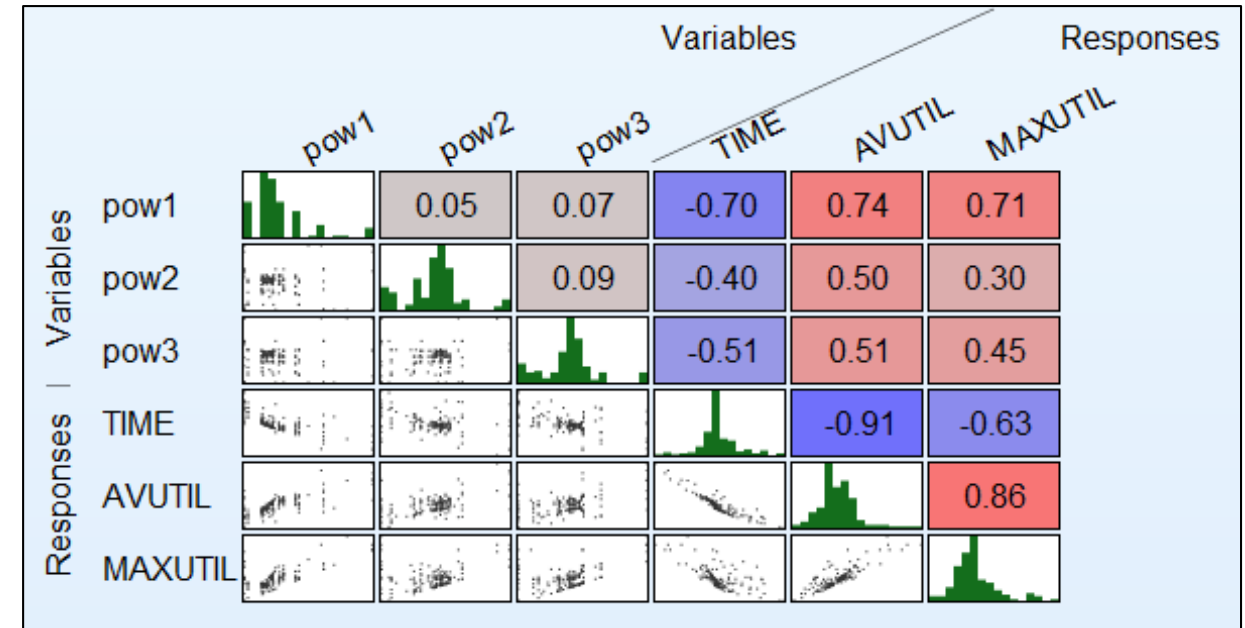
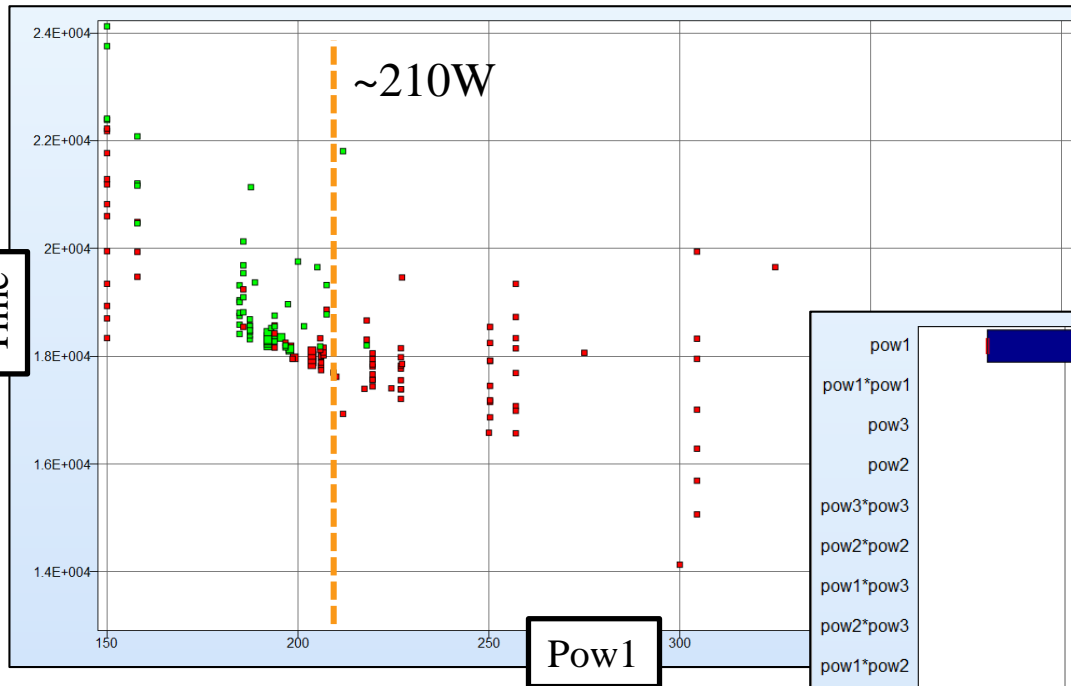
Final Result

- Much more useful.
- Several possible (and similar) strategies all yielding similar times.
- Preferred result:
 - Stage 1 = 218 W (3 hrs 11 mins).
 - Stage 2 = 214 W (51 mins).
 - Stage 3 = 251 W (61 mins).
 - Total Time = 5 hrs 3 mins.



Final Result

- Importance of stage 1 (and 3) reflected in other data.



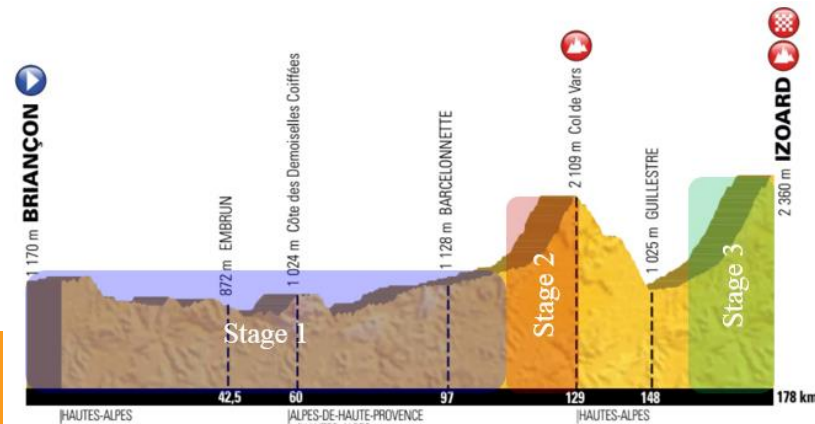
Physical Test

**BRIANÇON**  **IZOARD**
16TH JULY 2017



REAL TIME
06:11:18
REAL RANKING
261 / 11234

- Great success!
- During ride focus was stage 1 and stage 3.
- Prediction was 13 mins out.
- Difference is closer to ten mins due to water bottle refills.
- Finished 261st, 56 mins from winner.
- 91 minutes off TdF time...



Timing	Predicted	Actual
Stage 1	3:11	3:19
Stage 2	0:51	0:51
Stage 3	1:01	1:06
Total*	5:03	5:16

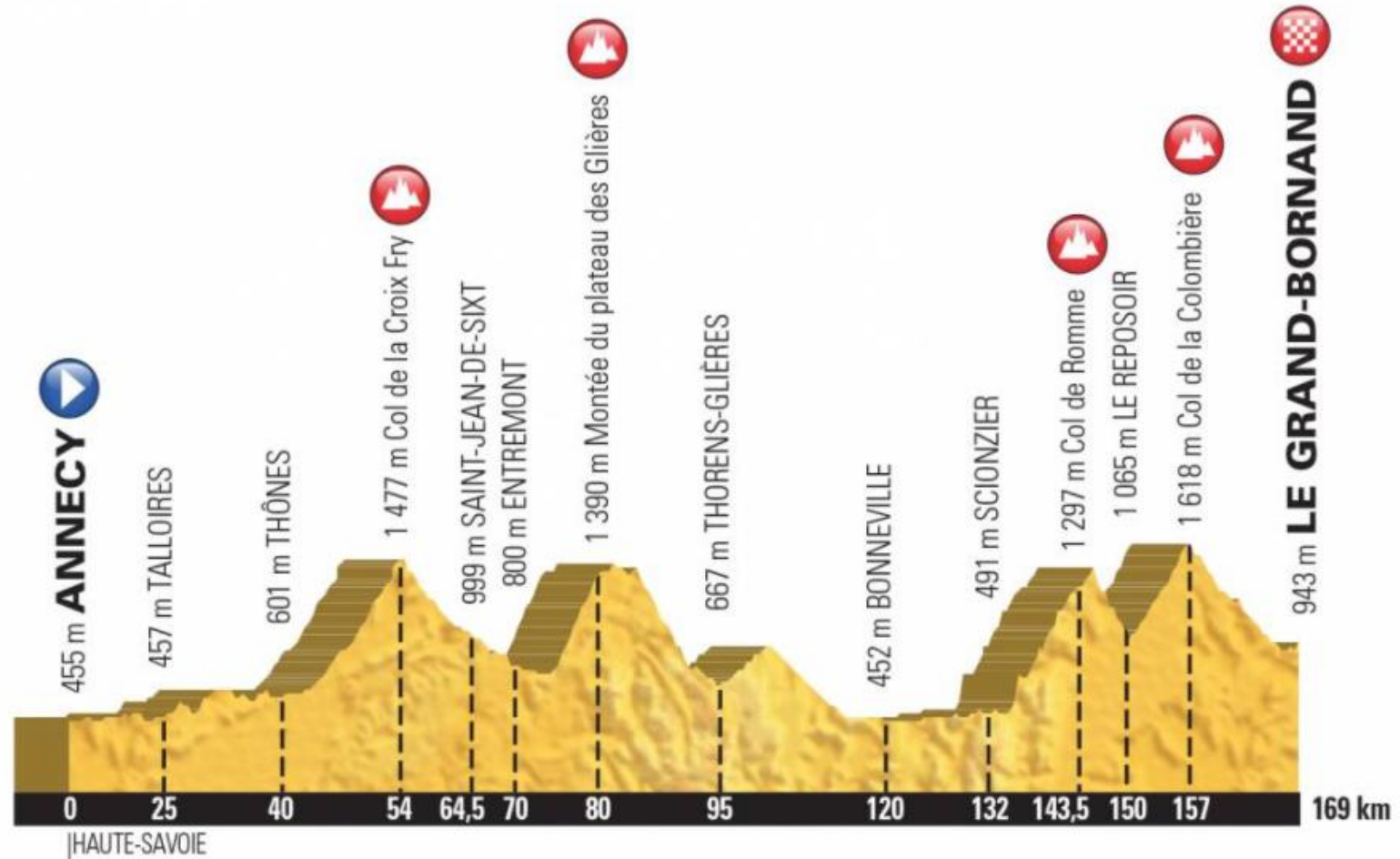
*Doesn't include downhill between stage 2 and 3.



Ben Crone

Next Steps...

- Apply it again this year!
- 105 miles.
- 4 mountains.
- +4000 m ascent.



Thank You