

# Recent and Ongoing Developments in LS-DYNA®

Presented by  
Jason Wang

<http://ftp.lstc.com/anonymous/outgoing/jason/Slides>



2018 Oasys LS-DYNA UK User's  
Meeting, 1/24/2018, Warwickshire

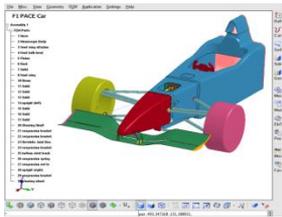
# Outline

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- Introduction
- User requests/enhancements Jason Wang
- Tire Development Suri Bala
- Implicit Roger Grimes
- SPH, DEM Jason Wang
- CPM Jason Wang
- LS-OPT Nielen Stander
- Mortar Contact Thomas Borrvall
- EM Pierre L'Eplattenier
- ICFD Facundo Del Pin

# LSTC Products

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**LS-PrePost**

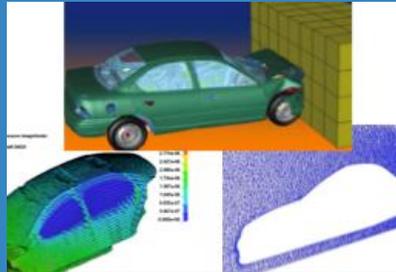


-  Surface
-  2D Interpolator
-  Accuracy
-  Sensitivity

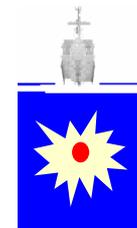
**LS-OPT/LS-TaSC**



**Dummies & Barriers**



**LS-DYNA**



**USA**

# LS-DYNA Applications

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Development costs are spread across many industries



## Automotive

Crash and safety  
NVH & Durability  
FSI



## Structural

Earthquake safety  
Concrete structures  
Homeland security



## Aerospace

Bird strike  
Containment  
Crash



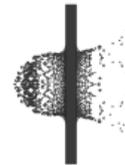
## Electronics

Drop analysis  
Package analysis  
Thermal



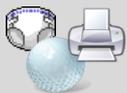
## Manufacturing

Stamping  
Forging  
Welding



## Defense

Weapons design  
Blast and Penetration  
Underwater Shock Analysis



## Consumer Products



## Biosciences

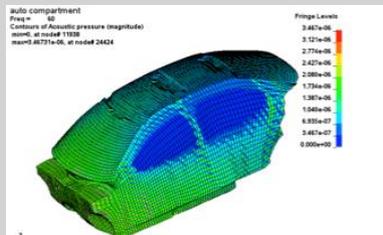
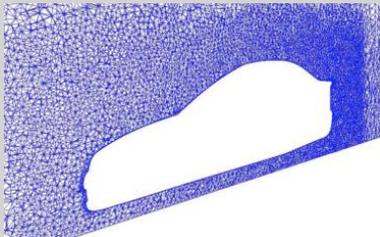
# LS-DYNA - Current Capabilities

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Includes coupled Multi-Physics, Multi-Scale , and Multi-Stage in one Scalable Code

- ✓ Explicit/Implicit
- ✓ Heat Transfer
- ✓ ALE & Mesh Free  
i.e., EFG, SPH, Airbag Particle
- ✓ User Interface  
Elements, Materials, Loads
- ✓ Acoustics, Frequency  
Response, Modal  
Methods
- ✓ Discrete Element Methods
- ✓ Incompressible Fluids
- ✓ CESE Compressible Fluids
- ✓ Electromagnetics
- ⚙️ Control Systems

# LS-DYNA - One Code, One Model



## Single Model for Multiple Disciplines

Manufacturing, Durability, NVH, Crash, FSI

## Multi-physics and Multi-stage

Structure + Fluid + EM + Heat Transfer

Implicit + Explicit ....

## Multi-scale

Failure predictions, i.e., spot welds

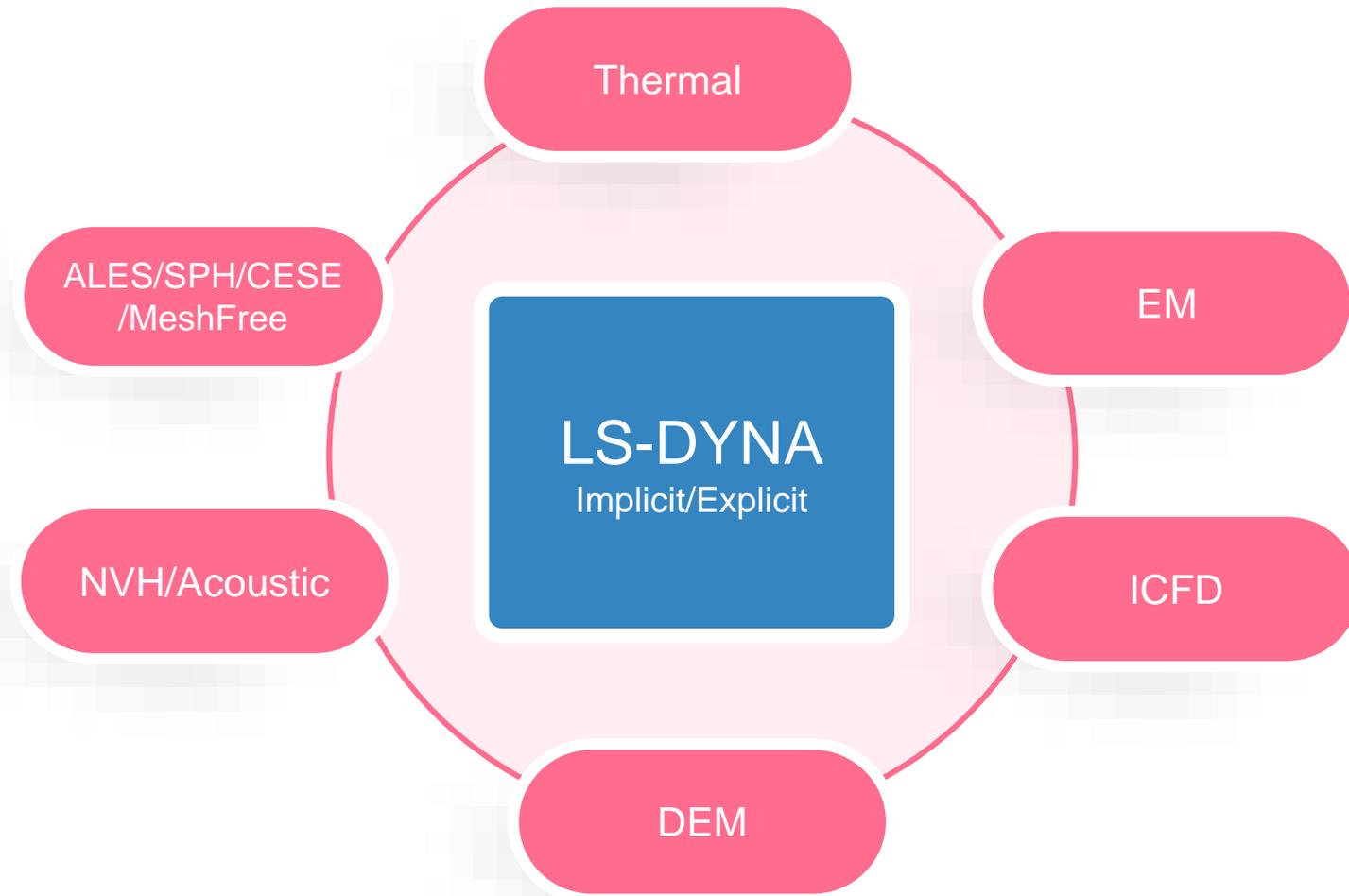
## Multi-formulations

linear + nonlinear + peridynamics + ...

The Neon crash model is courtesy of FHWA/NHTSA National Crash Analysis Center

# Strong Coupled Multi-Physics Solver

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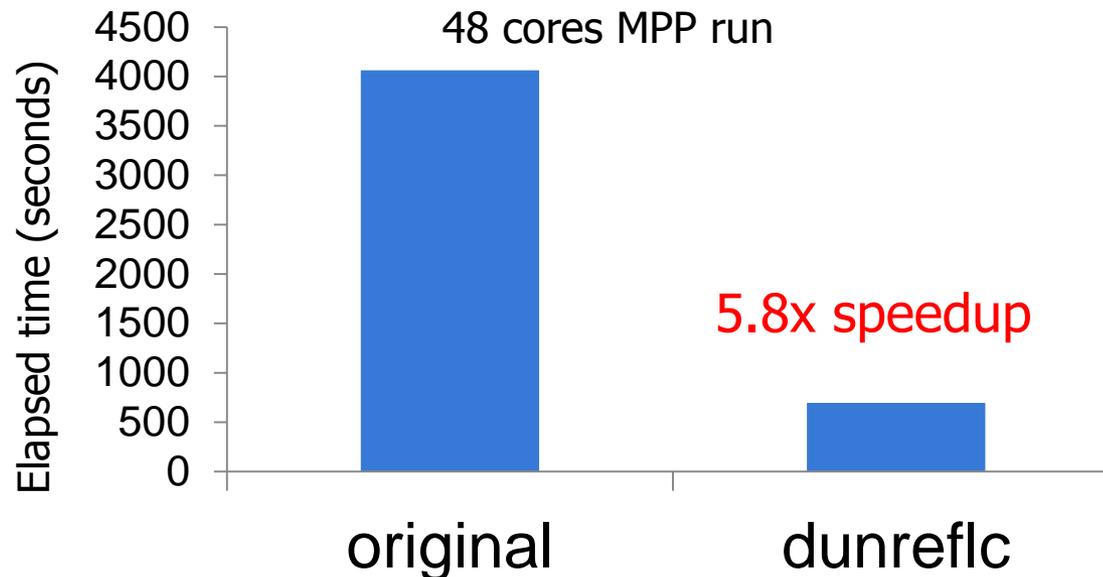
Computers that can handle multiphysics simulations are becoming affordable  
Scalability is rapidly improving for solving multi-physics problems

User requests/  
enhancements

# \*CONTROL\_MPP\_DECOMPOSITION\_DISABLE\_UNREF\_CURVES

## Multistep/Component analysis

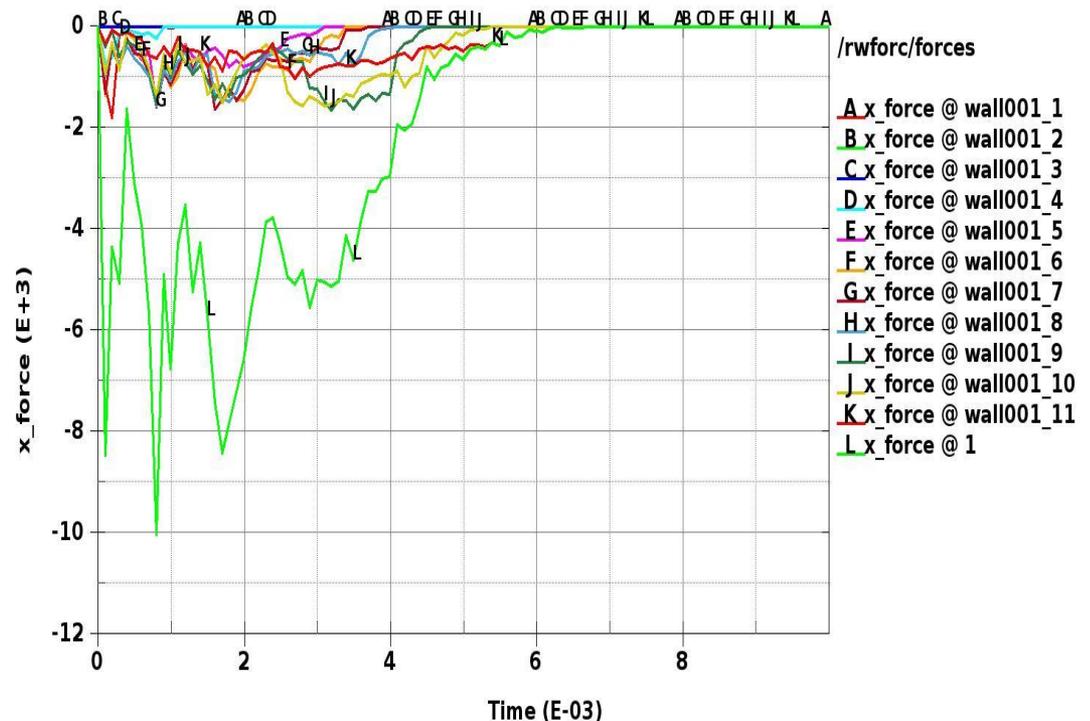
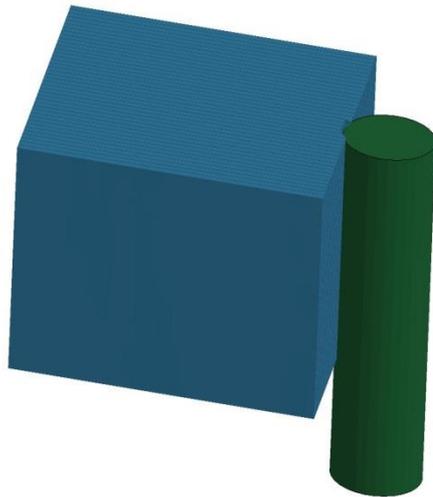
- 1<sup>st</sup> run generate the segment pressure, nodal forces, etc and saved in time history file
- 2<sup>nd</sup> applied the load to structure by one of the following way
  - \**BOUNDARY\_PRESCRIBED\_MOTION\_NODE*
  - \**LOAD\_NODE*
  - \**LOAD\_SHELL\_ELEMENT*
  - \**LOAD\_THERMAL\_VARIABLE\_NODE*
- 2<sup>nd</sup> run greatly speed up by skipping those unused curves.



# \*RIGIDWALL\_GEOMETRIC\_CYLINDER with multiple sections

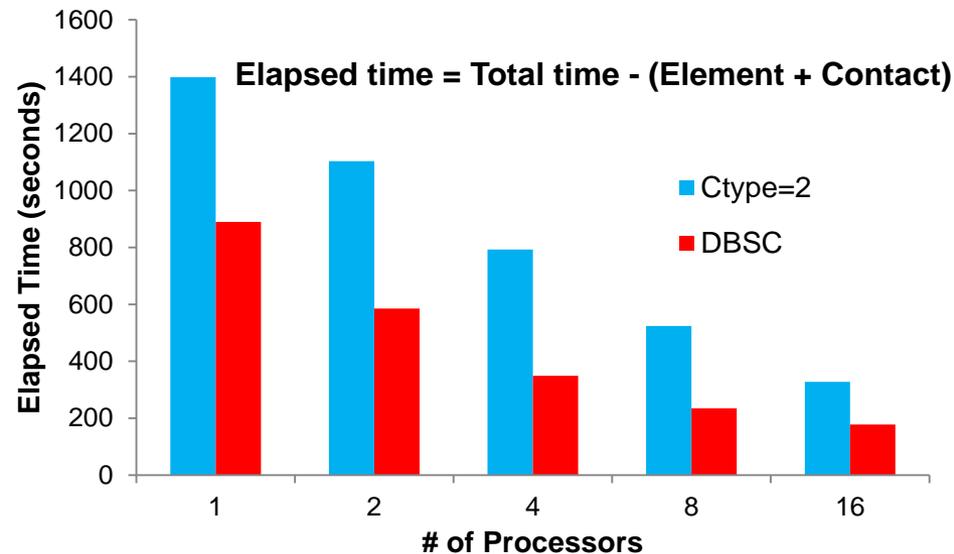
- Allow using one cylinder and subdivided it into many sections (please check keyword for the new options)
- Section's forces are reported in rwworc using the same format as regular segment set
- Shorter runtime by reducing number of CYLINDER definitions

Time = 0.00049635

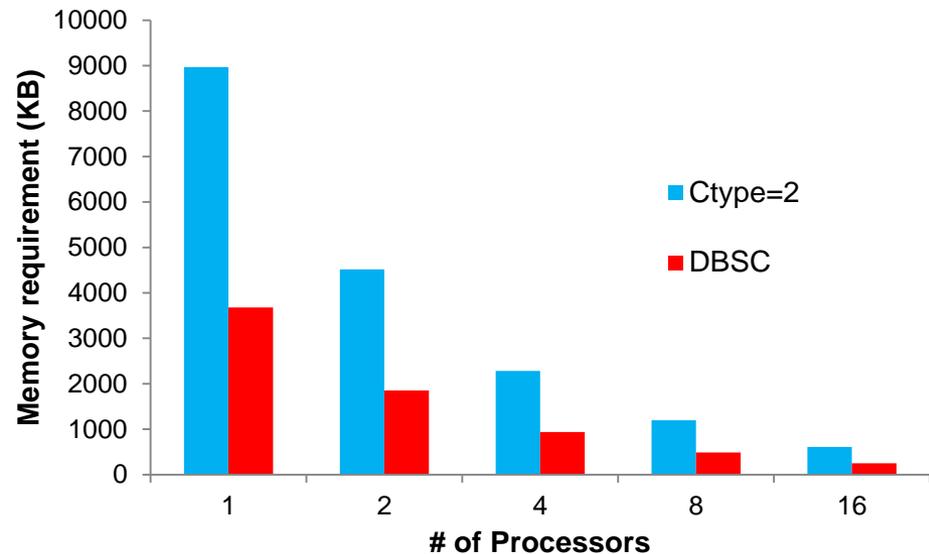


# \*DEINFE\_BEAM\_SOLID\_COUPLING

- New implementation to replace \*CONSTRAINED\_LAGRANGIAN\_IN\_SOLID for CTYPE=2 for embeded structures in solid (rebar in seats)
- Easy setup, better performance and less memory
- Supports constraint and penalty formulations
- Available in R9.2



CPU cost



Memory requirement

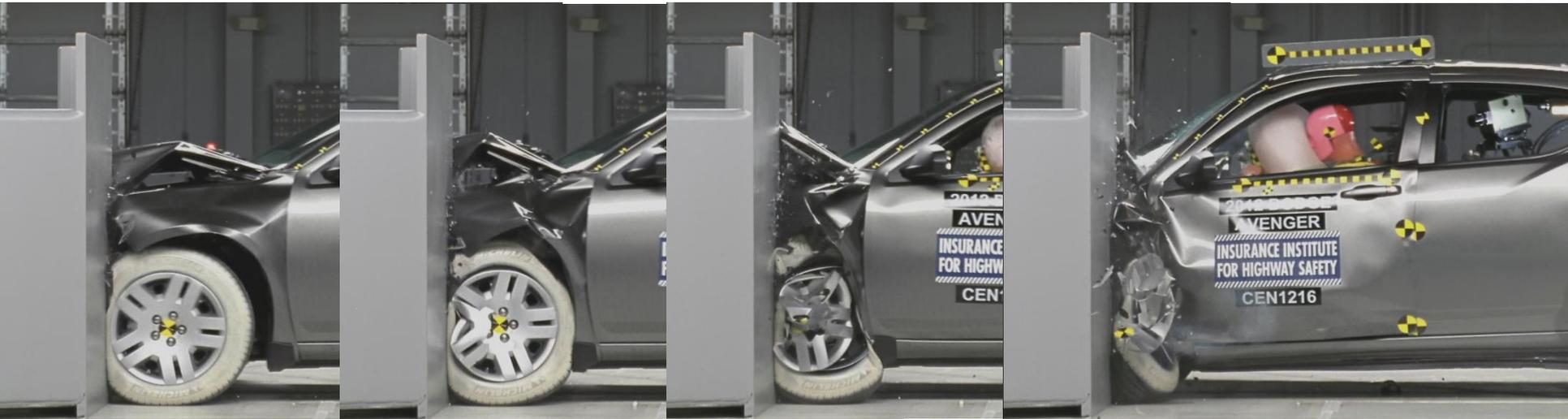
# Tire Development

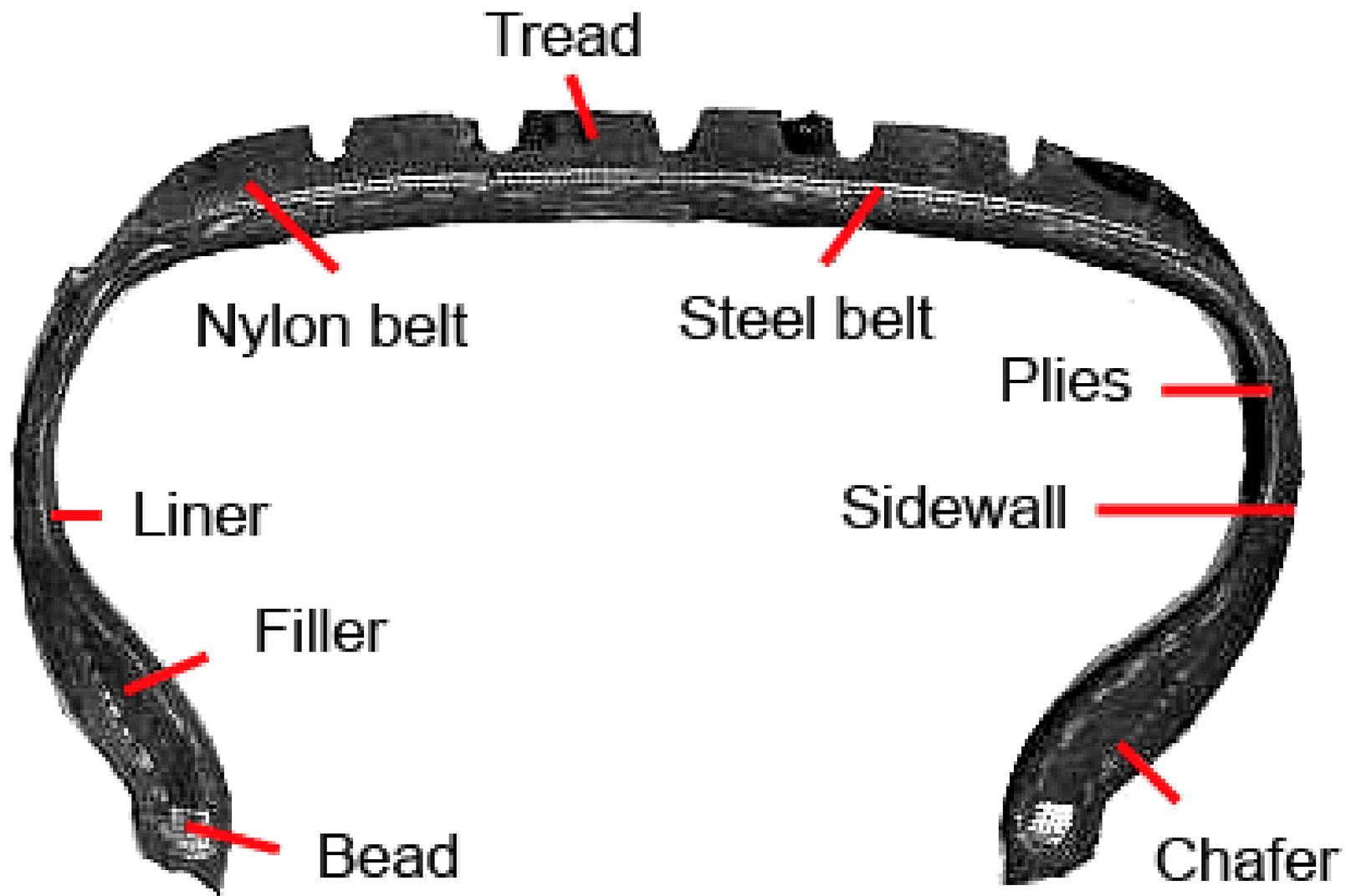
Hamid Keshtkar<sup>1</sup>, Kevin Thomson<sup>1</sup>, Michael Reeves<sup>1</sup>  
Mike Berger<sup>2</sup>, Dilip Bhalsod<sup>2</sup>, Srikanth Adya<sup>2</sup>, Suri Bala<sup>2</sup>  
Paul Du Bois<sup>3</sup>

<sup>1</sup> FCA, <sup>2</sup> LSTC, <sup>3</sup> Independent Consultant

# Small Overlap

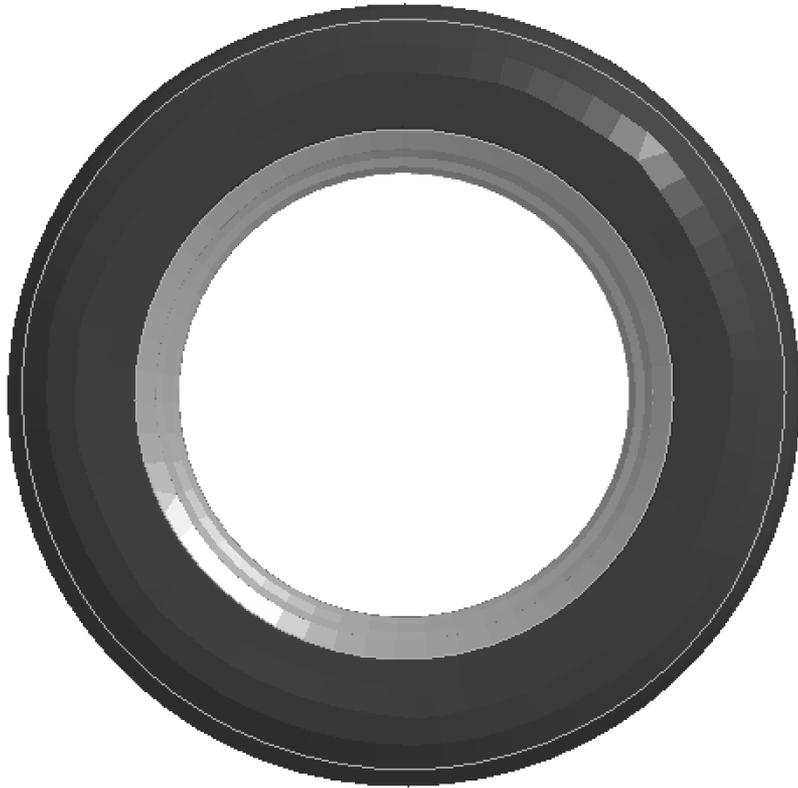
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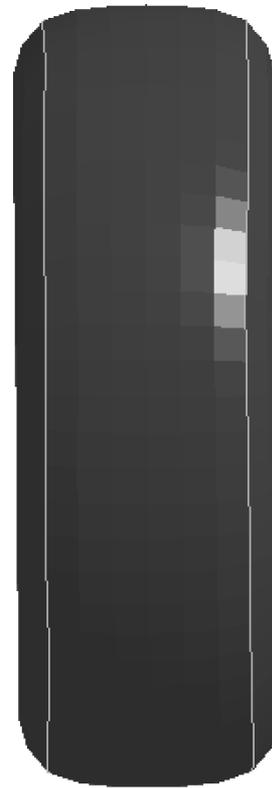


# Shell based Tire Model

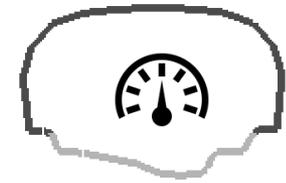
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Left View

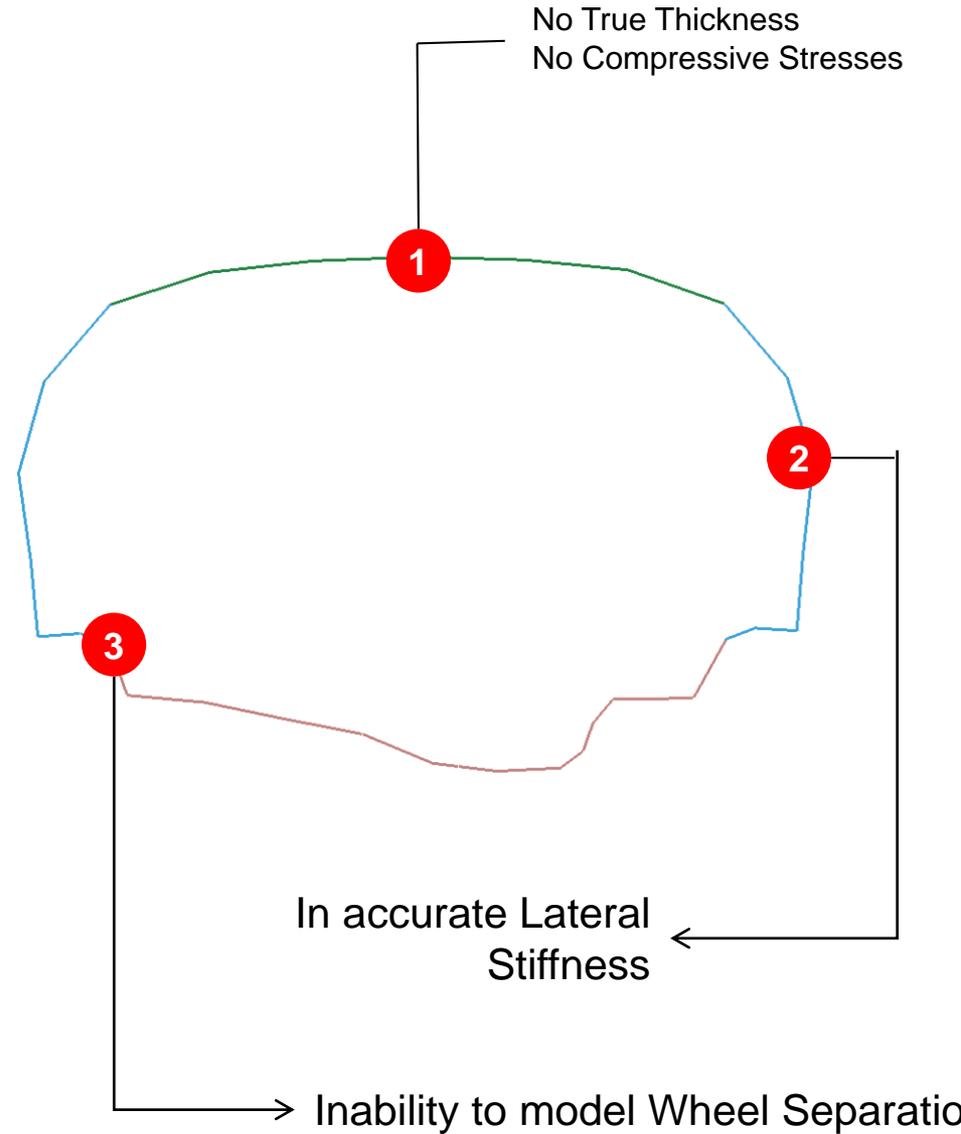
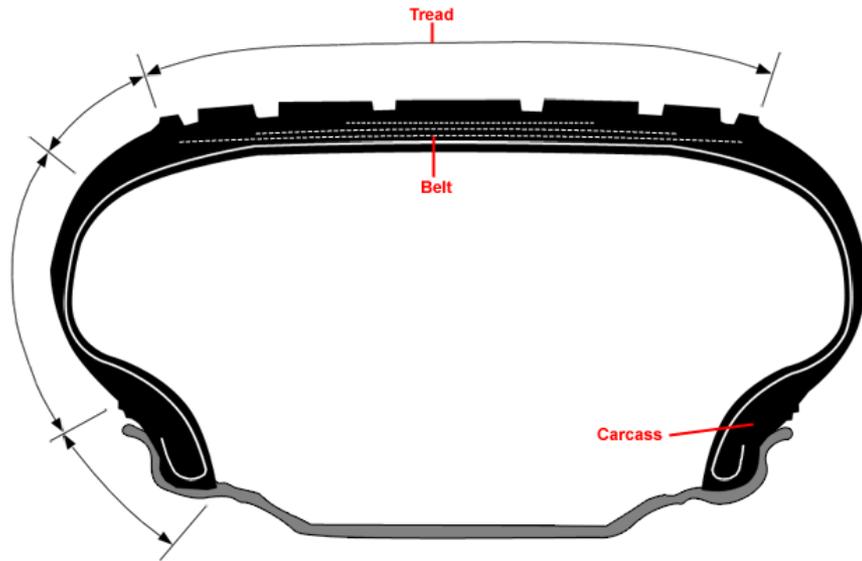


Front View



Section View

# Shell Based Tire Model





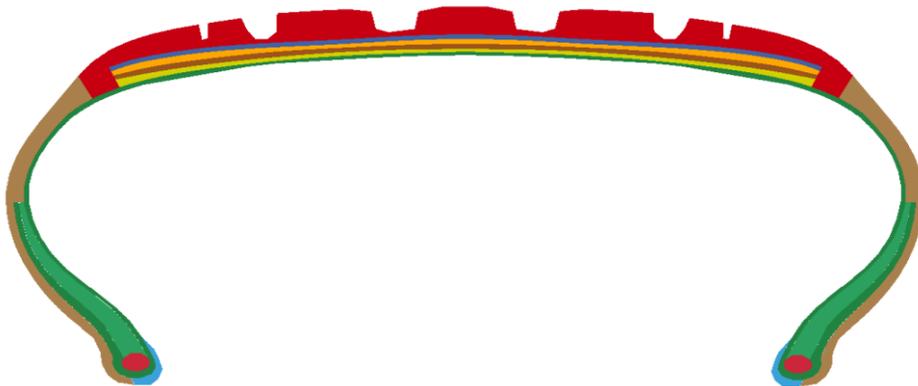
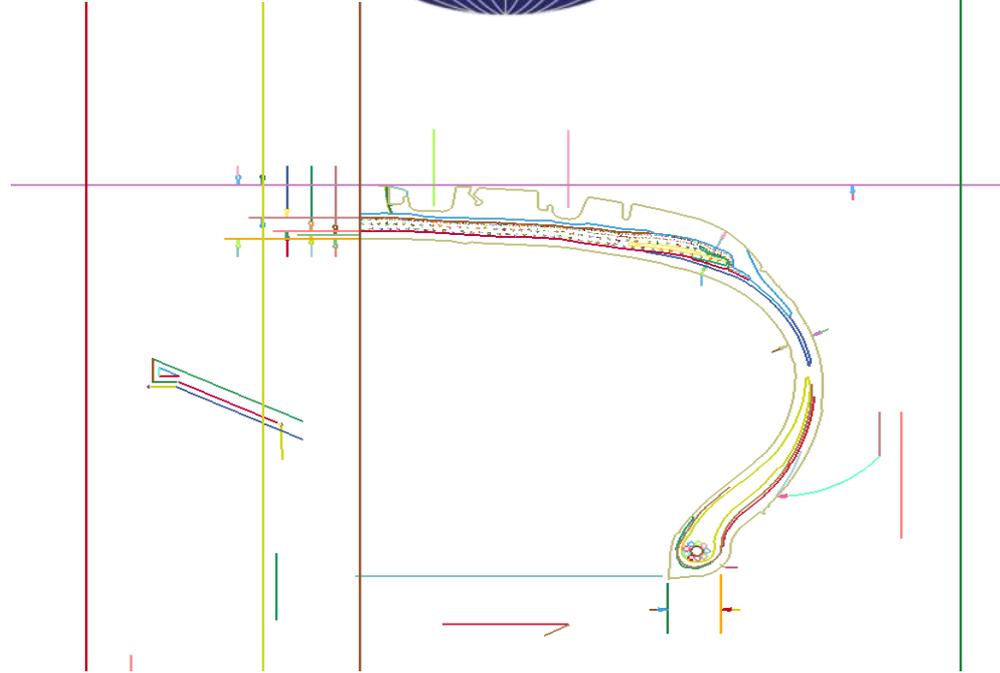
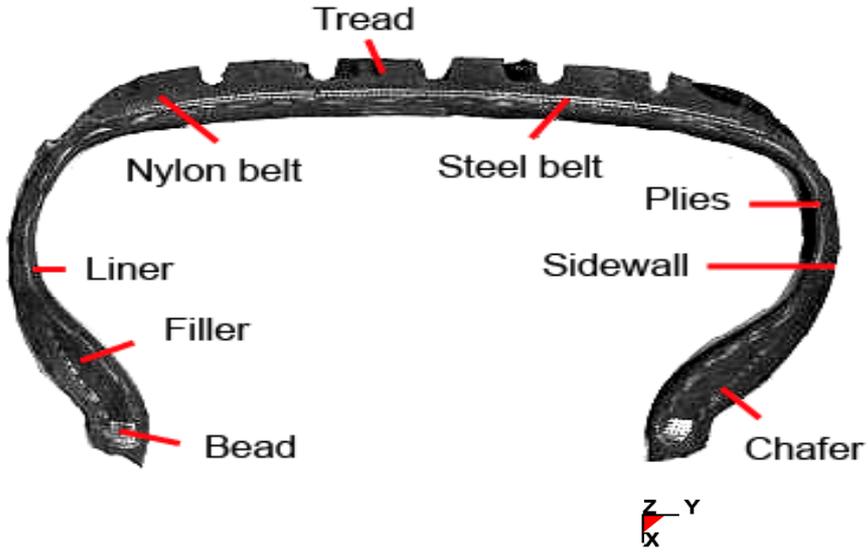
FIAT CHRYSLER AUTOMOBILES



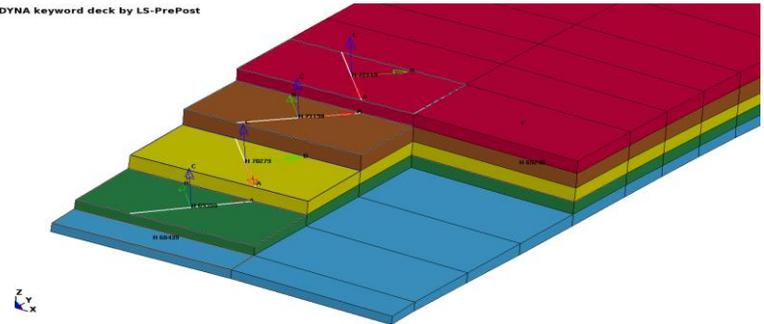
SMITHERS



LSTC  
Livermore Software  
Technology Corp.

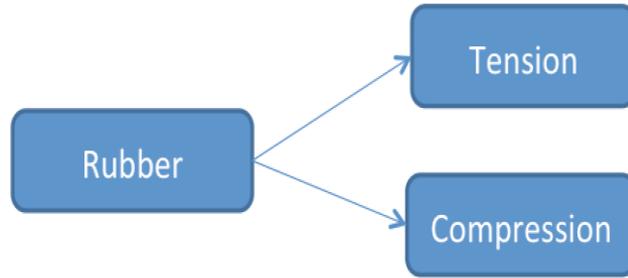


LS-DYNA keyword deck by LS-PrePost

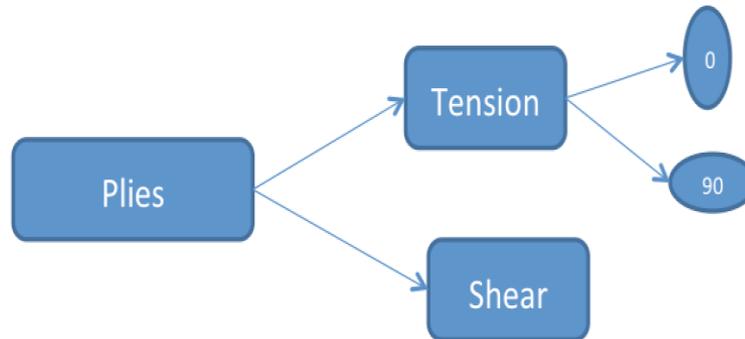


# Material Characterization Tests

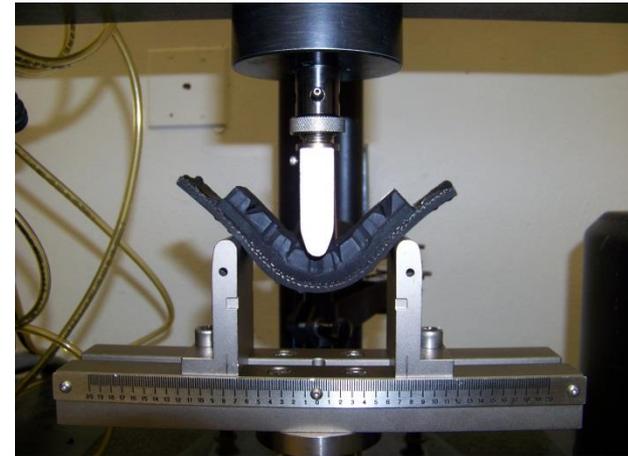
Tread,  
SubTread, Inner  
Liner, Apex  
(MAT\_181)



Belt Overlay,  
WireBelt,  
Body Ply  
(MAT\_002)

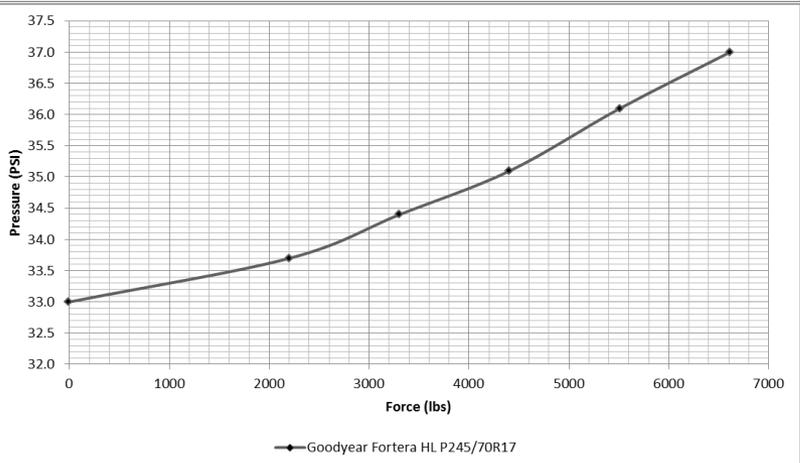
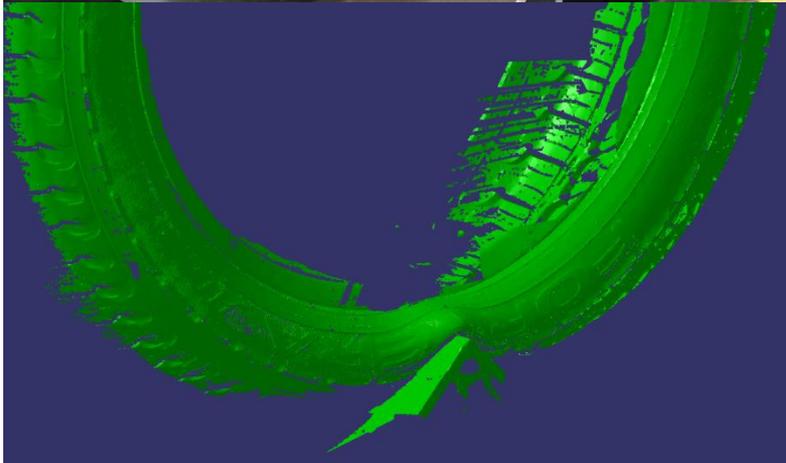
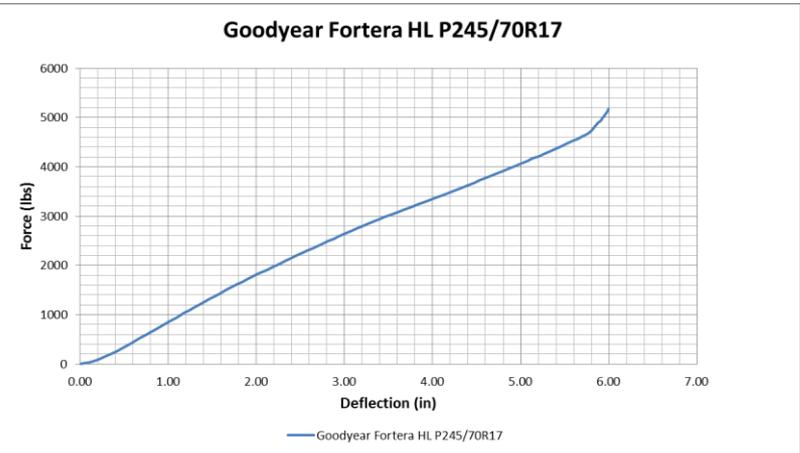


Bead  
(MAT\_001)



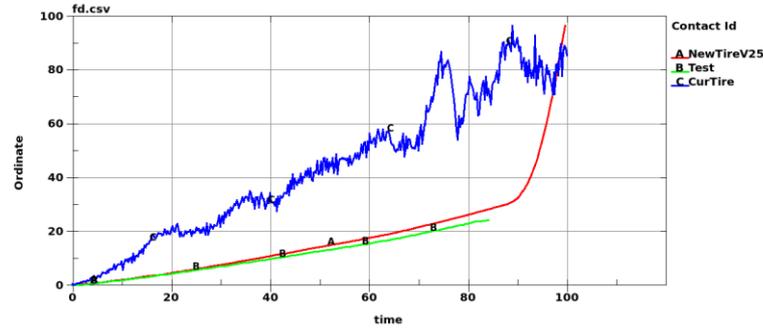
# Tire Tests

- Static and Dynamic Tests

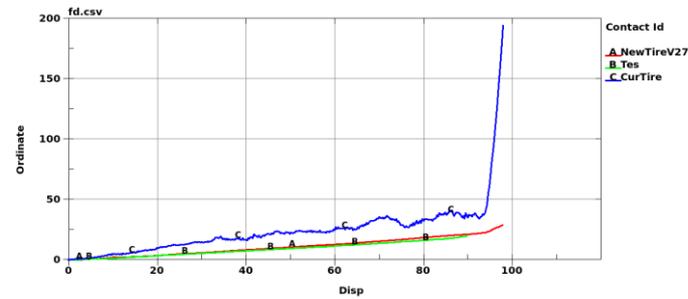


# Static Tests

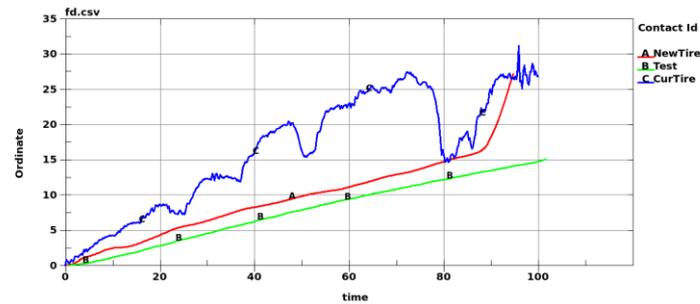
— Test  
— New tire  
— Current tire



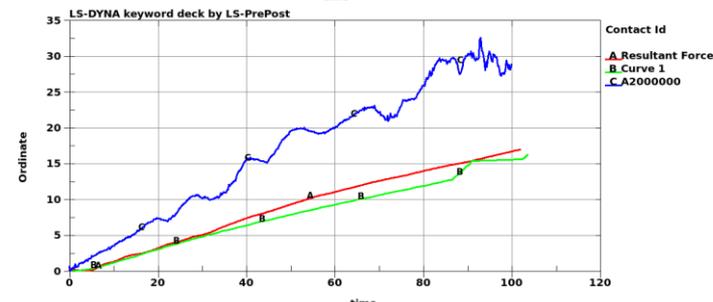
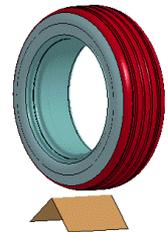
LS-DYNA keyword deck by LS-PrePost  
Time = 0



LS-DYNA keyword deck by LS-PrePost  
Time = 0



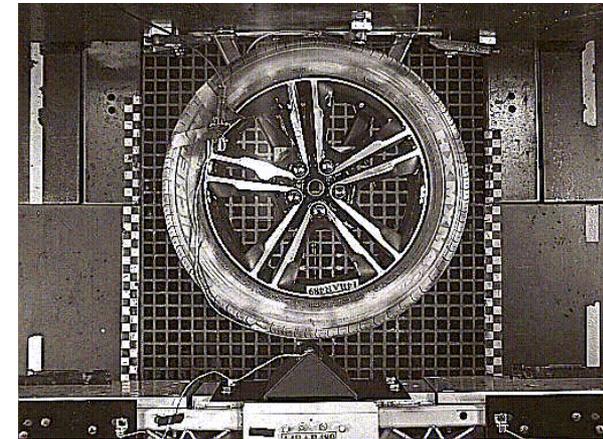
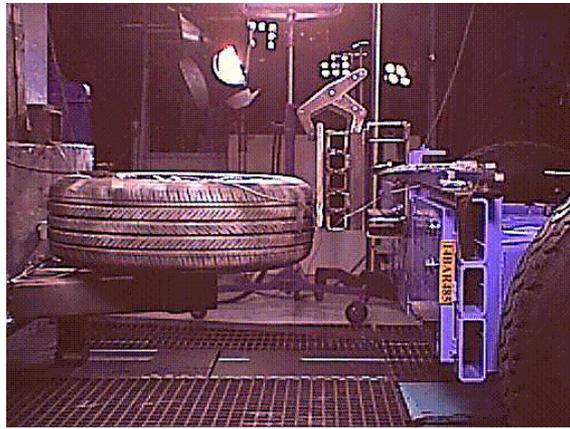
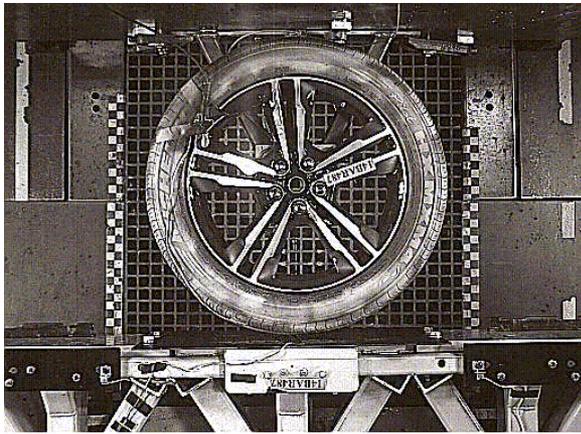
LS-DYNA keyword deck by LS-PrePost  
Time = 0



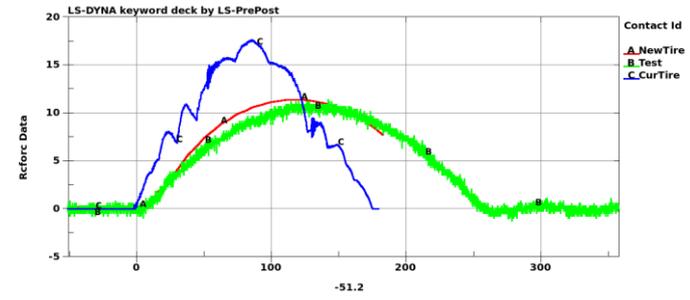
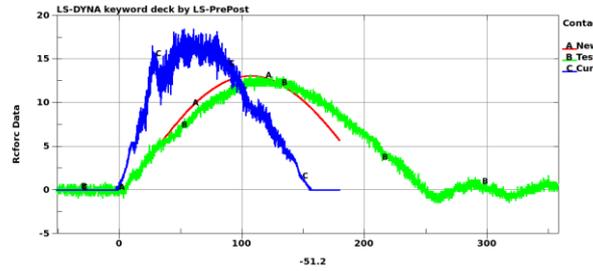
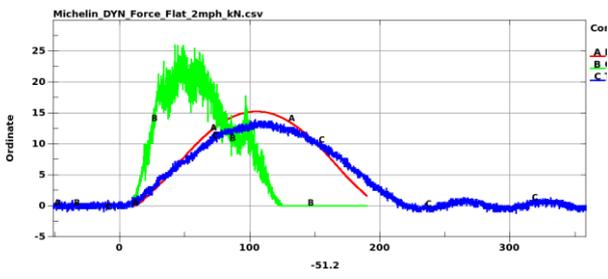
Time = 0



# Dynamic Tests



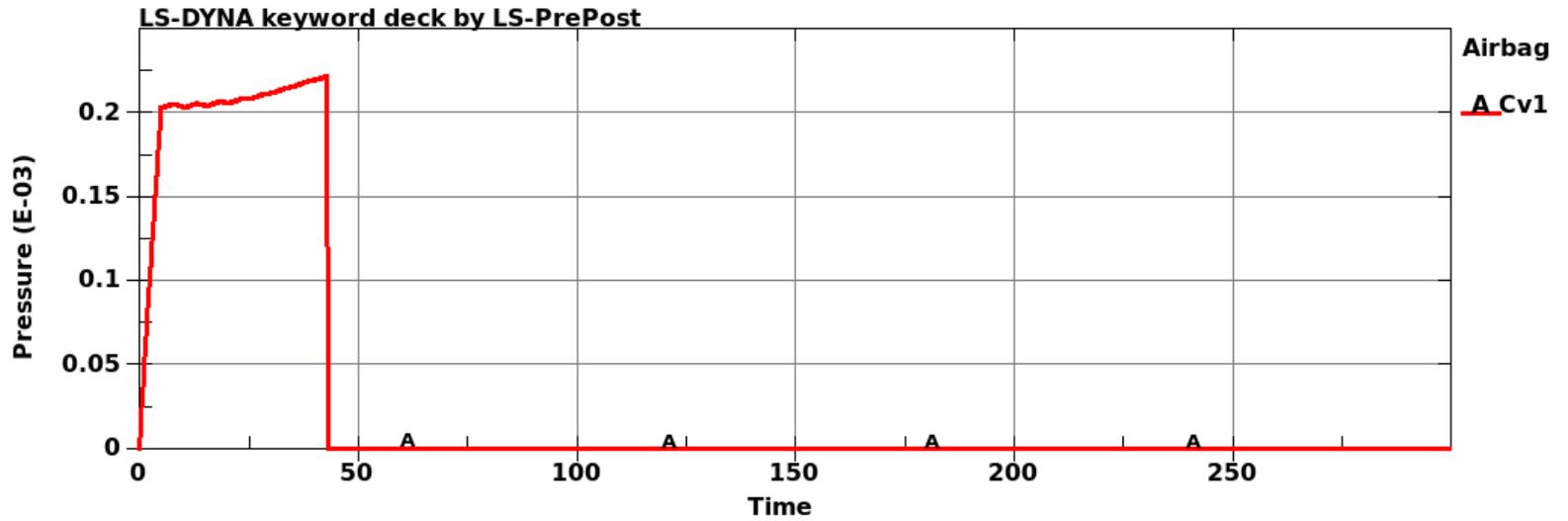
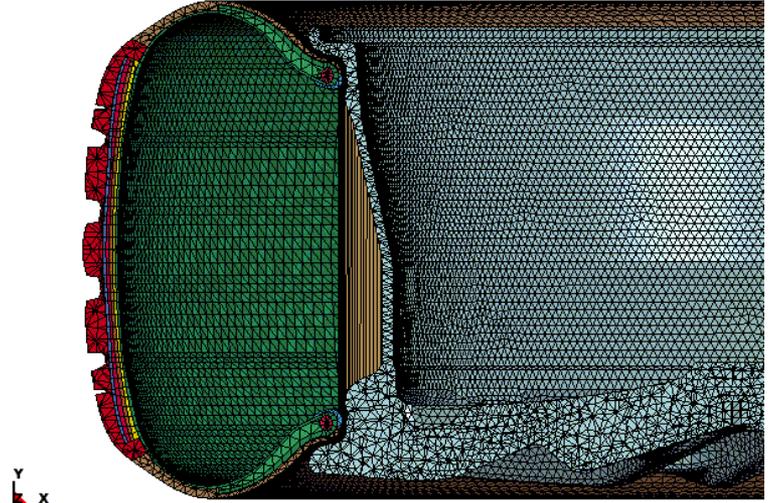
— Test  
— New tire  
— Current tire



LS-DYNA keyword deck by LS-PrePost  
Time = 0



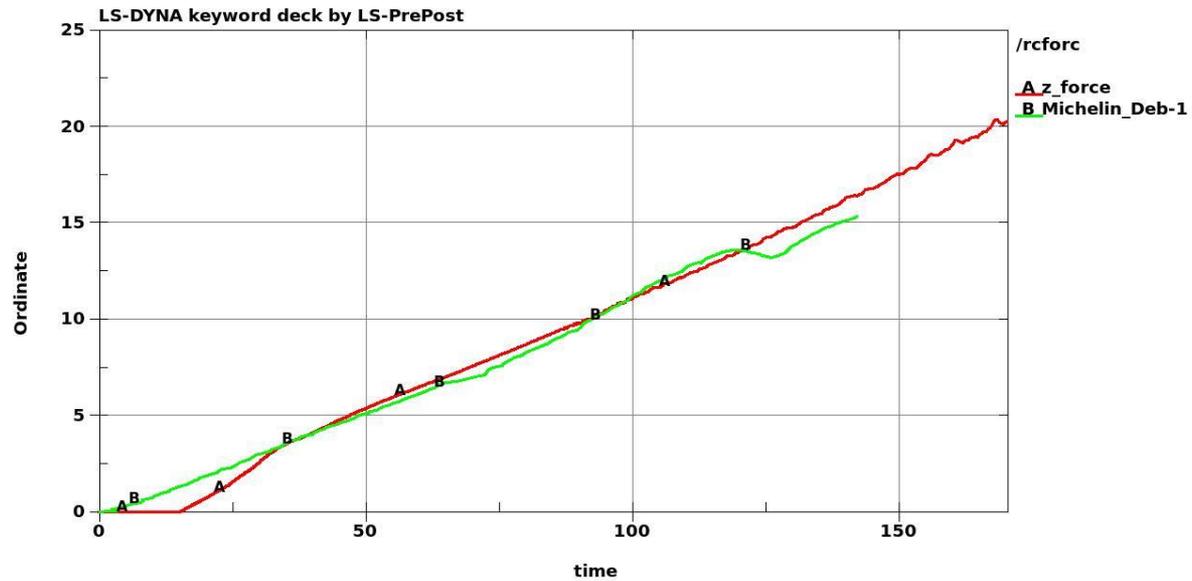
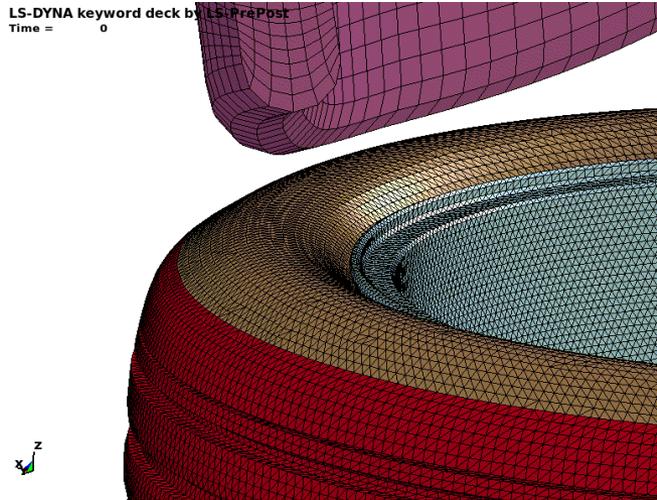
LS-DYNA keyword deck by LS-PrePost  
Time = 0



# De-beading

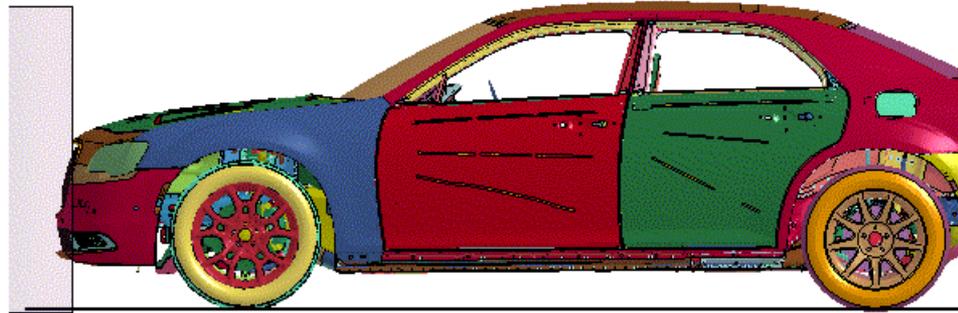


LS-DYNA keyword deck by LS-PrePost  
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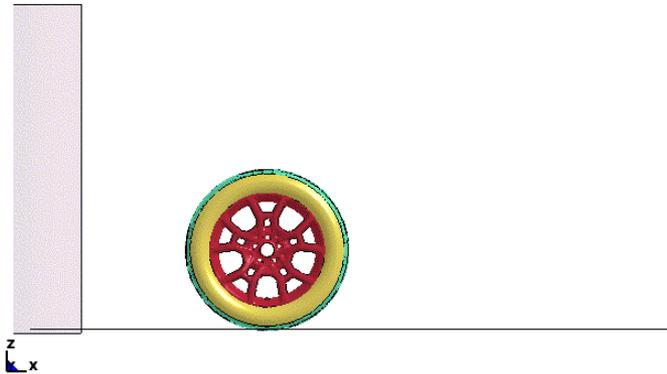


# Full Vehicle Integration

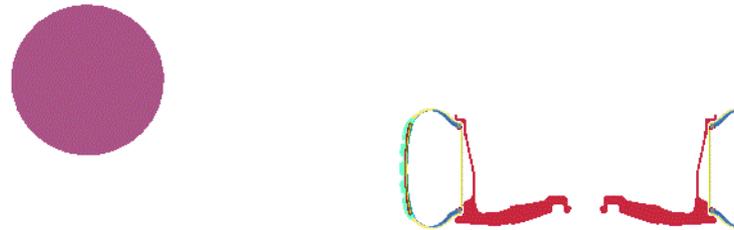
LS-DYNA keyword deck by LS-PrePost  
Time = 0



LS-DYNA keyword deck by LS-PrePost  
Time = 0



LS-DYNA keyword deck by LS-PrePost  
Time = 0



# Availability

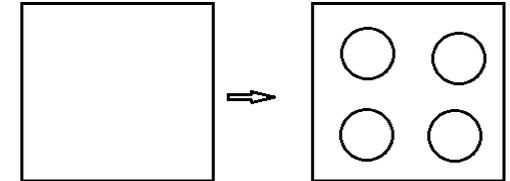
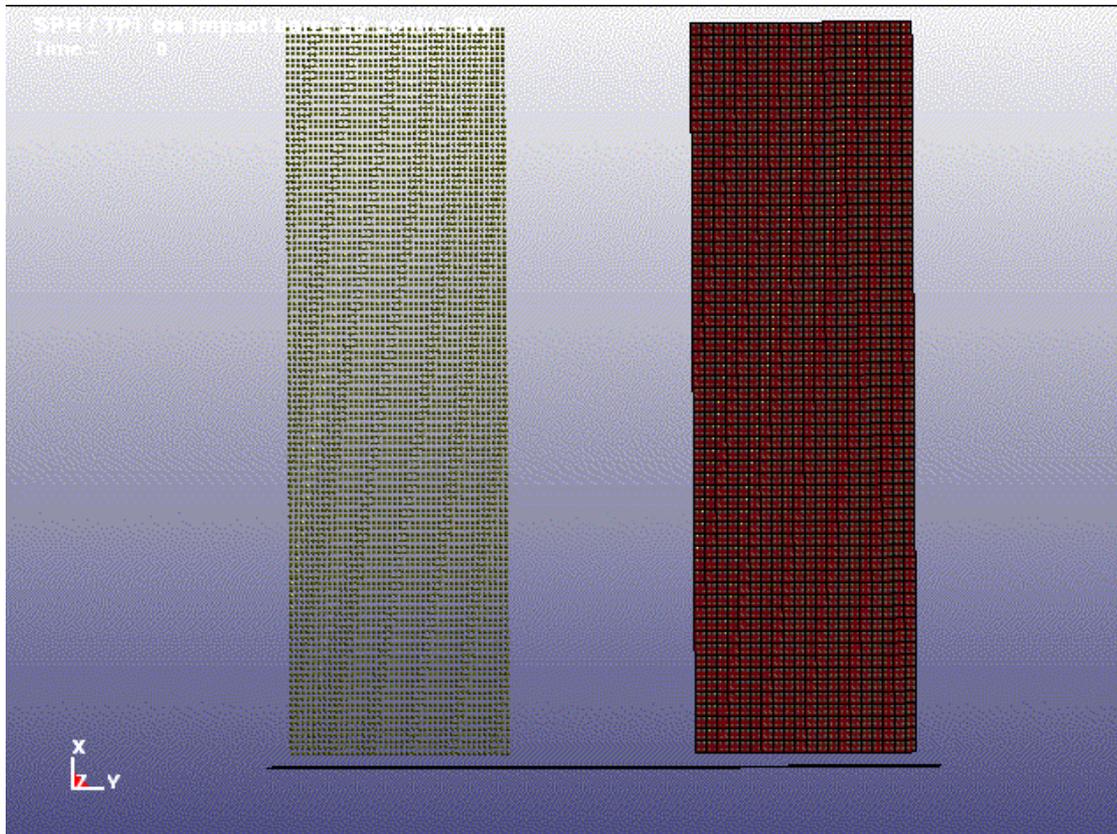
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- January 2018
- Model I
  - 400K solid elements, 1 Self Contact, 1 Surface 2 Surface Contact
  - Sensors to turn-off airbag based on tire pressure, wheel failure and contact separation
- Model II
  - With material failure MAT\_181\_WITH\_DAMAGE
  - Eroding single surface contact
  - Option to switch failed elements to DES/SPH for rubber
- Requesting tests from customers

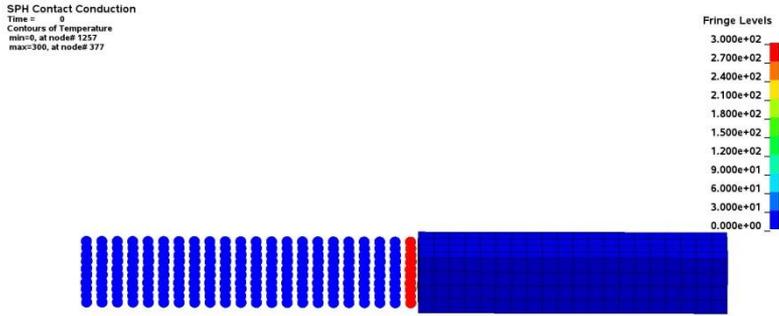
SPH, DEM

# \*DEFINE\_ADAPTIVE\_SOLID\_TO\_SPH for 2D Solids

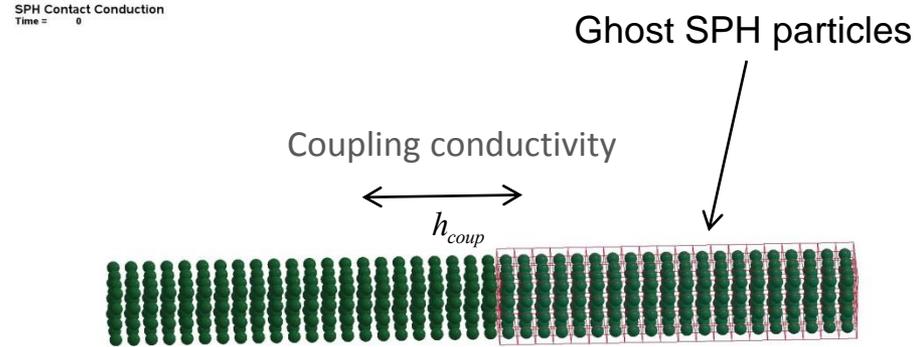
Adaptively transforms a 2D Solid part into 2D SPH particles with coupling or non-coupling options (works for 2D plane stress, 2D plane strain and 2D axisymmetric formulations, and supports all ICPL and IOPT options in this keyword).



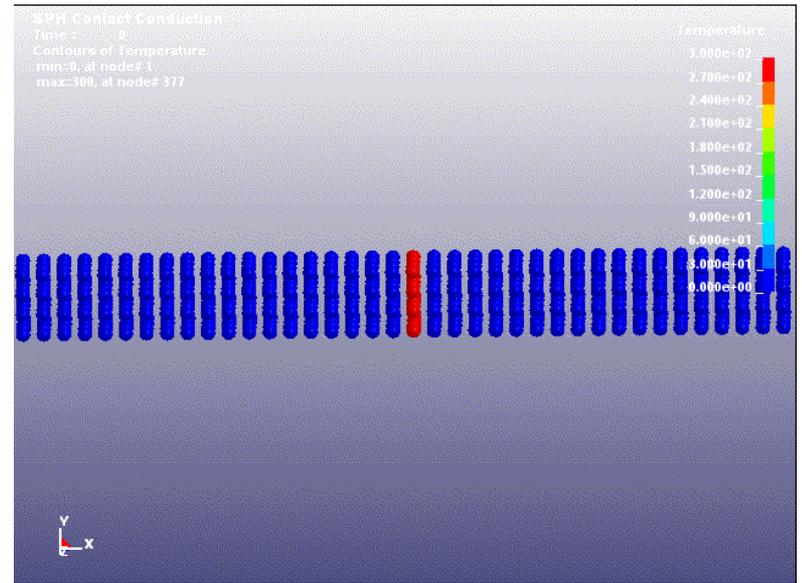
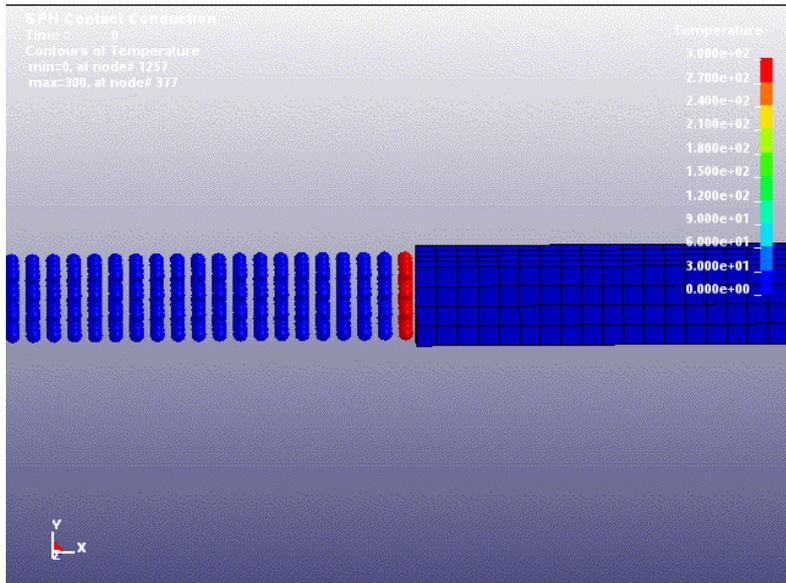
# Pure thermal coupling between SPH and Solid



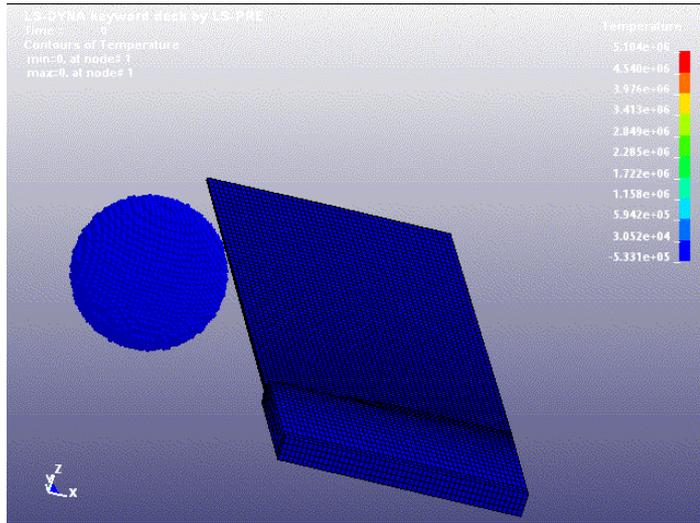
Initial Setup



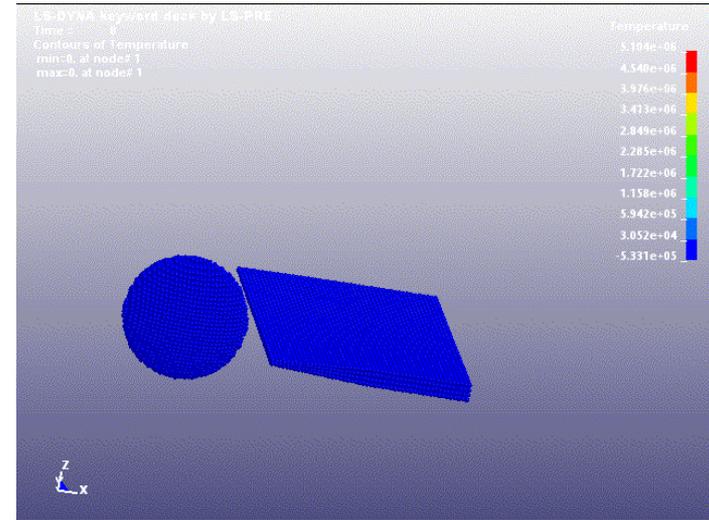
Coupling Setup



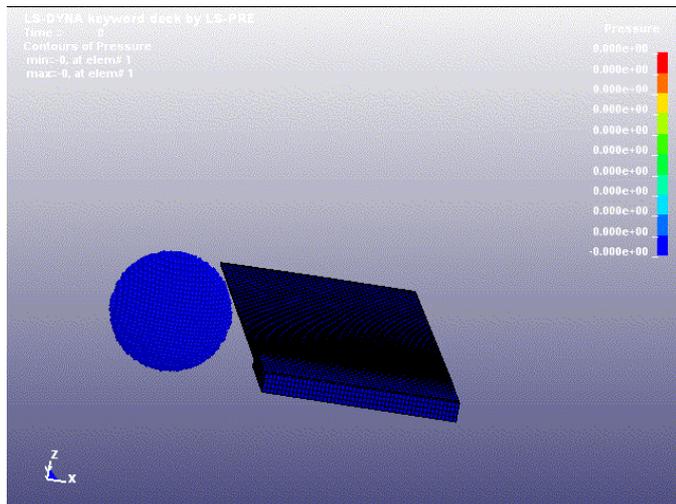
# High Velocity Impact with Solid Plate



Thermal contour



Thermal coupling between original and ghost SPH particles



Pressure contour

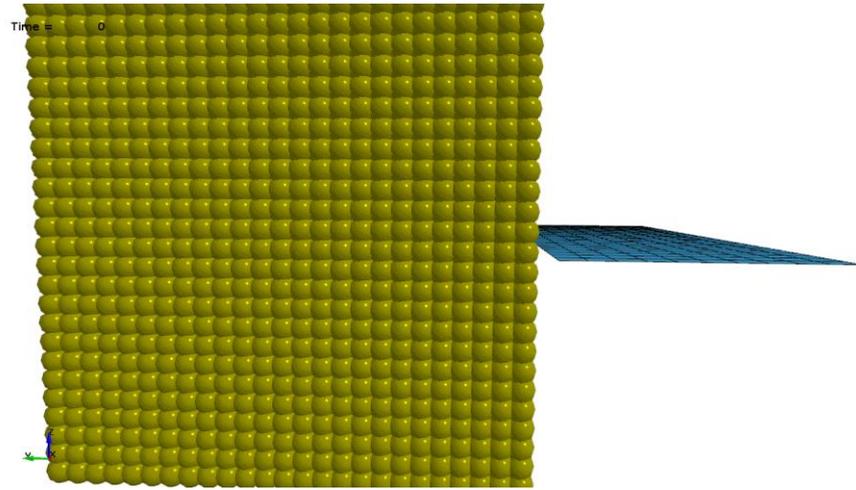
Heat from contact friction and the conversion of the mechanical work into heat.

\*DEFINE\_ADAPTIVE\_SOLID\_TO\_SPH:  
ICP = 3 and IOPT = 0

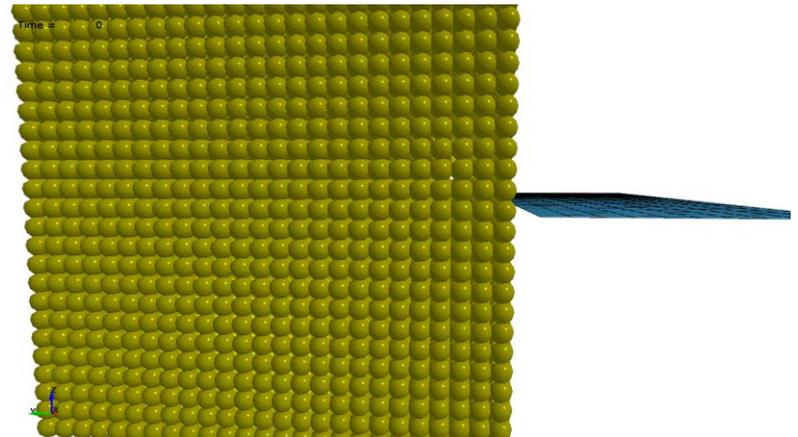
# Shell Edge Contact

\*Contact\_Automatic\_Nodes\_To\_Surface  
Optional card E, parameter SRNDE

.SRNDE = 0 Usual edge treatment



.SRNDE = 2 Square shell edges

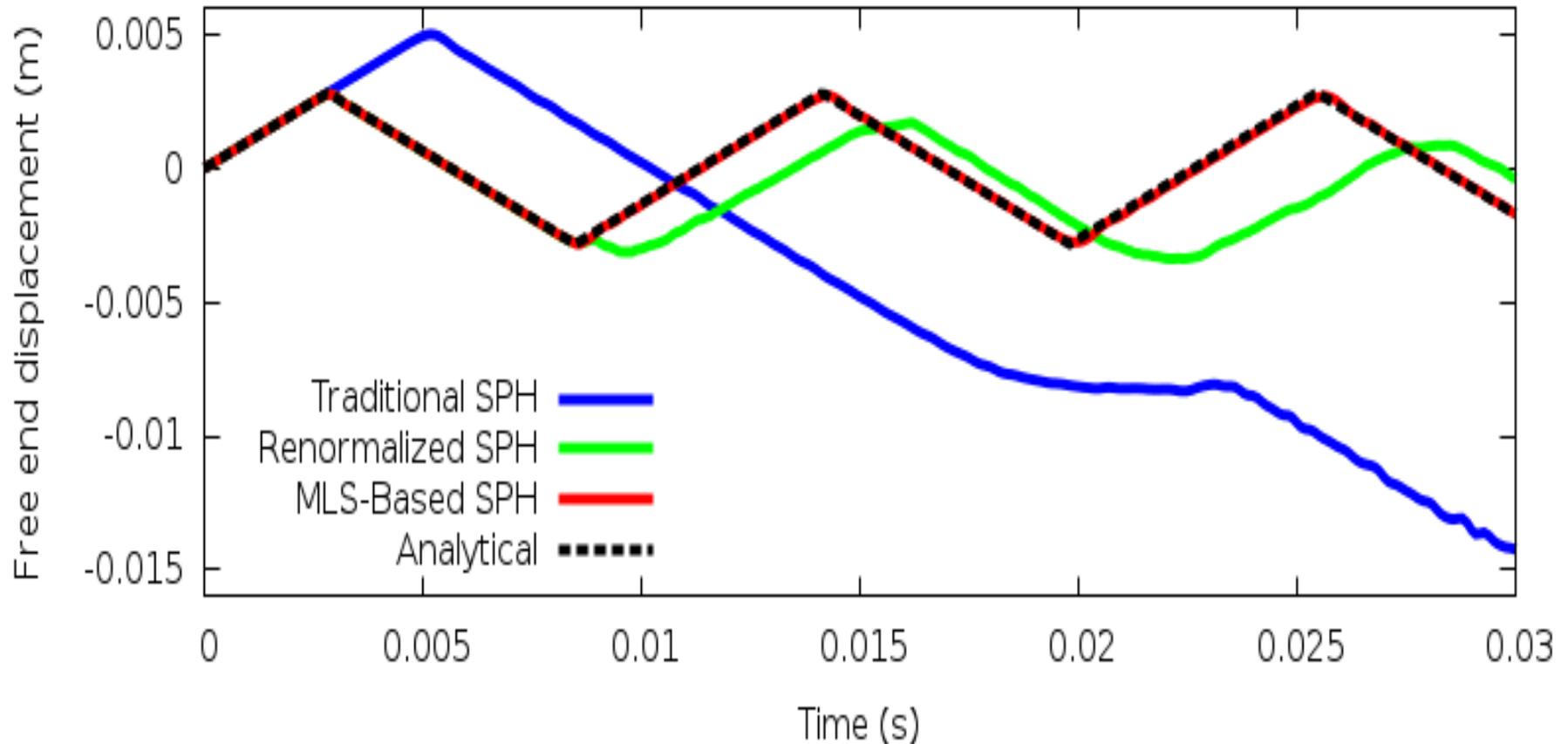


# MLS-Based SPH Formulation 12

\*Control\_SPH parameter IFORM = 12

✓Better accuracy

## Wave Propagation problem



# MLS-Based SPH Formulation 12

- ✓ Better accuracy
- ✓ Less tensile instability
- ✗ More CPU-intensive



MLS Based SPH (Form 12)



Traditional SPH (Form 0)

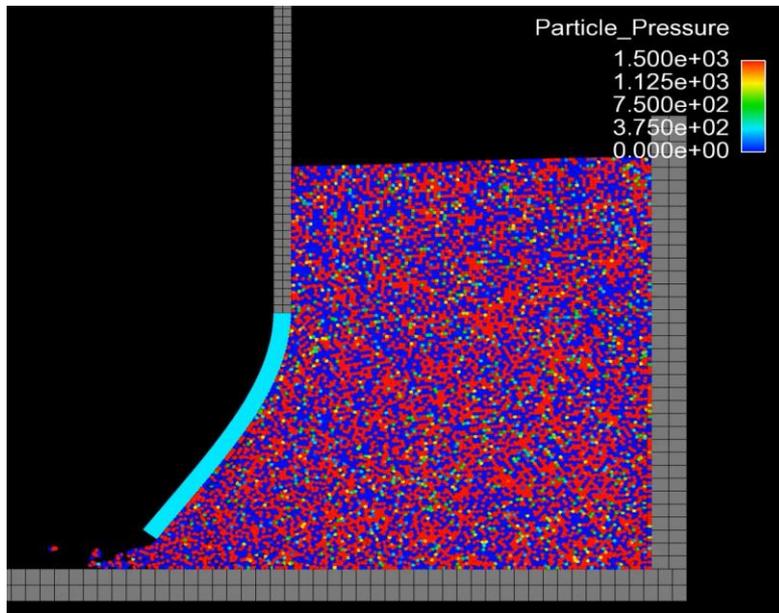
# SPH Enhancements

## \*CONTROL\_SPH

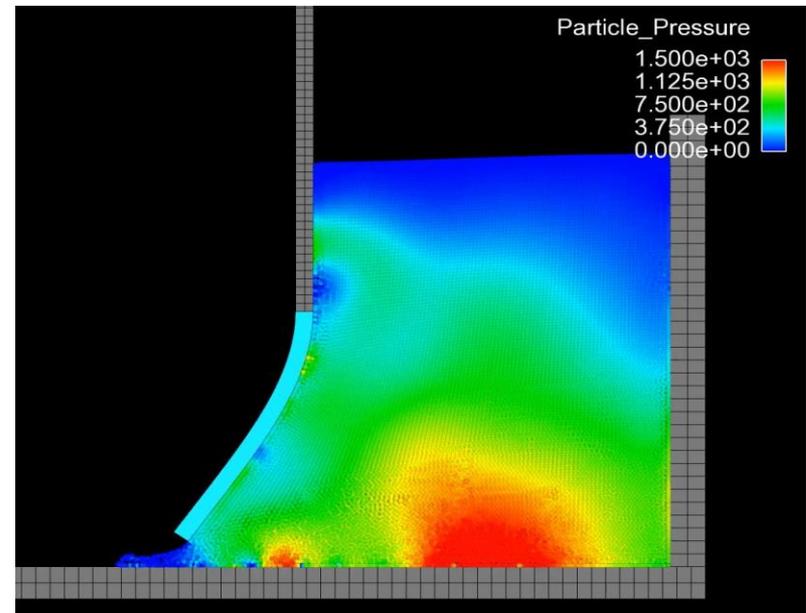
IFORM = 15/16 Enhanced fluid formulation wo/w kernel renormalization

Density smoothing:  $\tilde{\rho}_I = \frac{\sum_J \rho_J \phi_{IJ}}{\sum_J \phi_{IJ}}$  with  $\phi_{IJ} = W_{IJ} m_J / \rho_J$

→ Smooth pressure field



IFORM=0



IFORM=15

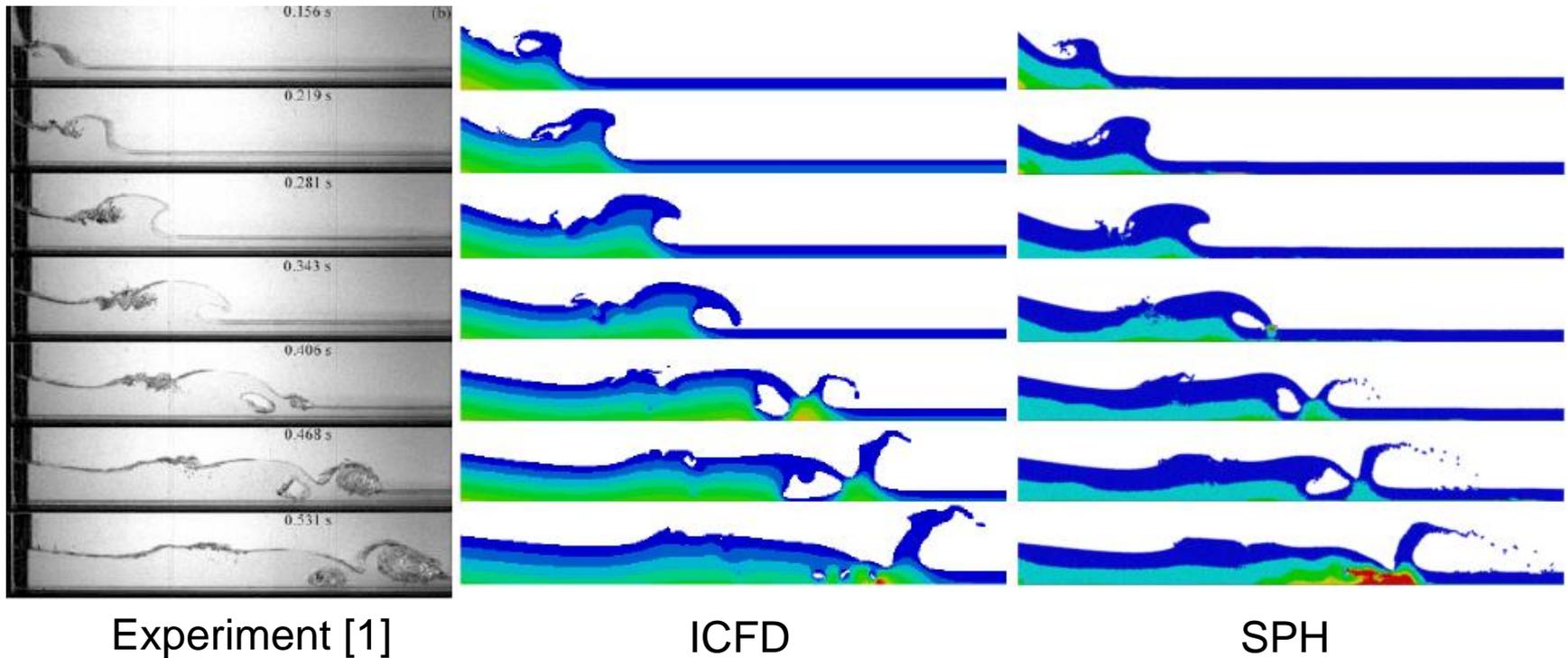
# SPH Enhancements

## Murnaghan Equation of State

Weakly compressible formulation to numerically reduce the sound speed, and consequently increase the time step size

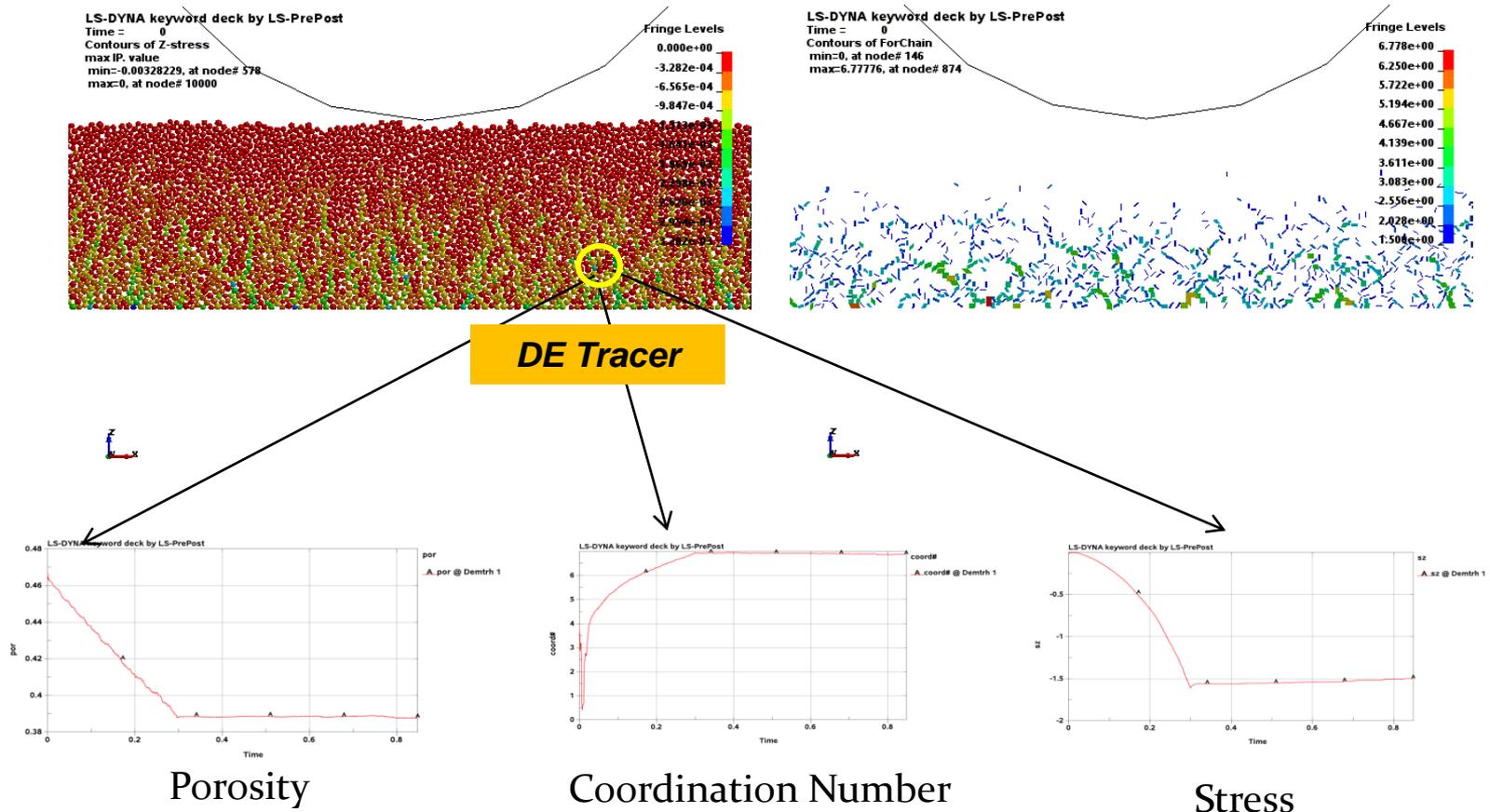
Enforce low compressibility

Validation: 2D dambreak, free surface flow



# DEM General Features

- Force chain fringe plot
- Porosity, stresses and coordination number can be traced



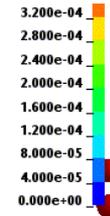
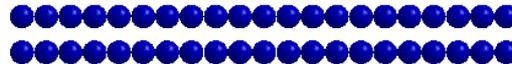
# DEM General Features

- Non-reflecting B.C. used on the exterior boundaries of an analysis model of an infinite domain

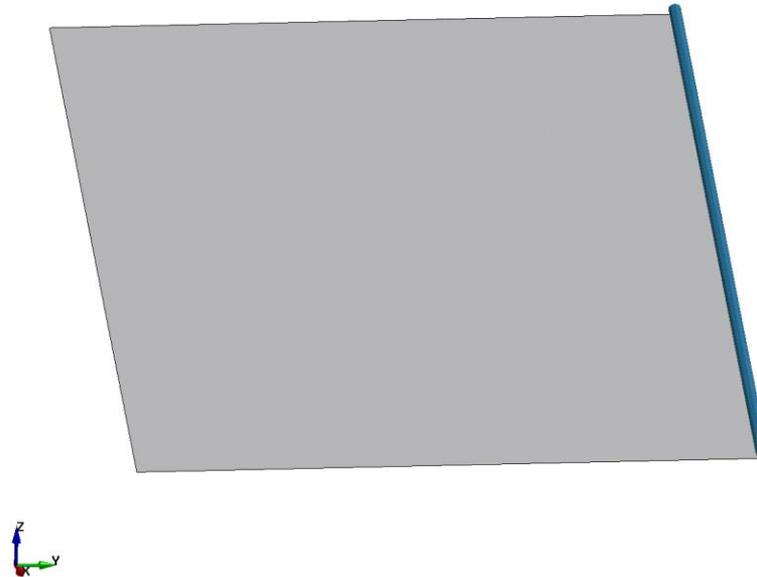
Without

NRBC

With

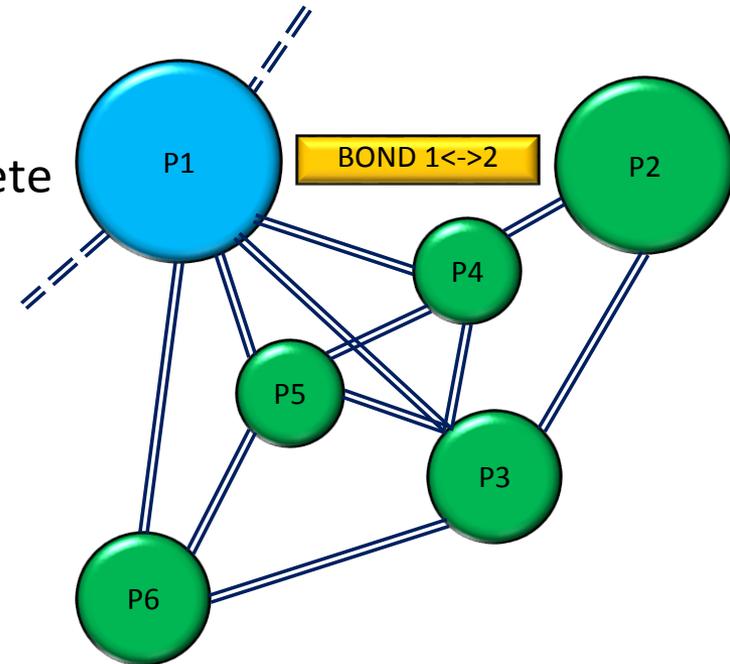


- \*DEFINE\_DE\_TO\_SURFACE\_COUPLING

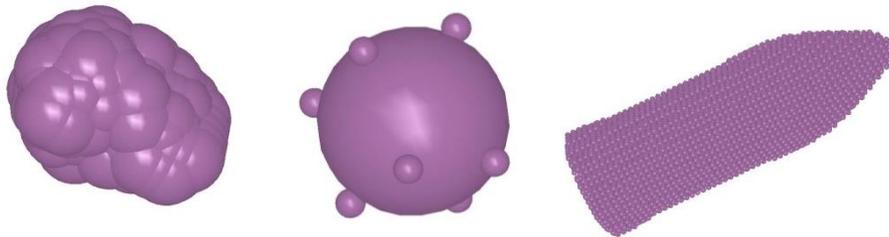


# DEM – Bonded DEM

- Particles are linked to their neighboring particles through bonds within a specified range.
- The properties of the bonds represent the complete mechanical behavior of Solid Mechanics.
- The bonds are independent from the DES model.
- They are calculated from Bulk Modulus and Shear Modulus of materials.
- Contact is disabled between bonded pair
- Contact is reactivated after bond broken



*Use bonds to form other shapes*

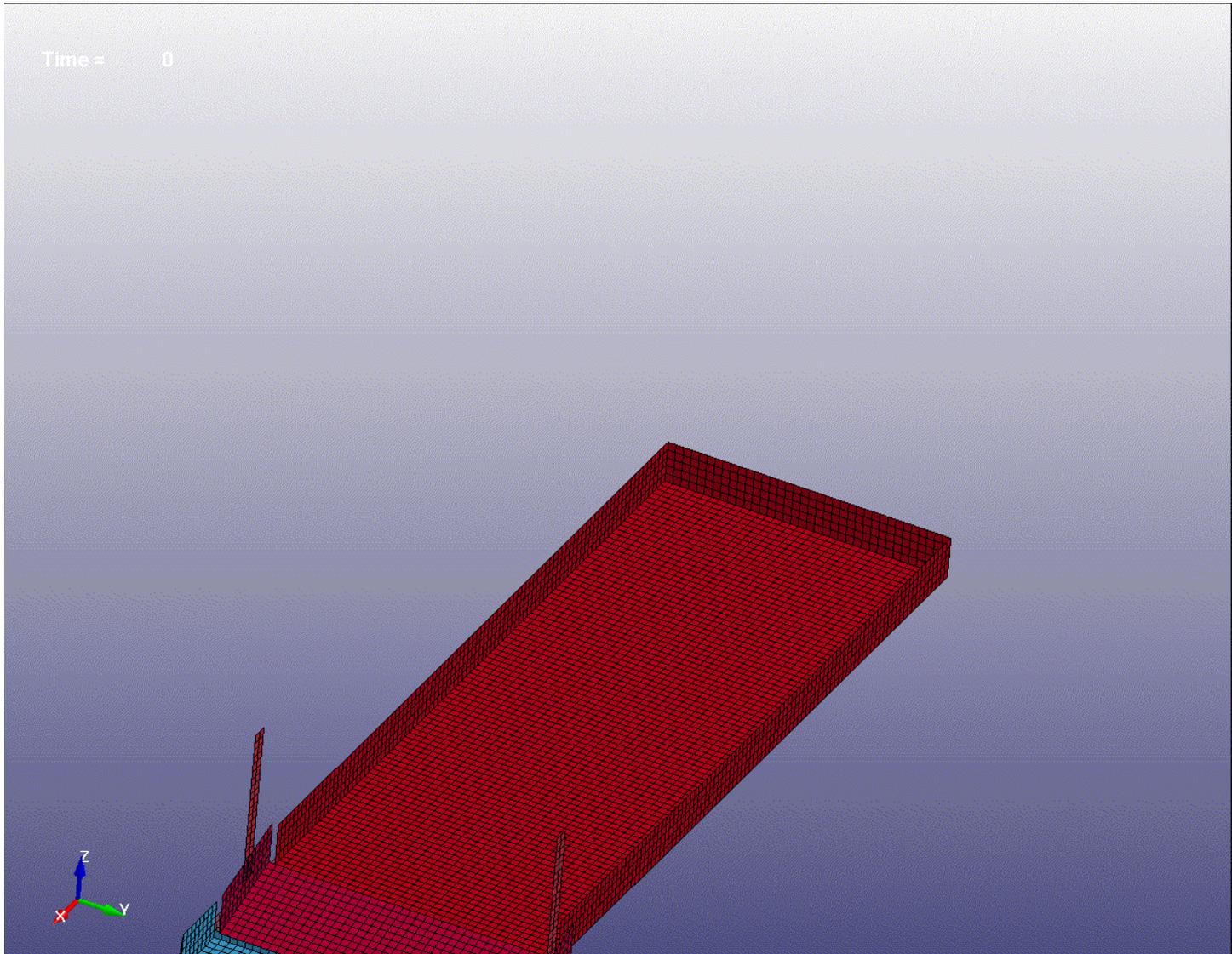


LS-DYNA keyword deck by LS-PrePost  
Time = 0



# DEM – Food sorting process

---



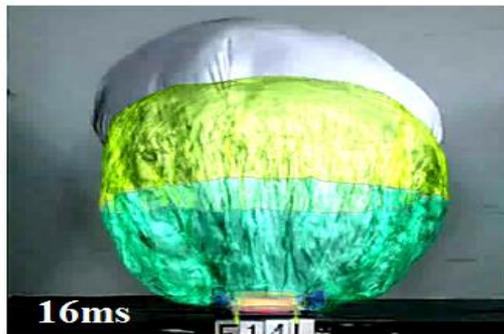
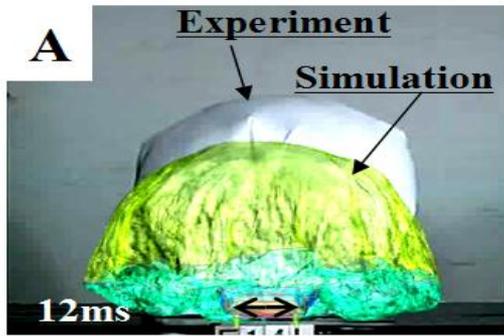
CPM

Airbag\_particle



# \*DEFINE\_CPM\_VENT

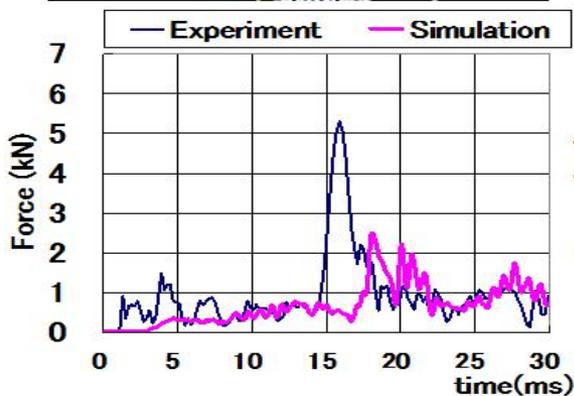
## Internal vent with cone angle



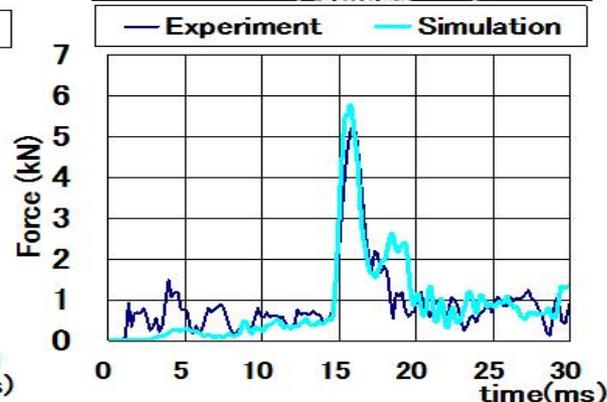
This new option greatly helps to improve the correlation between tests and simulations

1. Cone angle is defined by using above keyword card.
2. Additional option VANG=-1 will allow code to adjust the release based on the vent condition

*H. Ida, M. Aoki, M. Asaoka, K. Ohtani, "A Study of gas flow behavior in airbag deployment simulation", 24th International Technical Conference on the Enhanced Safety of Vehicles(ESV). No. 15-0081, 2015.*



**Deployment force of "A"**



**Deployment force of "B"**

# Benchmark DAB Models

*ALE*

*CPM: NO VANG*

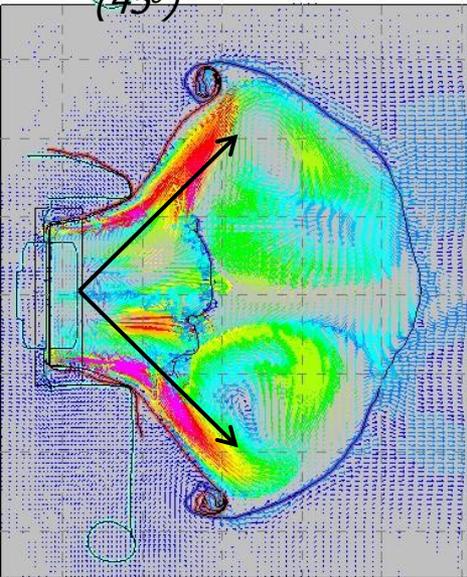
*CPM: VANG=-1*

D3PLOT: M1: DAB ALE 06

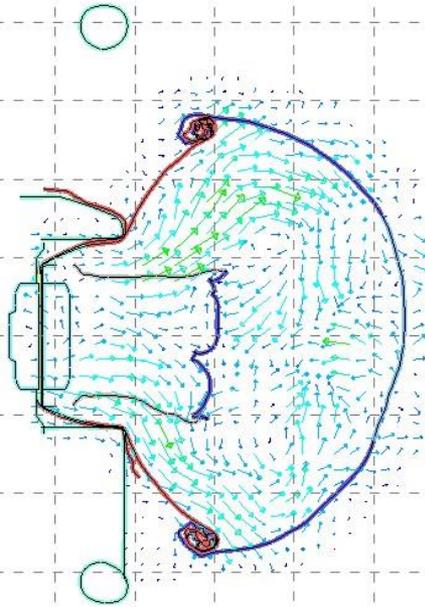
D3PLOT: M4: DAB CPM09

D3PLOT: M3: DAB CPM10

Estimated gas flow redirection angles  
(45°)

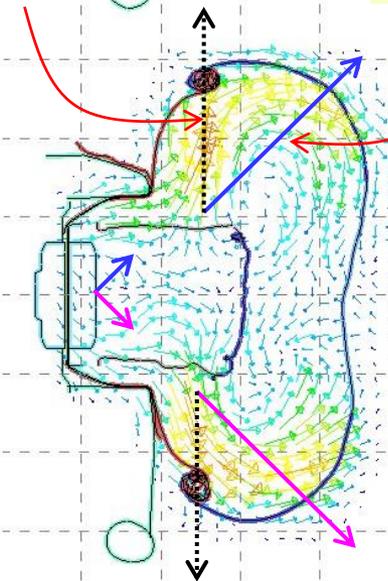


z  
x  
0.007



VANG=-1

NEW VANG FUNCTION



z  
x  
0.007

z  
x  
0.007

Velocity contour  
0~340m/s

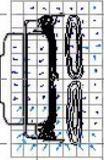
*Side View*

Courtesy of: Richard Taylor, Arup

```
*DEFINE_CPM_VENT  
VANG=-2
```

VANG=-2

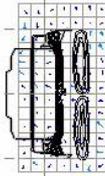
D3PLOT: M1: DAB CPM11



.000000000

VANG=-1

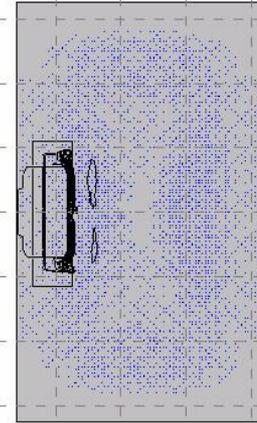
D3PLOT: M2: DAB CPM10



.000000000

ALE

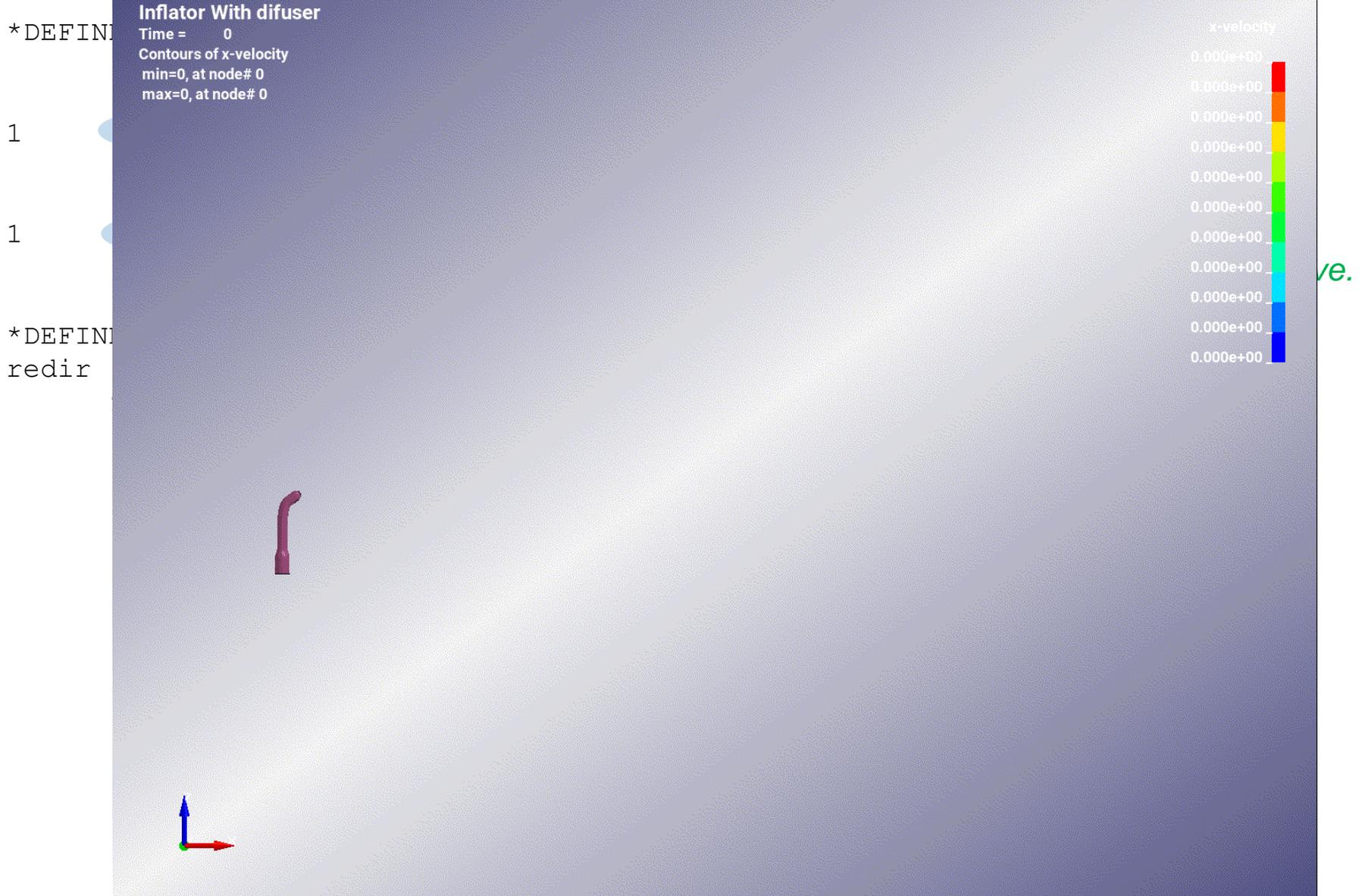
D3PLOT: M3: DAB ALE 06



0.001000

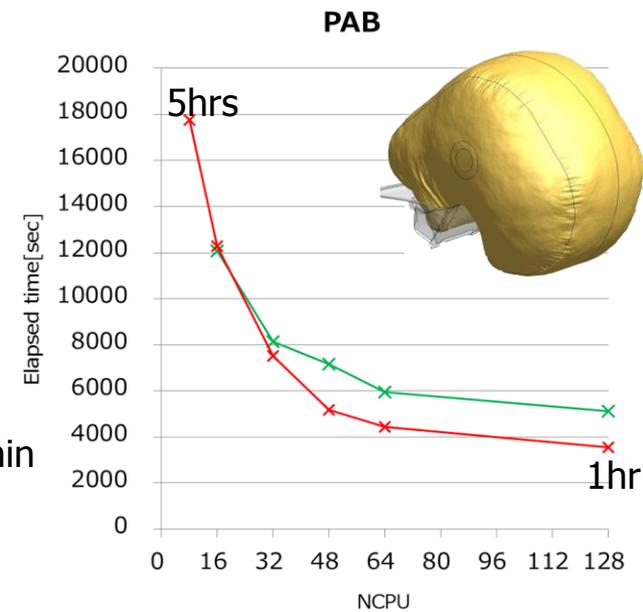
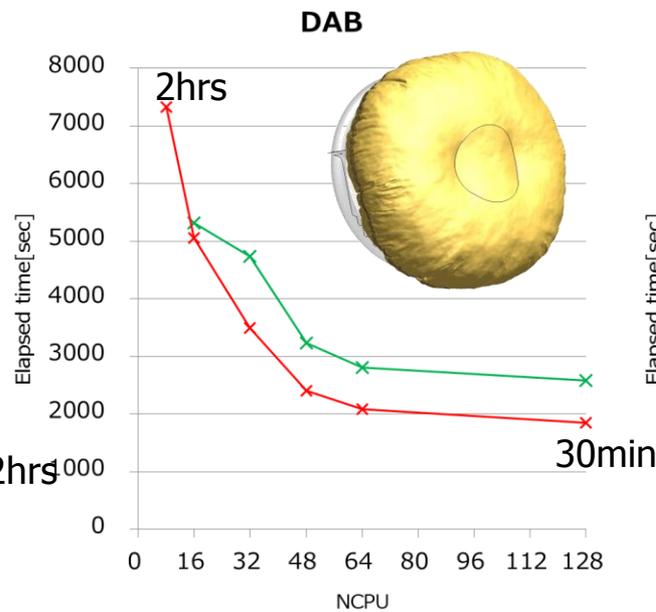
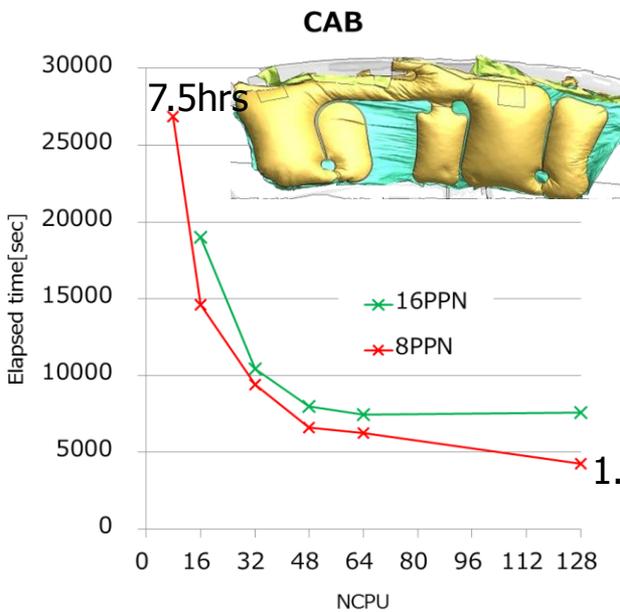
Under development, VANG=-2  
user can define a local coordinate system for 'jet' to follow.

# \*DEFINE\_CPM\_VENT, Internal vent with cone angle



# Baseline Airbag Models

- Baseline airbag models created by JSOL/Arup for demo/research purposes.
  - CAB = curtain airbag, DAB = driver's airbag, PAB = passenger airbag
- All models have typical size, shape, inflator & fabric.
- All have been developed to be robust (insensitive, repeatable, not prone to error) and inflate with no issues.

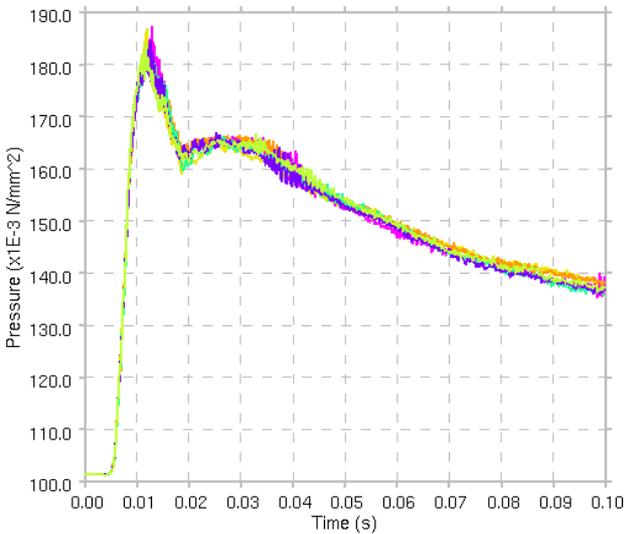


Courtesy of: Richard Taylor, Arup

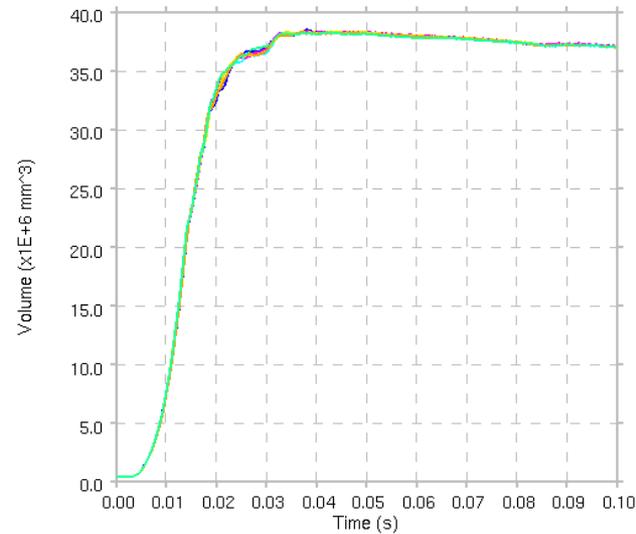
# CAB – Results Check (R9)

- The CAB model has no external vents and no porosity.
- It also has a constant decomposition pattern: particle domain divided along X-axis
- Results are very consistent across all analyses.
- The reason for the slight increase in internal energy in all cases is unknown.

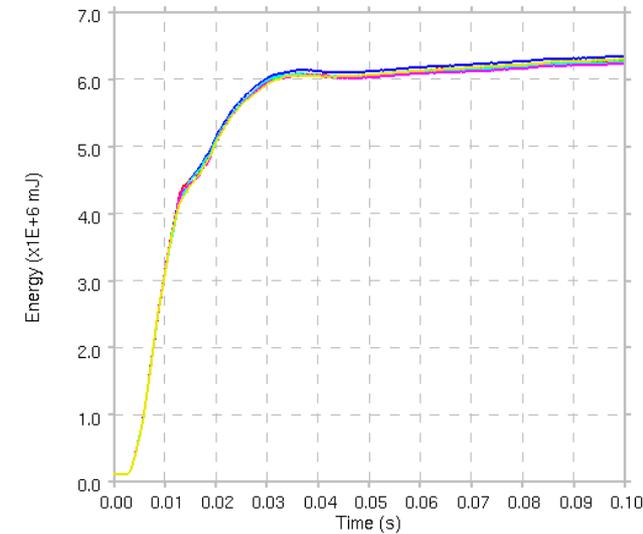
Pressure



Volume

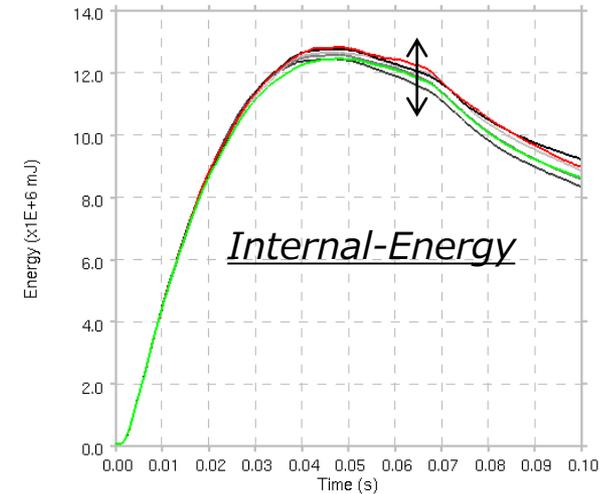
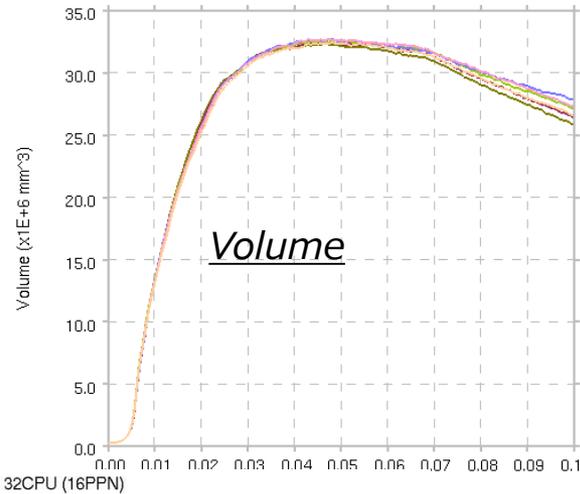
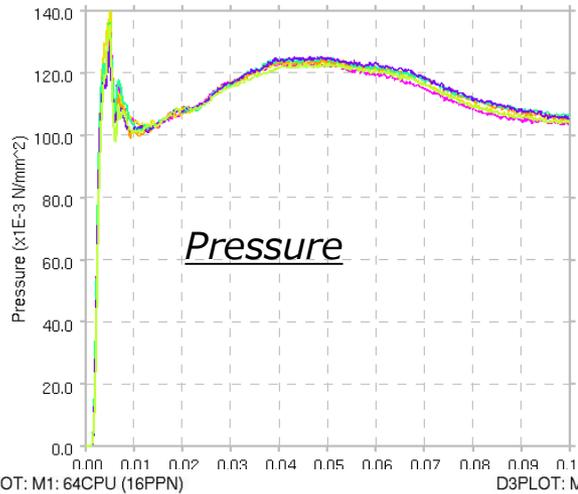


Internal-Energy

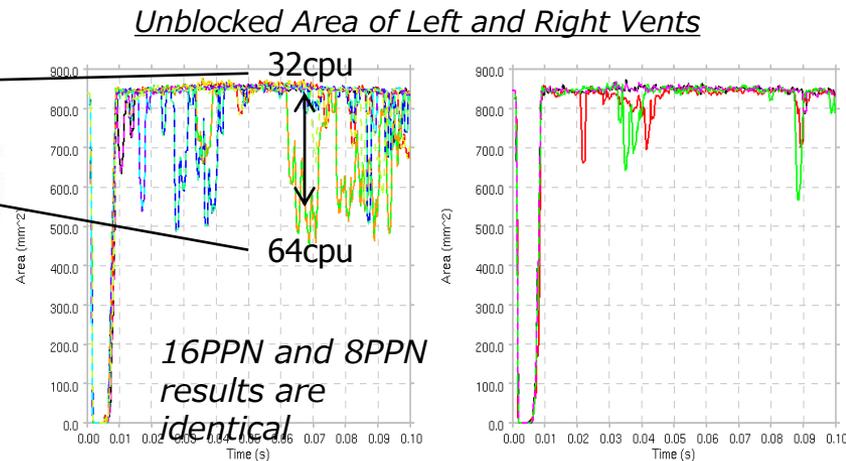
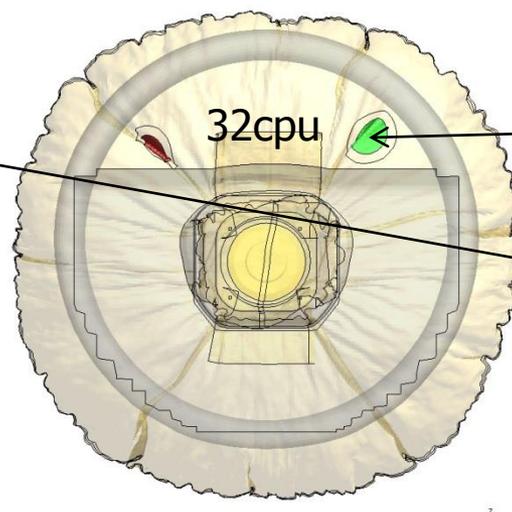
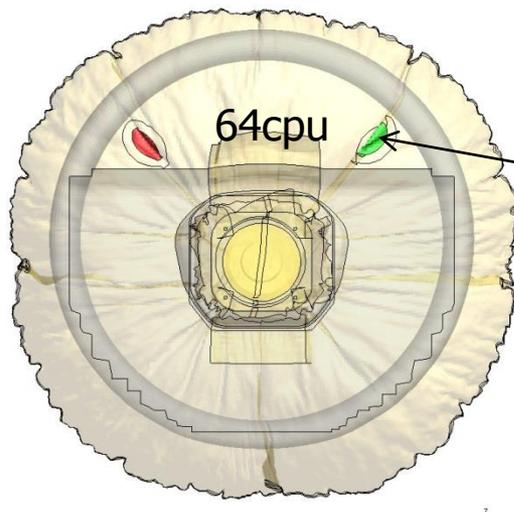


# DAB – Results Check (R9)

- The DAB model has two external vents, fabric and seam line porosity, all affected by contact blocking. Despite this results are very similar for all analyses.



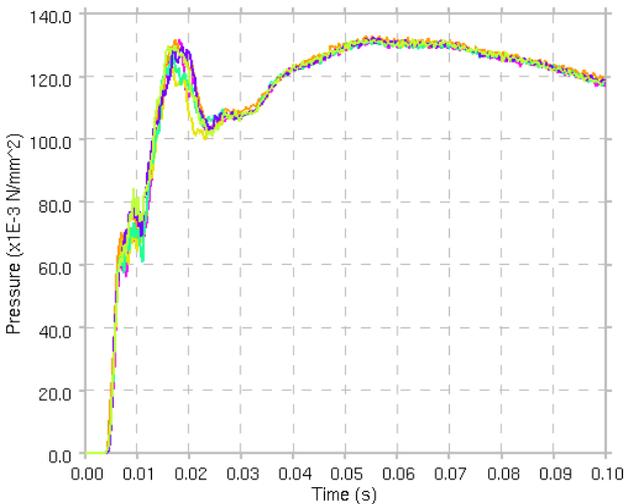
The slight difference in internal energy is due to different levels of **vent contact blocking** by **different crease patterns**.



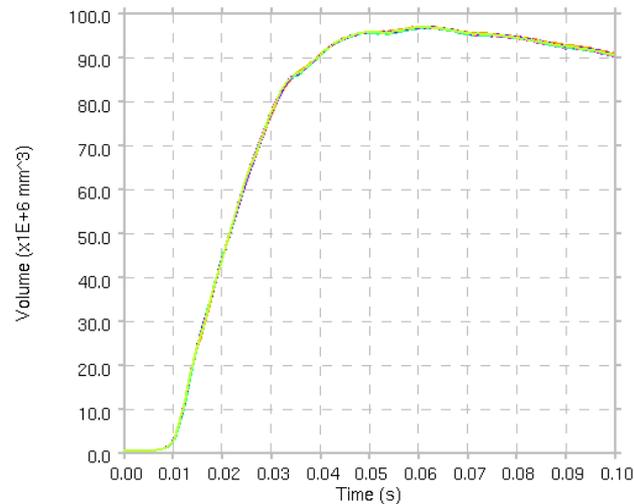
# PAB Results Check (R9)

- The PAB model has two large external vents but no fabric or seam porosity.
- Creases are not generated in the fabric near the vents so the sensitive contact blocking seen in the DAB is not a problem.
  - Unblocked area and mass-flow from vents in all models is consistent

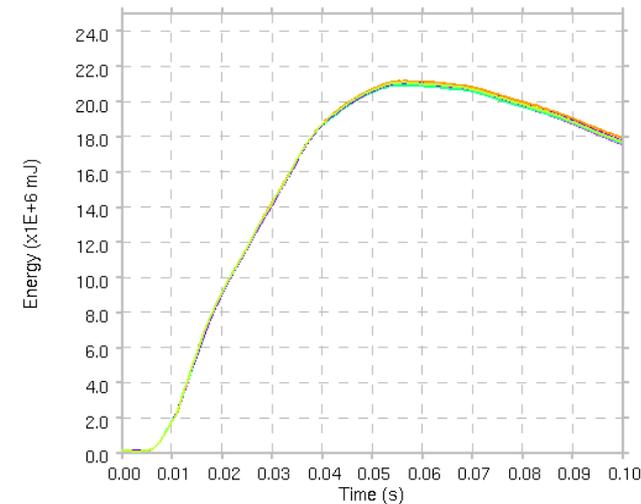
*Pressure*



*Volume*



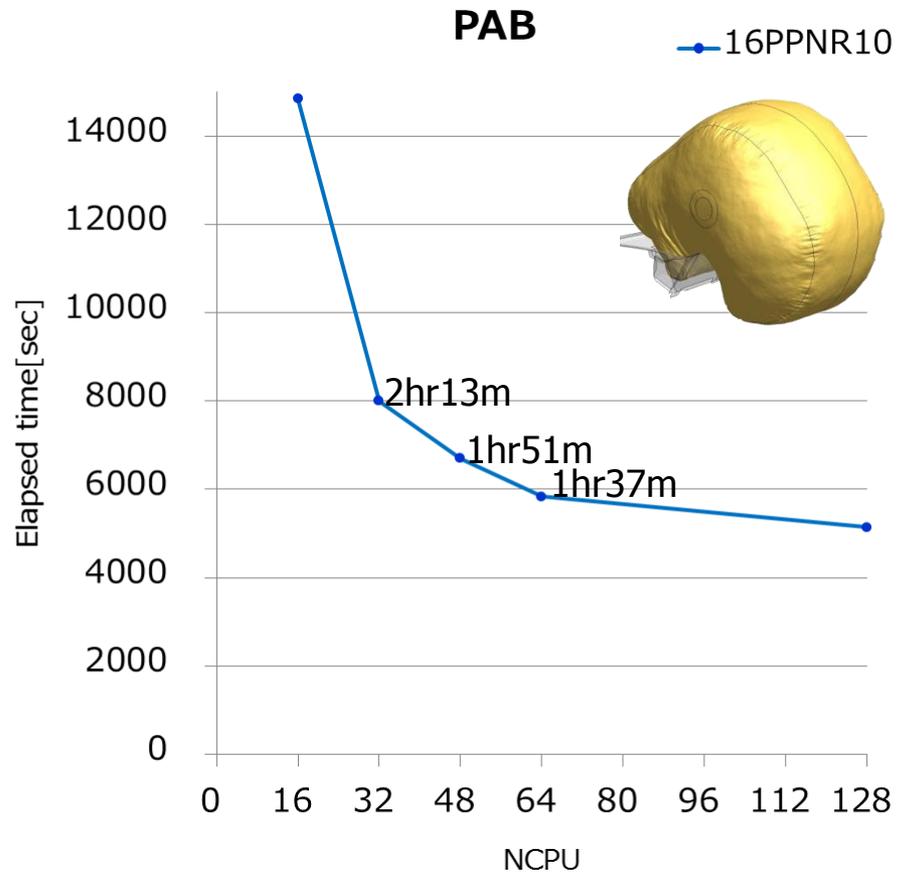
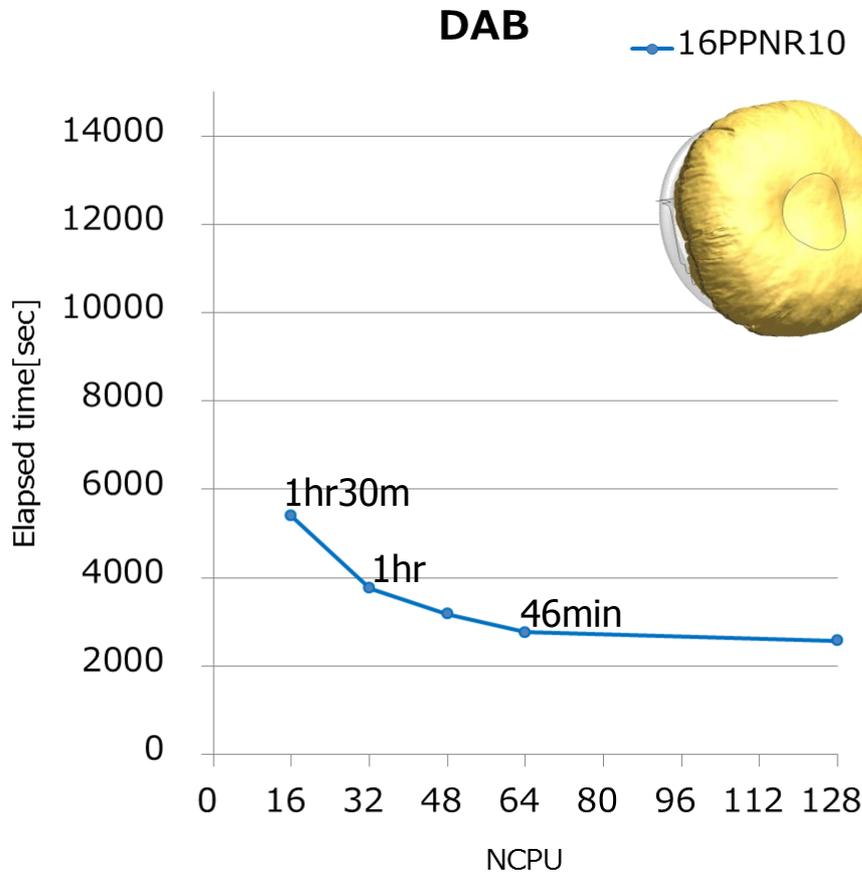
*Internal-Energy*



# \*CONTROL\_MPP\_DECOMPOSITION\_ARRANGE\_PARTS NPROC option with Two Bags Summary (R10)

- Two airbags deployed in one model
- Each airbag has its own \*CONTROL MPP DECOMP ARRANGE PARTS.
- All models run on 64cpu in R10.

*Elapsed Time when run separately (R10)*



# MPP Decomposition

---

**\*CONTROL\_MPP\_DECOMPOSITION\_ARRANGE\_PARTS**

*Part/Part Set ID, TYPE, NPROC, FRSTP*

- Part/Part Set ID
- TYPE:
  - 0 Part ID to be distributed to all processors
  - 1 Part Set ID to be distributed to all processors
  - 10 Part ID to be lumped into one processor
  - 11 Part Set ID to be lumped into one processor

- PROC: Evenly distributed elements in above Part/Part Set to number of NPROC processors
- FRSTP: Starting MPP rank

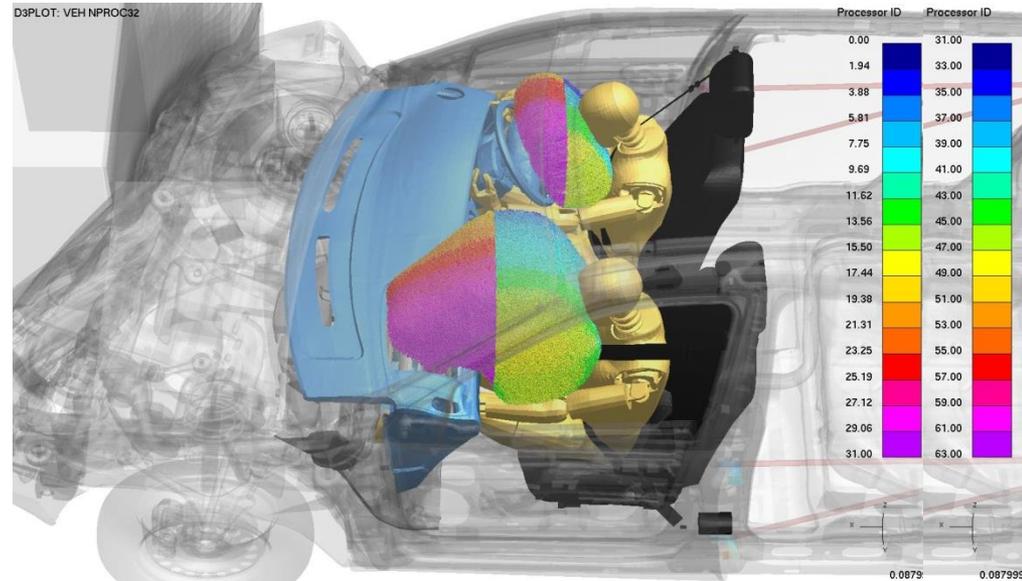
*These options only work with element distribution, Type=0/1*

*pfile options:*

region { parts/partset *ID* nproc # *nfrst* }

# Two Airbags in Full Vehicle (R10)

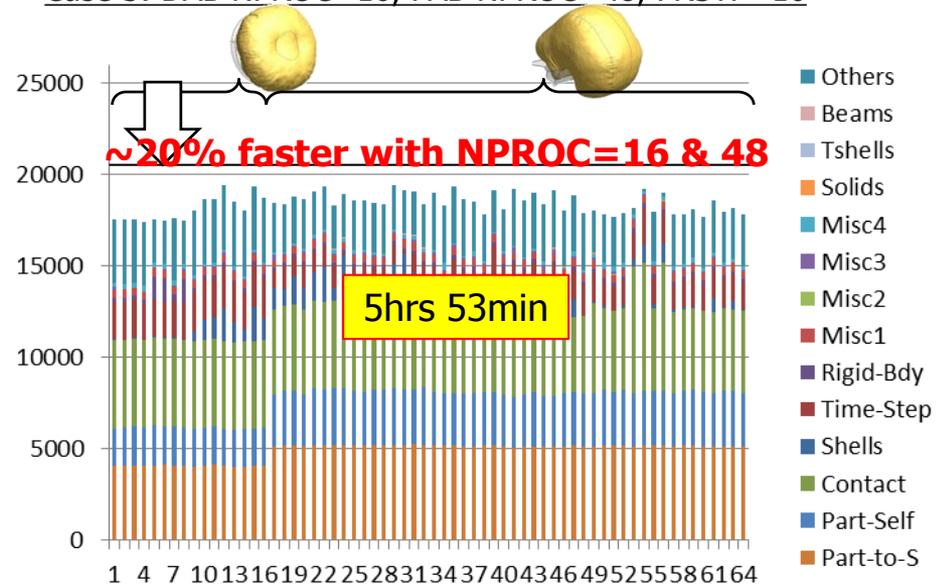
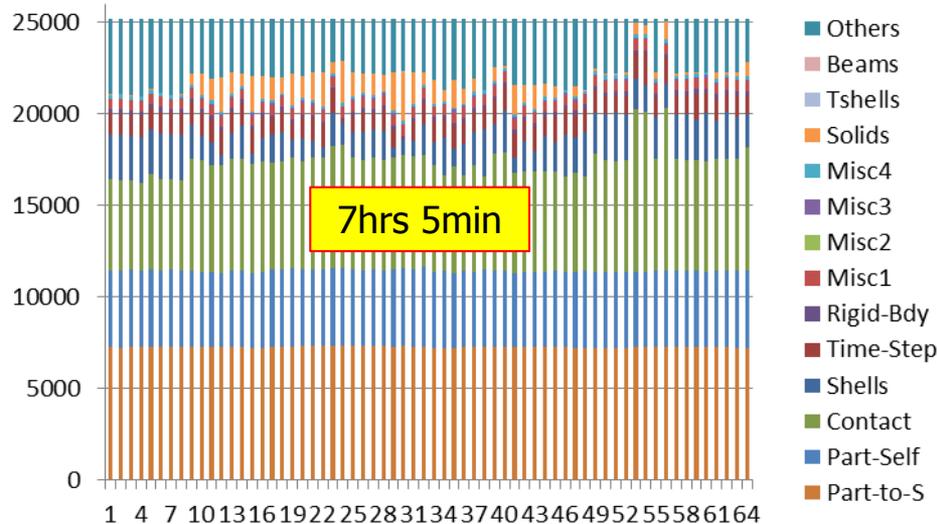
To try and reduce total run time we set NPROC=16 for the DAB and NPROC=48 for the PAB. We allocate the PAB from processor 16 (FRSTP=16).

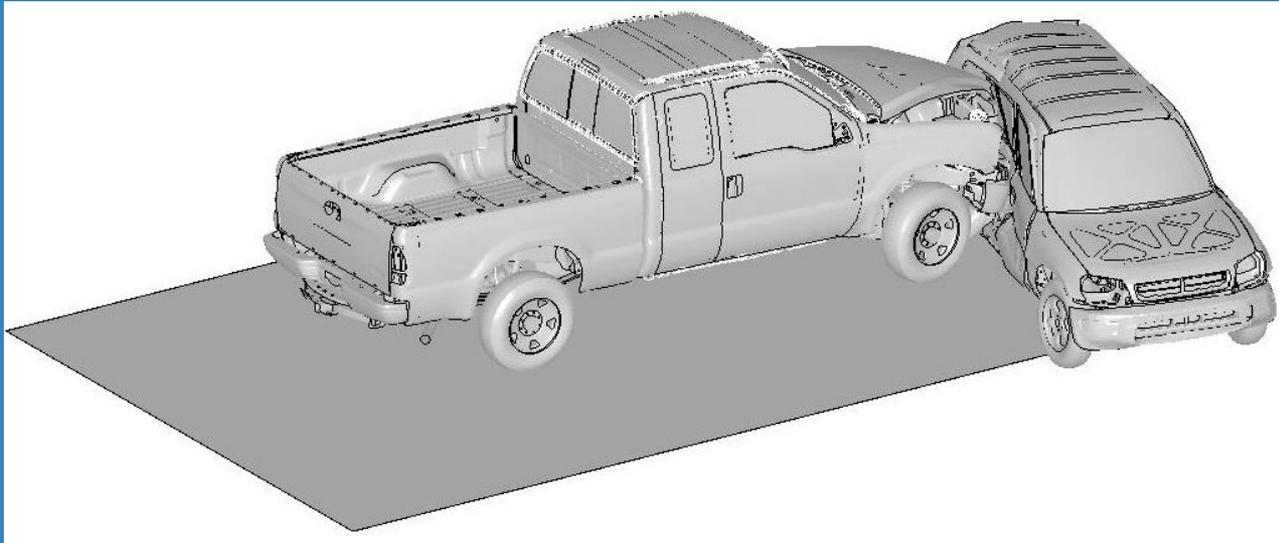


Case 3: DAB NPROC=16, PAB NPROC=48, FRSTP=16

Runtime reduced from 7hrs 5min to 5hrs 53min. *20% faster.*

Case 1: DAB & PAB 64cpu, NPROC=0





# Contacts

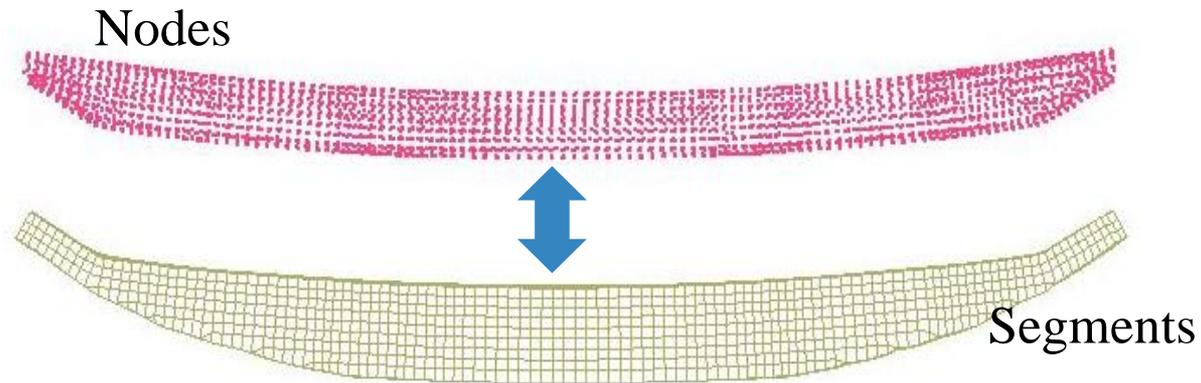
Allows unmerged Lagrangian elements to interact with each other

- Parts that impact/push/slide/rub against each other
- Parts that should be tied together

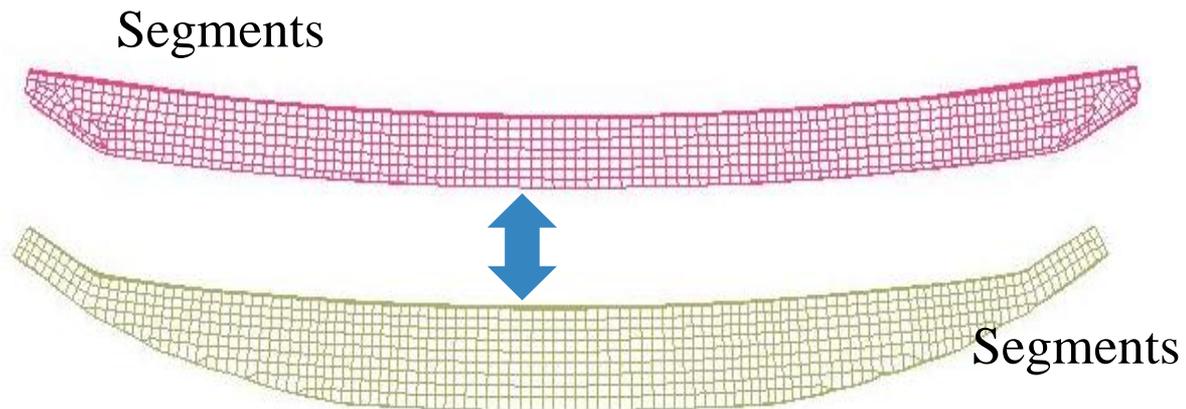
# Contacts

---

- Nodes/Segments based, Soft=0/1



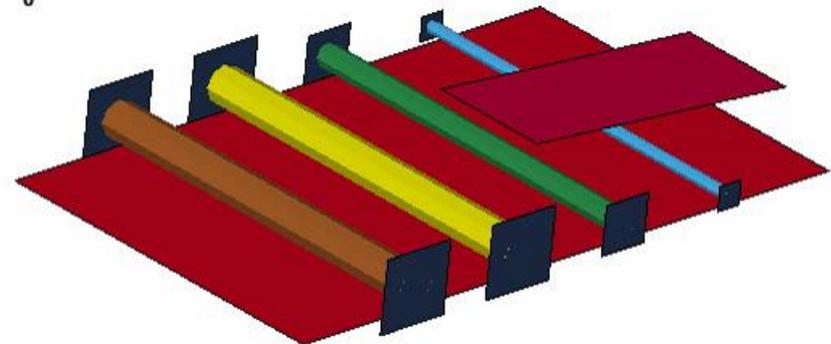
- Segments/Segments based, Soft=2, Mortar



# Mortar Contact for Lagrangian/Classical FEM

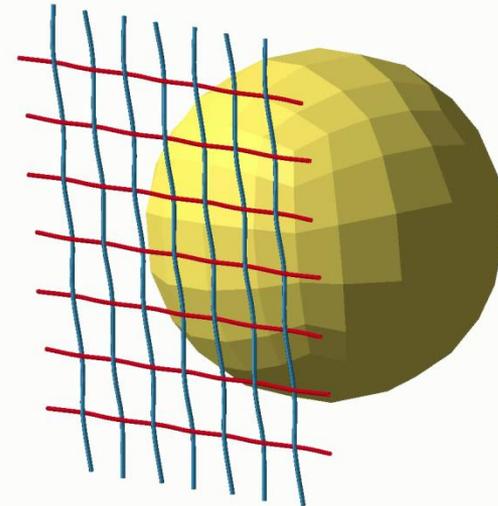
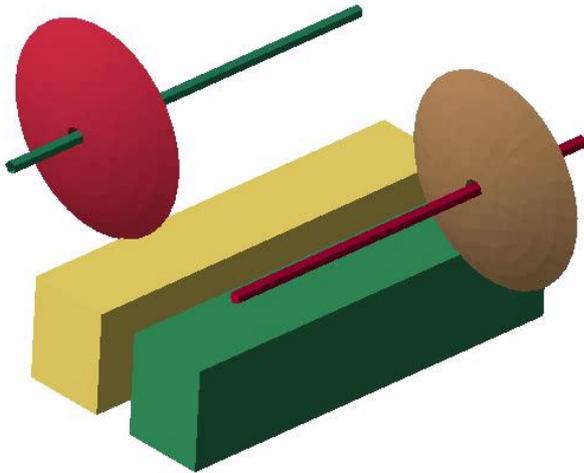
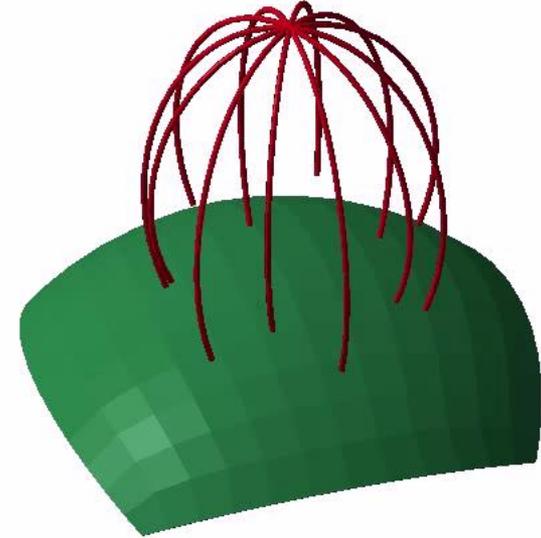
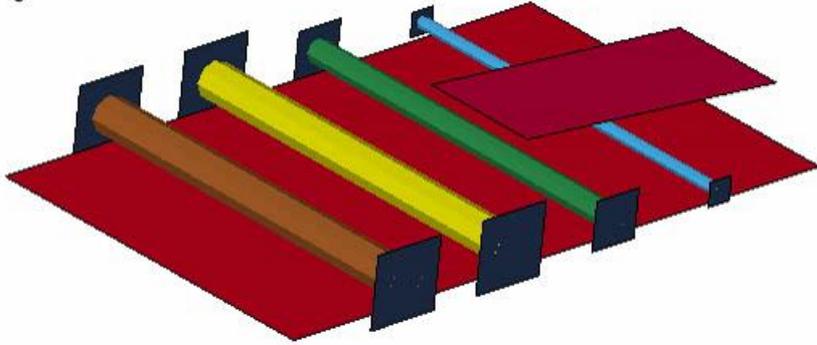
- M.A.Puso and T.A.Laurson, A mortar segment-to-segment contact method for large deformation solid mechanics, *Comput. Methods Appl. Mech. Engrg.* 193 (2004)
- Goal to make it simple and universal with minimal options
  - Additional CPU time for increased accuracy
- Features
  - Segment to Segment with Accurate Contact Stress Integration
  - Physical Geometry Contact
    - Flat edges on shells
    - Beams are cylinders with flat ends
    - Couples to rotations for beams to exert moments
    - Contact with sharp edges on solids and thick shells
  - Friction
    - Table, part and dynamic friction
    - Wear prediction
- Ongoing improvements
  - High Order Element support
  - Bucket sort frequency

LS-DYNA keyword deck by LS-PrePost  
Time = 0

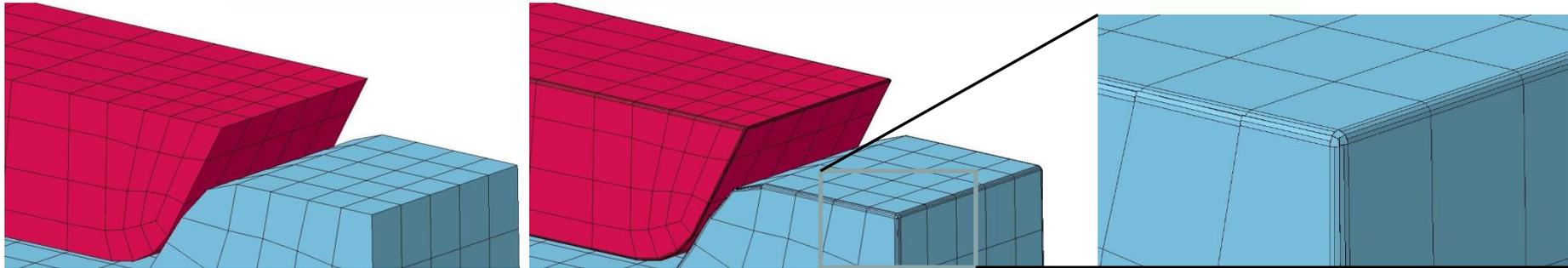
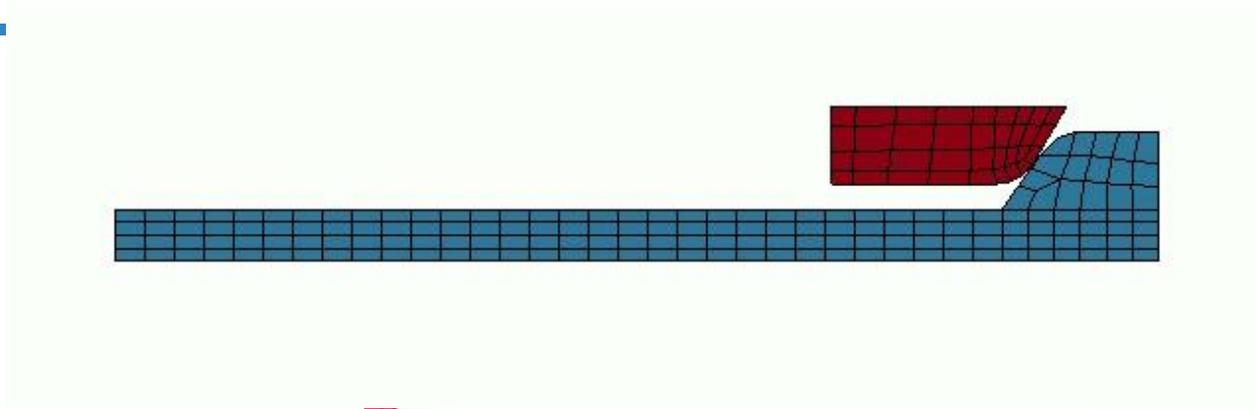


# Implicit Examples

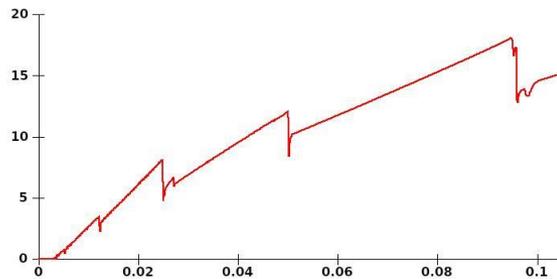
LS-DYNA keyword deck by LS-PrePost  
Time = 0



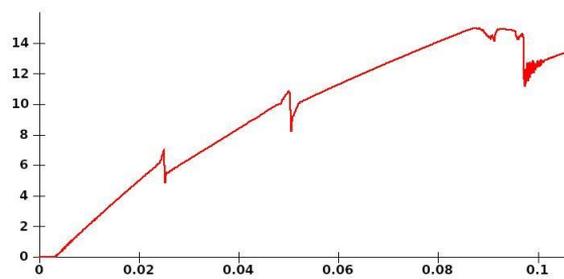
# Mortar Contact - Solids



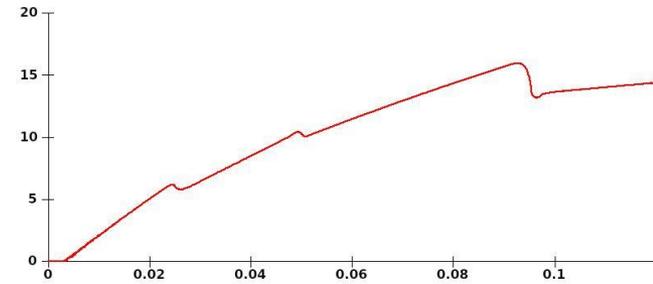
Mortar contact creates internal contact segments to deal with edges



$SOFT=0 / 1$



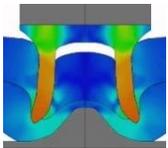
$SOFT=2$



$MORTAR$

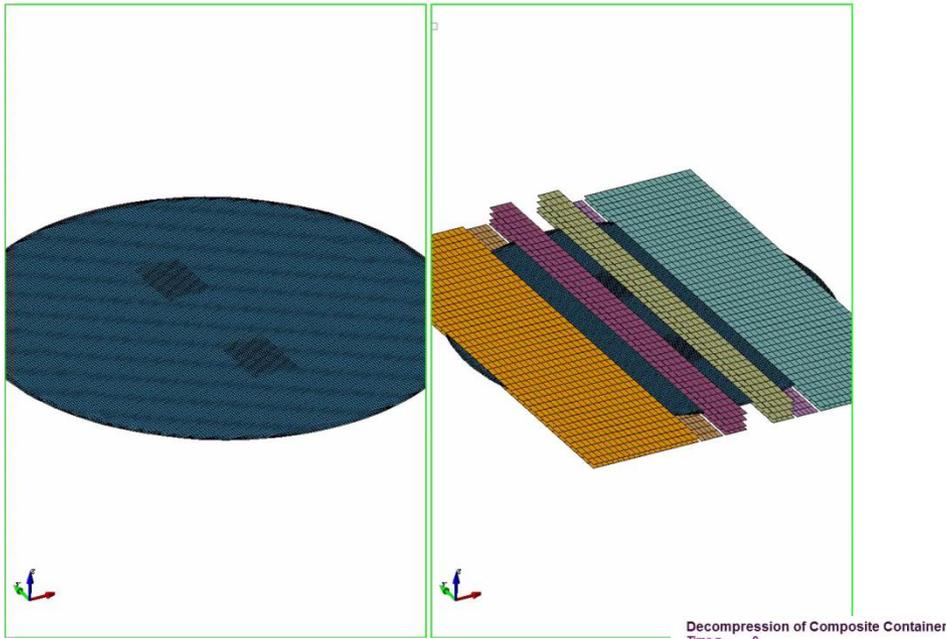
# Current State for Explicit Analysis

- The same contact regardless of analysis type or version
  - SMP and MPP the same
  - Implicit and Explicit the same
  - Excellent for Implicit/Explicit switch
- Explicit is supported by means of providing an alternative to well established contacts when
  - Contact results are of importance
    - Pressure distribution and friction response
  - Other contacts go unstable

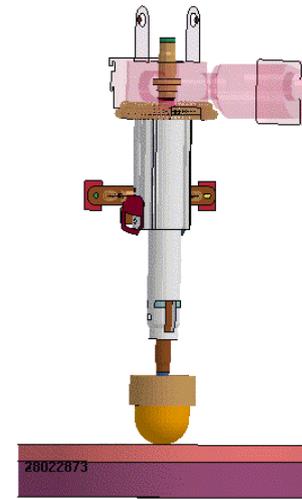


Problem	SOFT=0/1	SOFT=2	MORTAR
SPR detachment (24 cores, MPP single)	1.13	1.00	1.89
B-pillar bend (8 cores, MPP single)	1.13	1.00	2.32

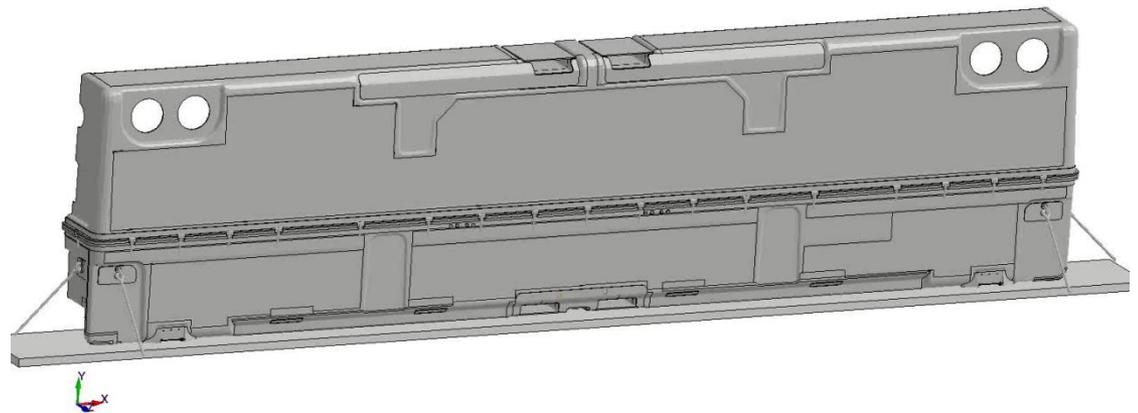
# Explicit Examples



Time = 0



*Jensen et al,  
"Broad-Spectrum Stress and  
Vibration Analysis of Large  
Composite Container"*



# Electromagnetics

Pierre L'Eplattenier, Iñaki Çaldichoury, Sarah Bateau-Meyer

# Battery - Introduction

Vehicle



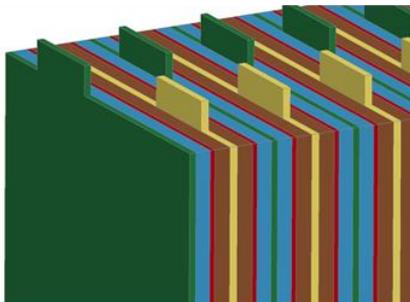
Dual-Packs



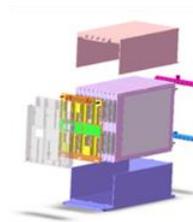
Cell



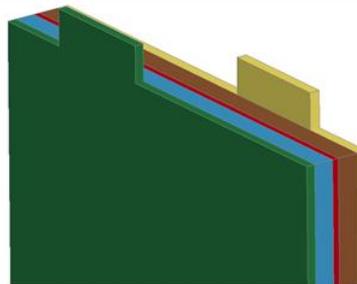
Cell (zoomed in z)



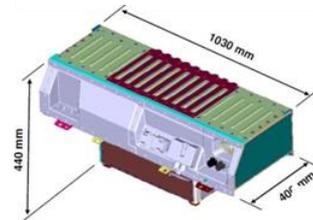
Module



Unit cell (zoomed in z)



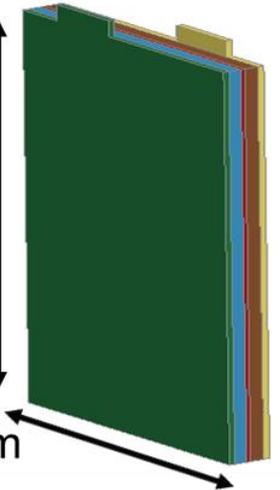
Pack



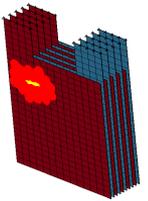
180μm

20cm

15cm

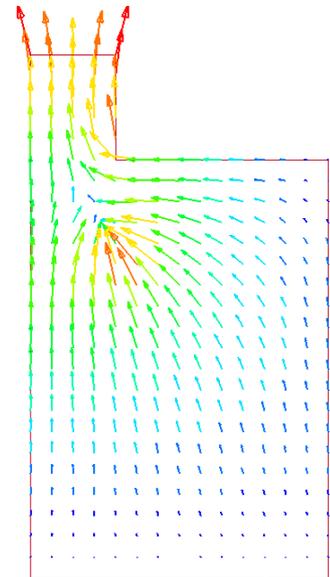
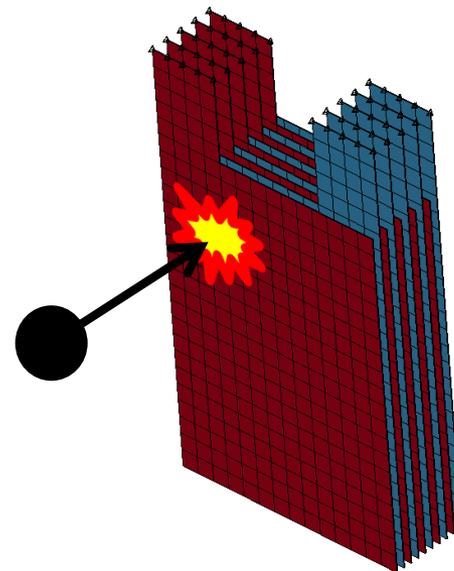
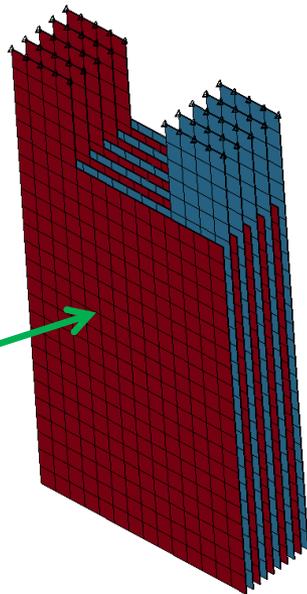


# New battery module :



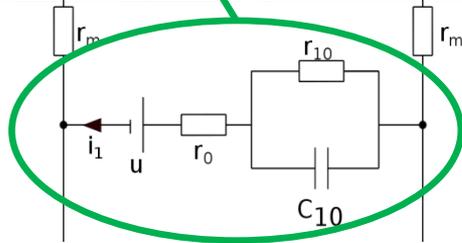
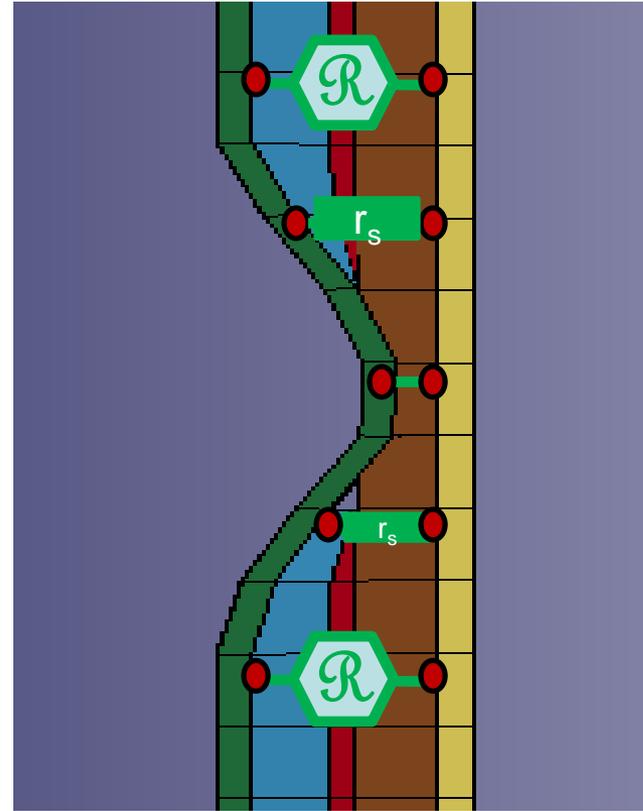
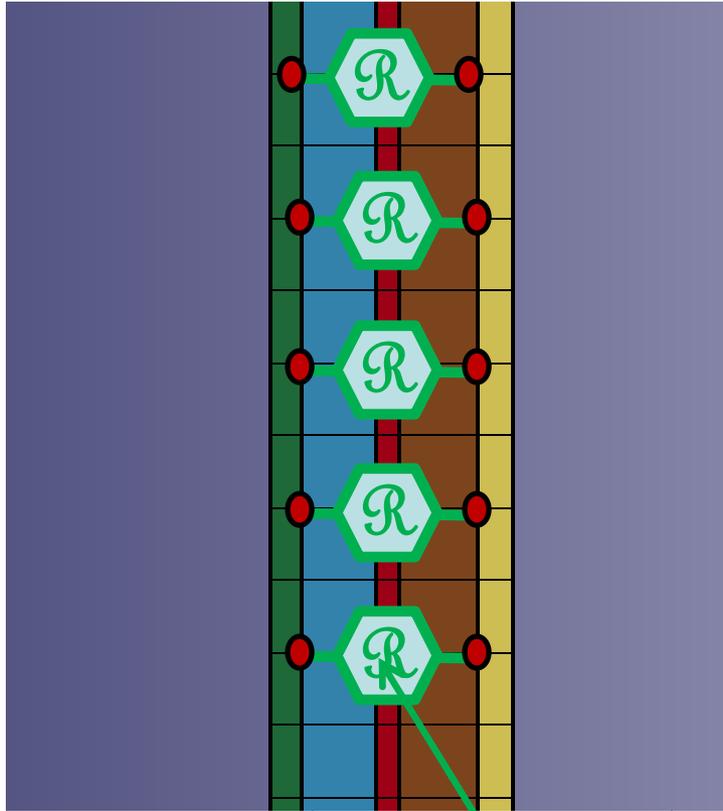
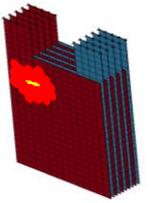
New capabilities are being developed within the EM module in order to simulate short circuits in batteries. The final objective is to be able to predict the combined structural, electrical, electrochemical, and thermal (EET) responses of automotive batteries to crash-induced crush and short circuit, overcharge, and thermal ramp, and validate it for conditions relevant to automotive crash.

## Lithium-Ion cell



In collaboration with  
J. Marcicki et al,  
Ford Research and Innovation Center, Dearborn, MI

# Short-circuit simulation :



Replace Randle circuit by  
resistance  $R_s$

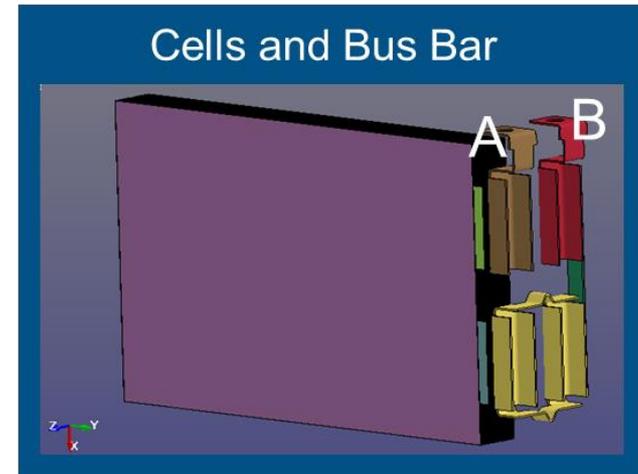
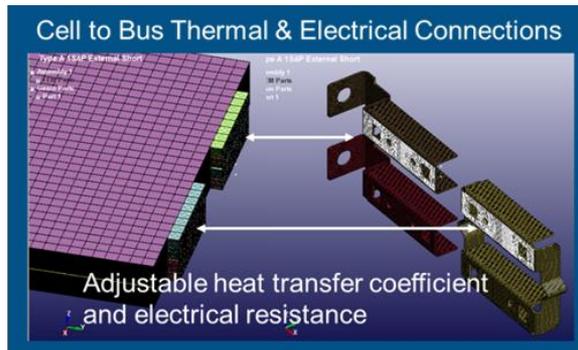
$R_s \times i^2$  added to thermal



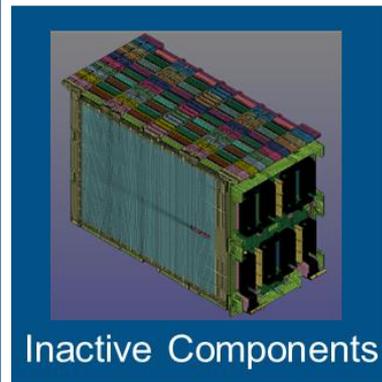
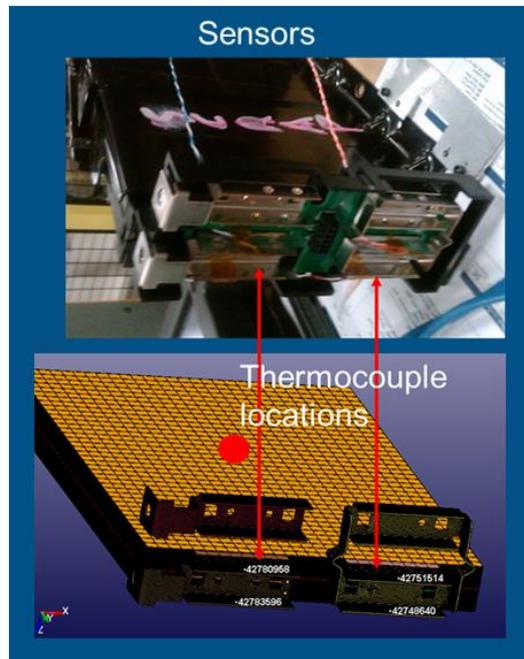
**ONE FORD**  
ONE TEAM • ONE PLAN • ONE GOAL

# Battery – External short (1)

## External short on a cell module



*Short circuit resistance applied between A and B creates current pathway*

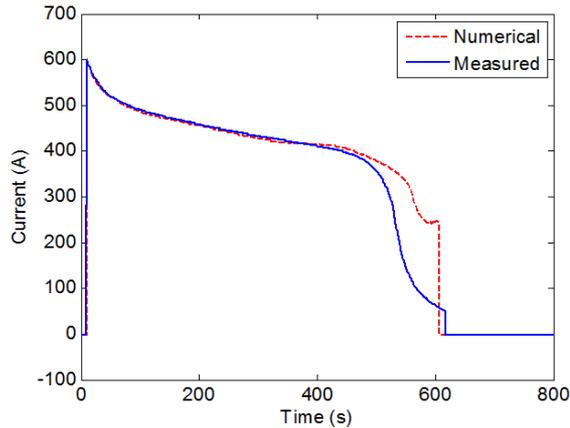


In collaboration with J. Marcicki et al  
Ford Research and Innovation Center,  
Dearborn, MI, USA

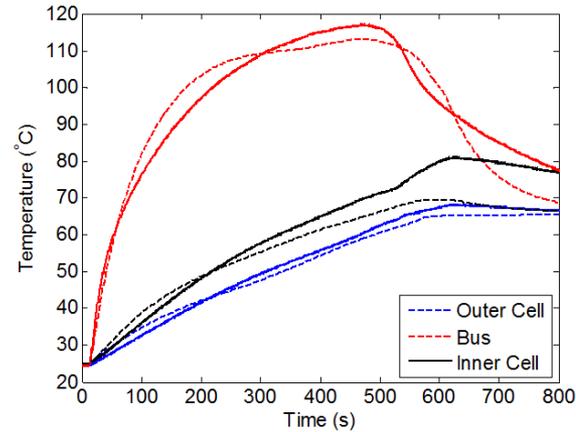


# Battery – Exp. vs Num. temperature elevation at different locations

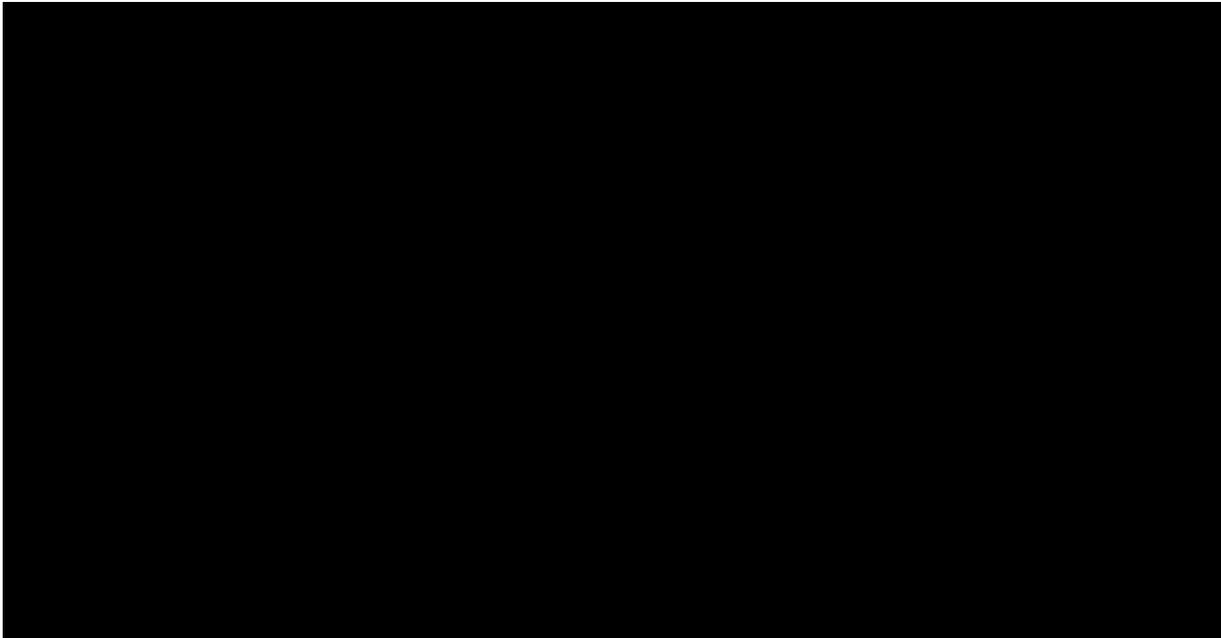
Model Predicted Current versus Experiment



Model Predicted (Dashed) Temperatures versus Experiment (Solid)

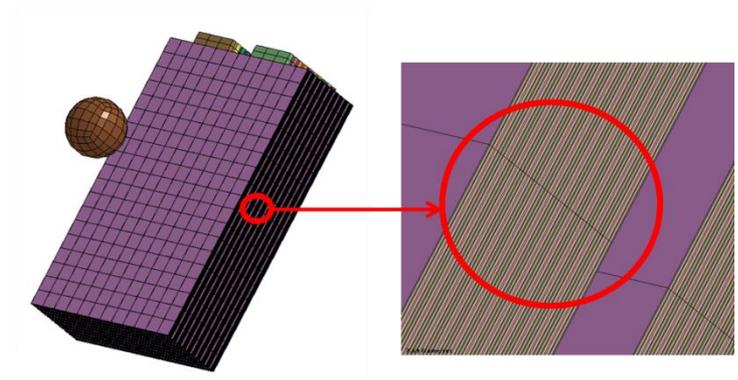
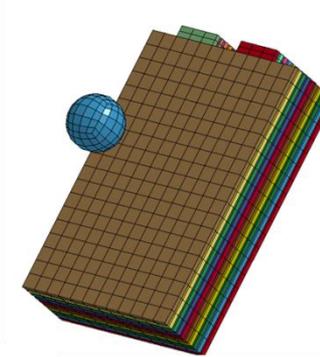


In collaboration  
with J. Marcicki  
et al  
Ford Research  
and Innovation  
Center,  
Dearborn, MI,  
USA



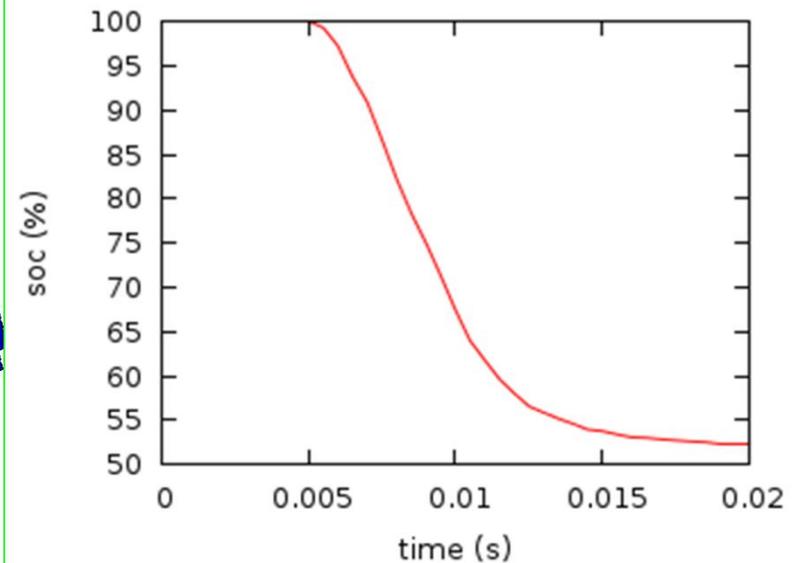
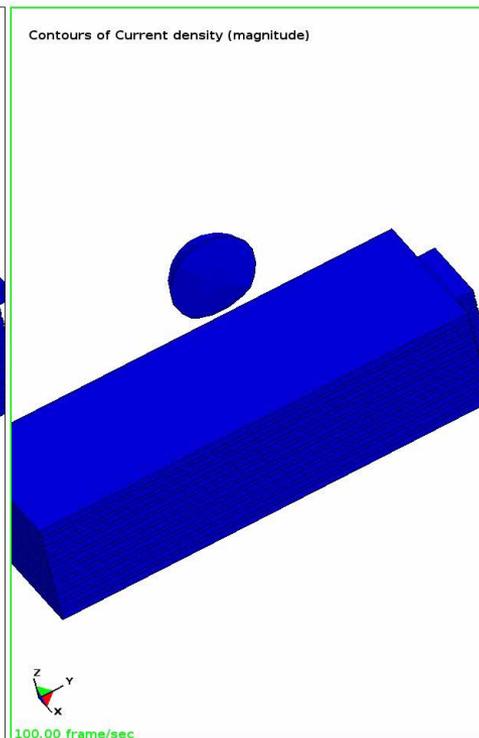
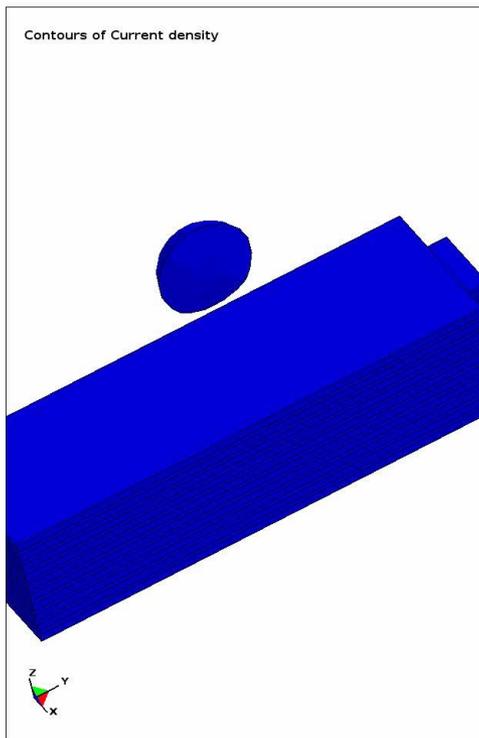
# Battery – Internal short (1)

10 cells module crushed by a sphere using Composite Tshells



Potential

Current density



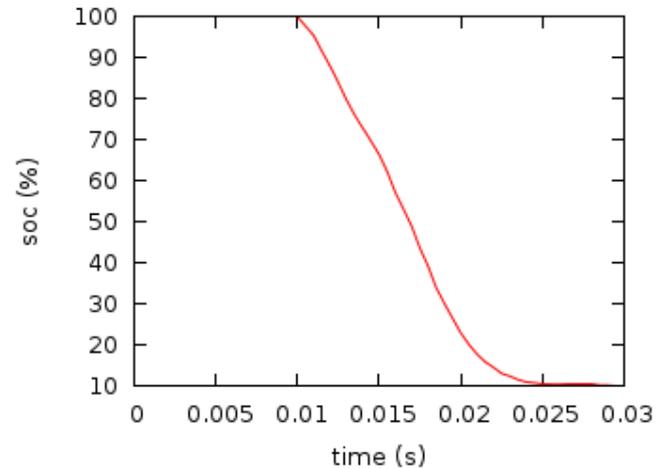
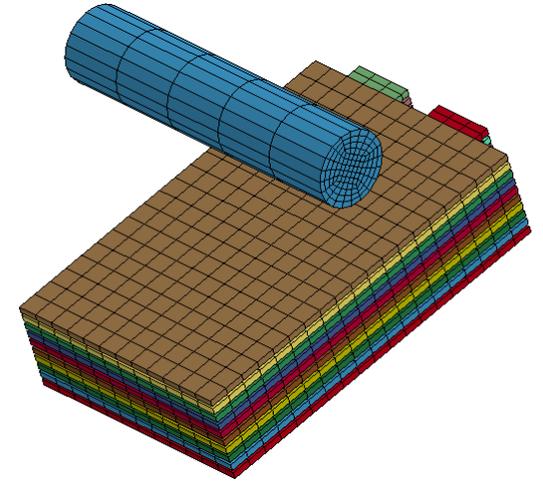
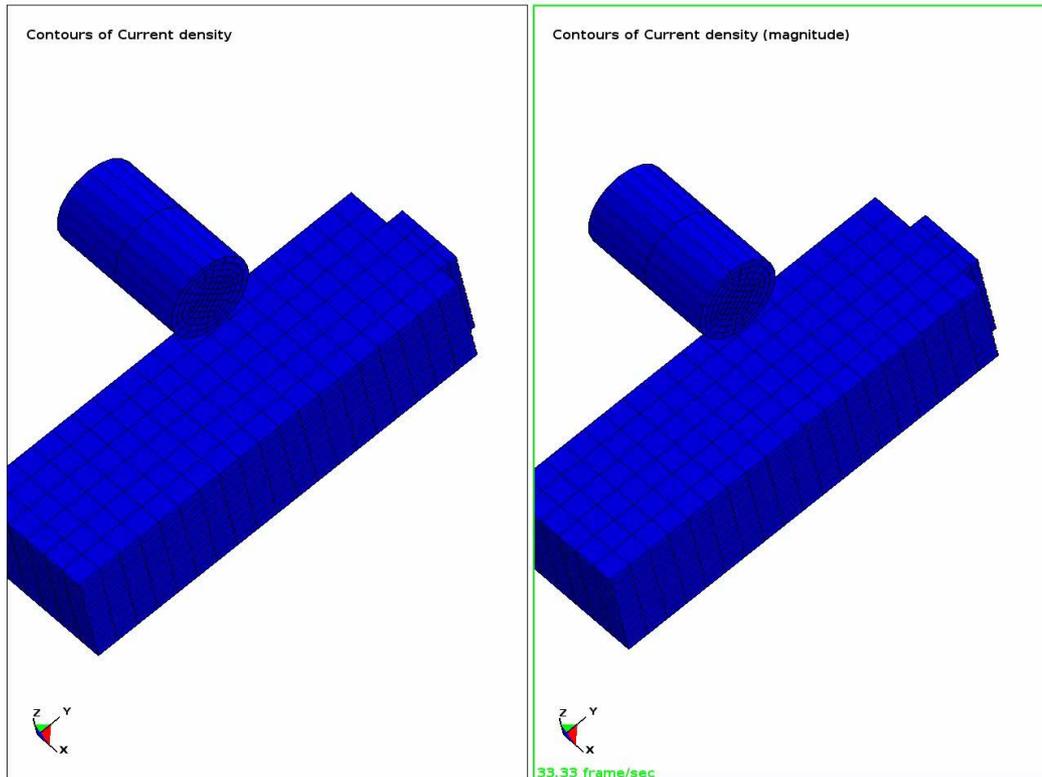
State Of Charge vs time

# Battery – Internal short (2)

10 cells module crushed  
by a cylinder using  
Composite Tshells

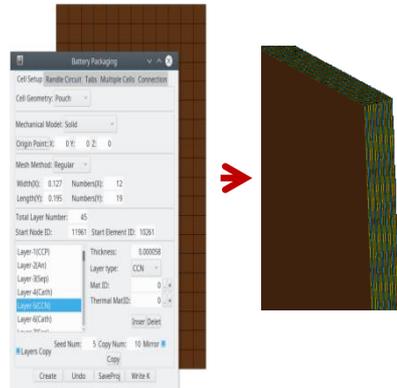
Potential

Current density



State Of Charge vs time

# LS-PREPOST Battery Packaging Application

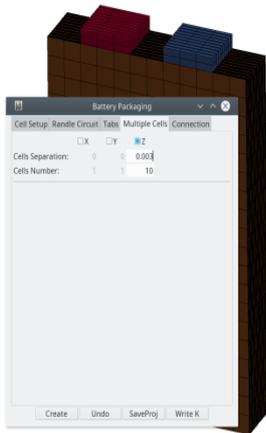


a

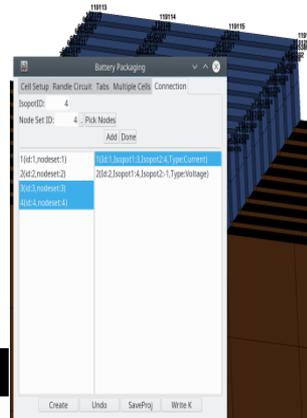


b

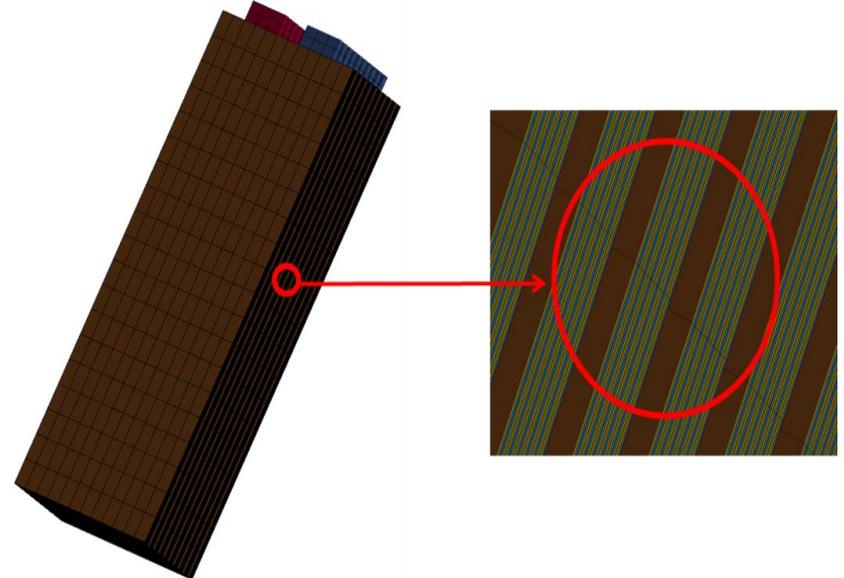
- Easy design of the layers of a single cell
- Addition of connecting tabs
- Multiplication of cells to create modules
- Electrical connections



c



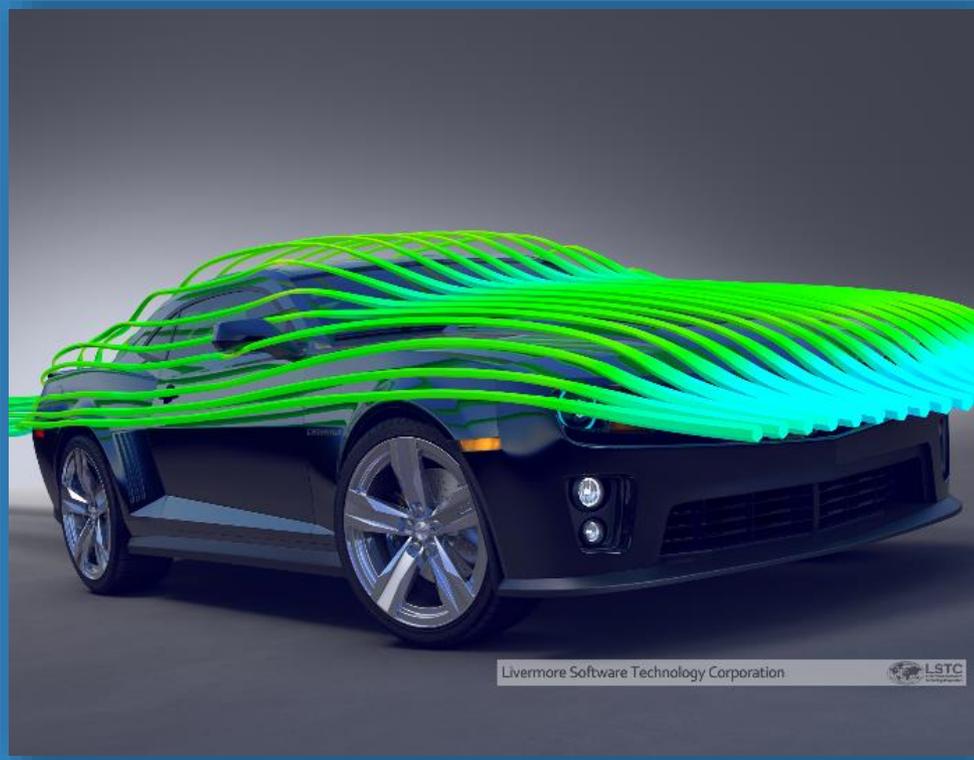
d



# Battery – Plans for the future

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- Collaborations with Ford Research and Innovation Center and Oak Ridge National Labs to improve:
  - Mechanical simulations of layered cells
  - Criteria for onset of internal short circuits
  - Setting of internal short resistance
- Development of more macroscopic models for modules and packs
- Addition of new features in LS-PREPOST battery packaging application



# Incompressible CFD (ICFD)

Facundo Del Pin

# ICFD

## CFD solver through revisions

R7

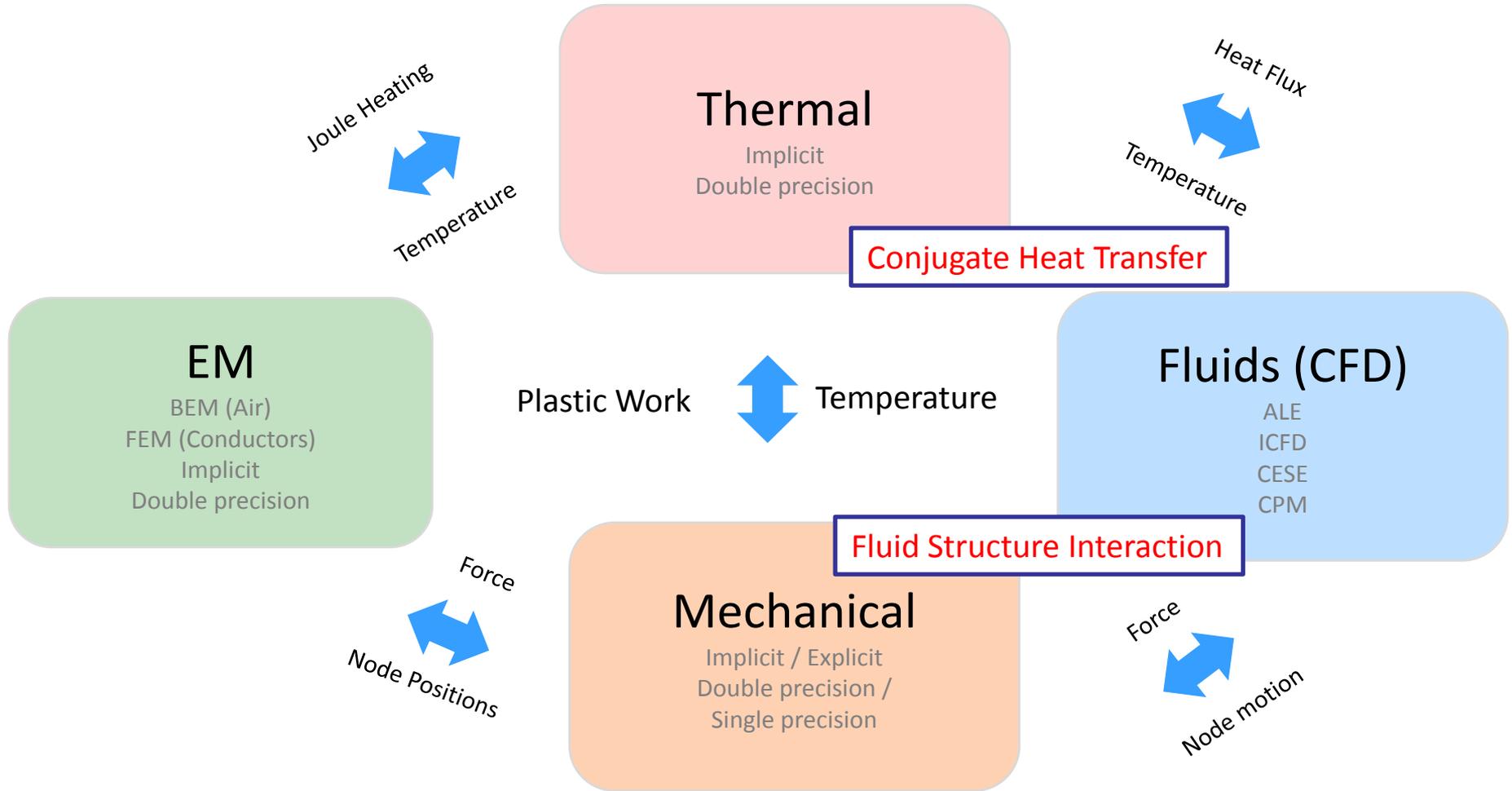
R10

New turbulence models including k-e, k-w, relizable k-e, Spalart-

- Steady state analysis coupled to thermal and FSI.
- Generalized flow in porous media on fabric material for parachute simulation and deformable structures.
- Improvements in RANS turbulence models and addition of new models.
- User control over automatic boundary layer mesh generation.
- Improvements on FSI accuracy and stability.
- LSPP new pre processing GUI.

- Several new control and database options.
- Non-inertial reference frames

# ICFD



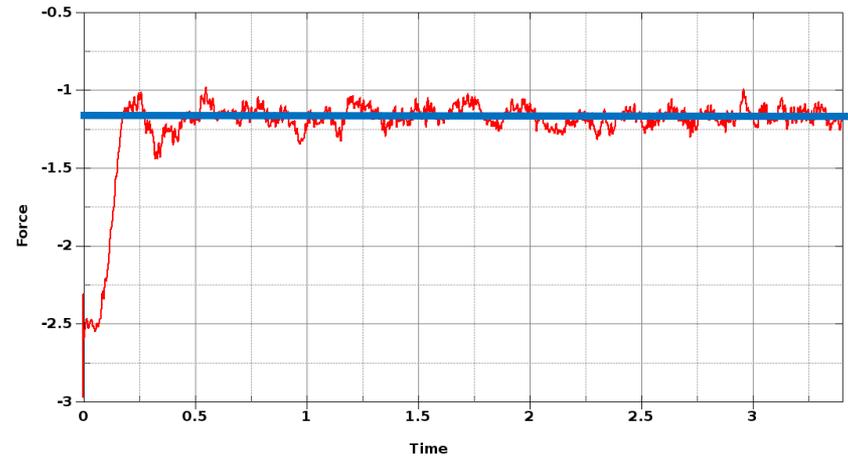
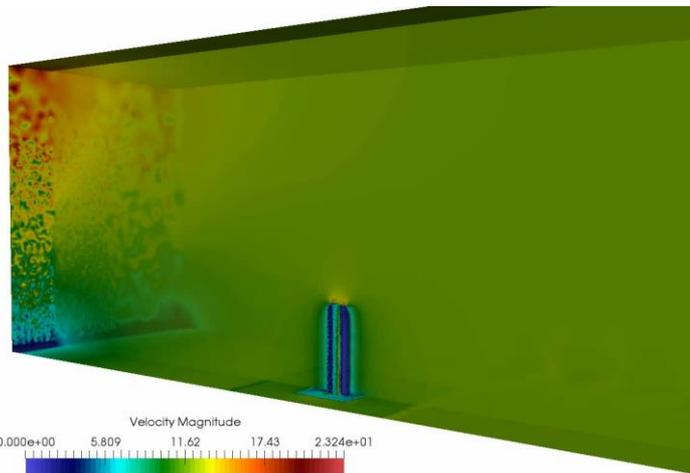
CAE consolidation without co-simulation

# ICFD R10

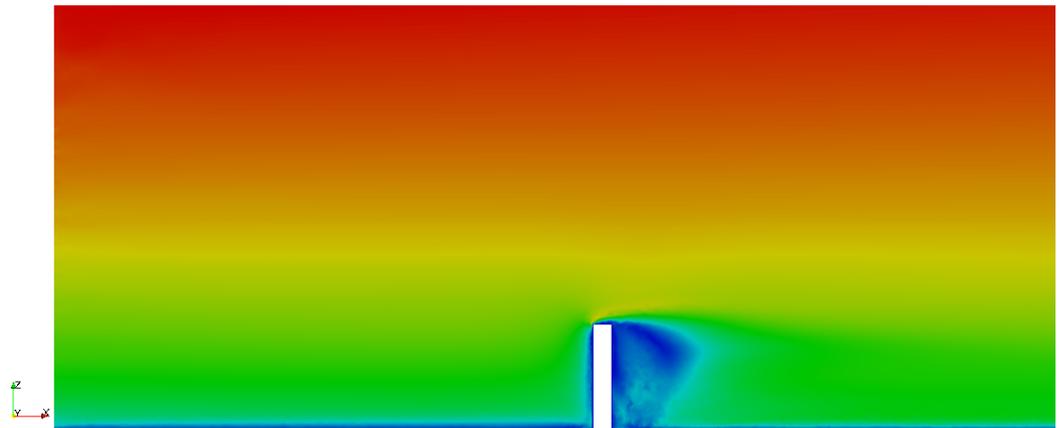
## Steady state analysis

Most engineering applications are transient.

Some times engineers do not need the instantaneous transient fluctuations of the force but a time average value.



Steady state analysis allows engineers to study physical problems in a time average fashion.



# ICFD

## RANS turbulence models

Most commonly encountered RANS Turbulence models are present :

- Turbulent models with High Re number wall treatment : Standard K-Epsilon, Realizable K-Epsilon, Wilcox K-Omega
- Turbulent models with Low Re wall treatment : Menter SST, Spalart-Allmaras

These models can be either used in conjunction with the transient solver or the steady state solver.

Backward facing step problem :

Velocity



Turbulent Kinetic energy



# ICFD

## Generalized Anisotropic Flow Through Deforming Porous Media and Deforming Solids

### ICFD-LSDYNA User Interface:

New Anisotropic Porous Media flow model (**PM model ID=9**): The model reads the solid mesh and the state field and maps elemental permeability tensors and solid displacements to the fluid mesh

```
*ICFD_MODEL_POROUS
$ material ID=2, porous media model ID=9
2,9
$porosity, Forchheimer factor, nstepsolid, solidts, file-
basename
1.,0.1,8,0.02,solidst_
```

where:

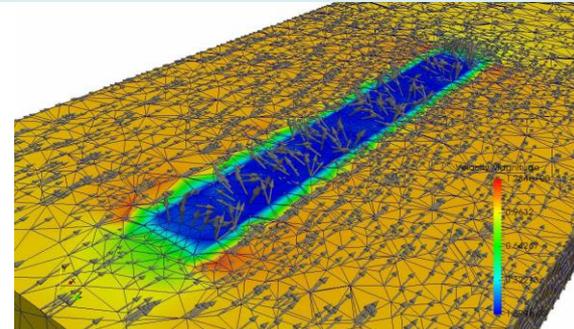
**nstepsolid**: number of time steps for the solidproblem  
(number of files with solid state data),  
**solidts**: time step for the solid problem (fluid time  
step<=solidts),  
**file basename**: filename pattern for solid state.

### Deforming Solid Problem Definition:

- Structural solver computes permeability tensor and stores it in a file
- The LSDYNA file format loaded by the ICFD solver is:

```
*NODE
1 0.0 0.0 0.0
2 0.0 0.0 0.5
...
*ELEMENT_SOLID
1 1 6 96 98 33 53 99 179 119
...
*INITIAL_STRESS_SOLID
$for each solid/hexa element (we only used  $K_{i,j}$ )
1 1 9 1 0 0 0
0.0 0.0 0.0 0.0 0.0
0.0 0.0 K11 K12 K13
K21 K22 K23 K31 K32
K33
...
```

Linear interpolation between time steps for mesh displacements and permeabilities  
if  $\Delta t_{\text{fluid}} < \Delta t_{\text{solid}}$



# ICFD

## Parachute modeling in CFD Porous Media Solver: an FSI approach

```
*MAT_FABRIC
```

```
$ mid      ro      ea      eb      ec      prba      prca      prcb
      4 533.772 4.3090E+8 0.000 0.000 0.140000 0.000 0.000
```

```
*ICFD_MODEL_POROUS
```

```
$ material ID=2, PM ID=8
2,8
$ porosity, permeab, frabric thickness
1., 0.001, 0.005
```

```
*ICFD_CONTROL_FSI
```

```
$ two-way coupling
```

```
0
```

```
*ICFD_BOUNDARY_FSI
```

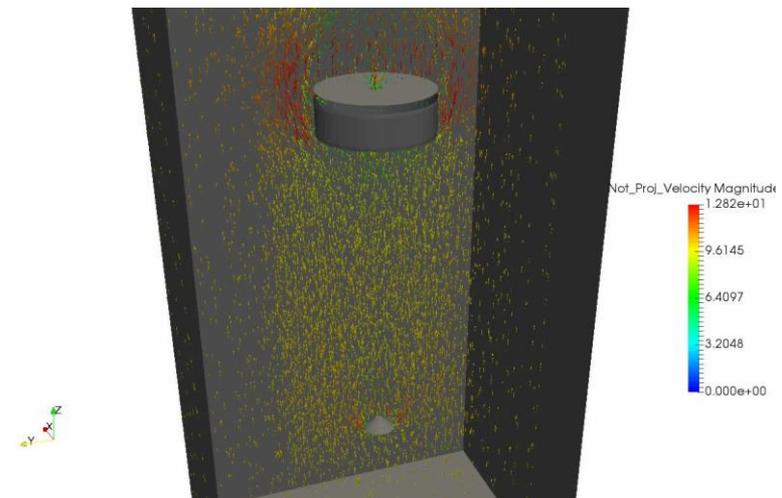
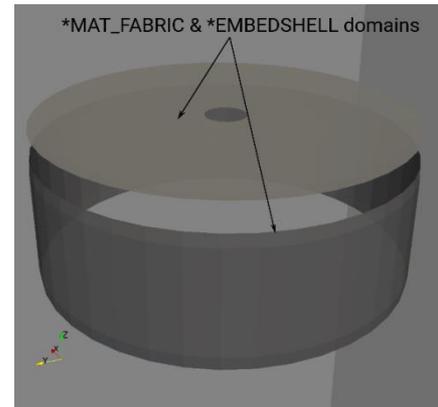
```
$PID's
```

```
4,5,6
```

```
*MESH_EMBEDSHELL
```

```
1
```

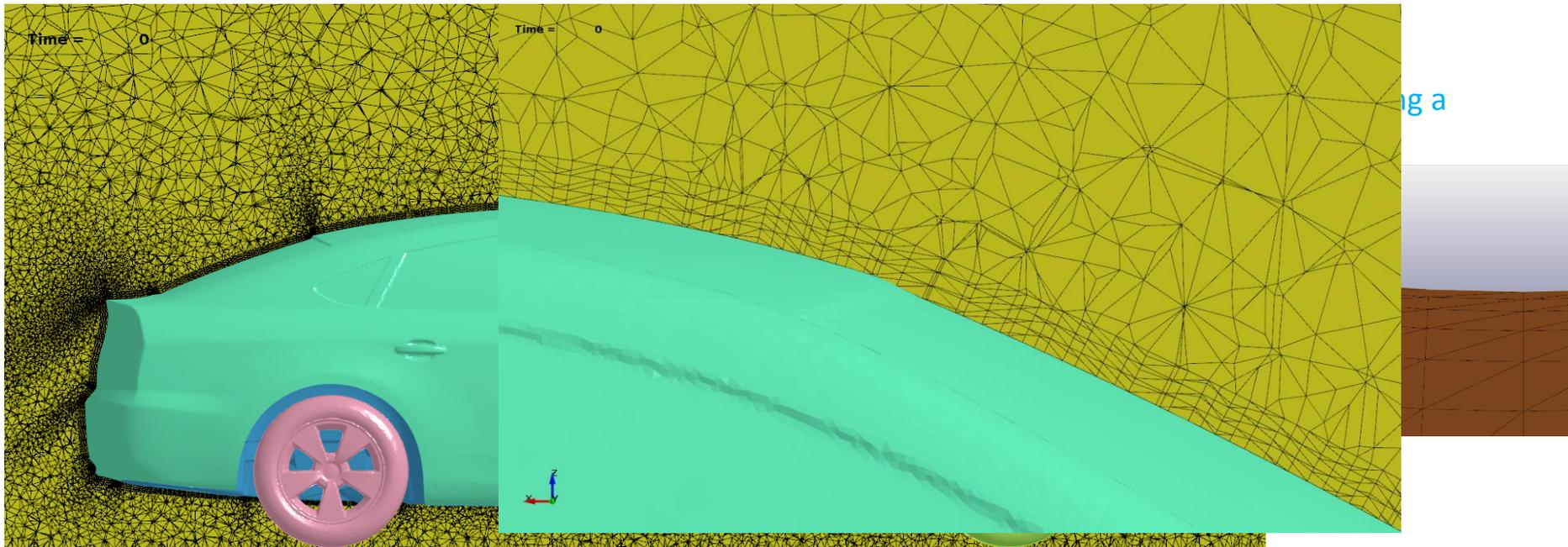
```
4, 5, 6
```



# ICFD

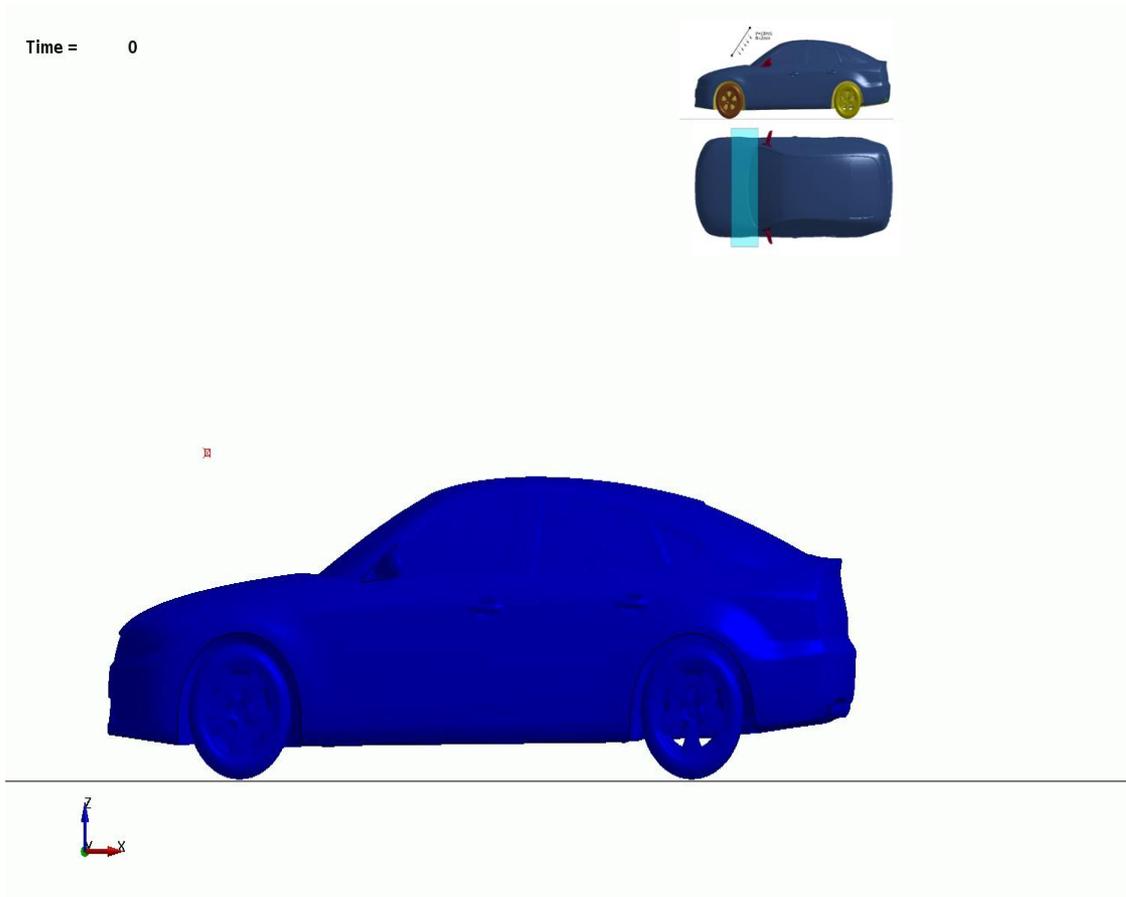
## User Control over boundary layer mesh

Users can control the size, height and distribution of elements in the boundary layer as well as position of the first volume node for more control of the  $y^+$ .

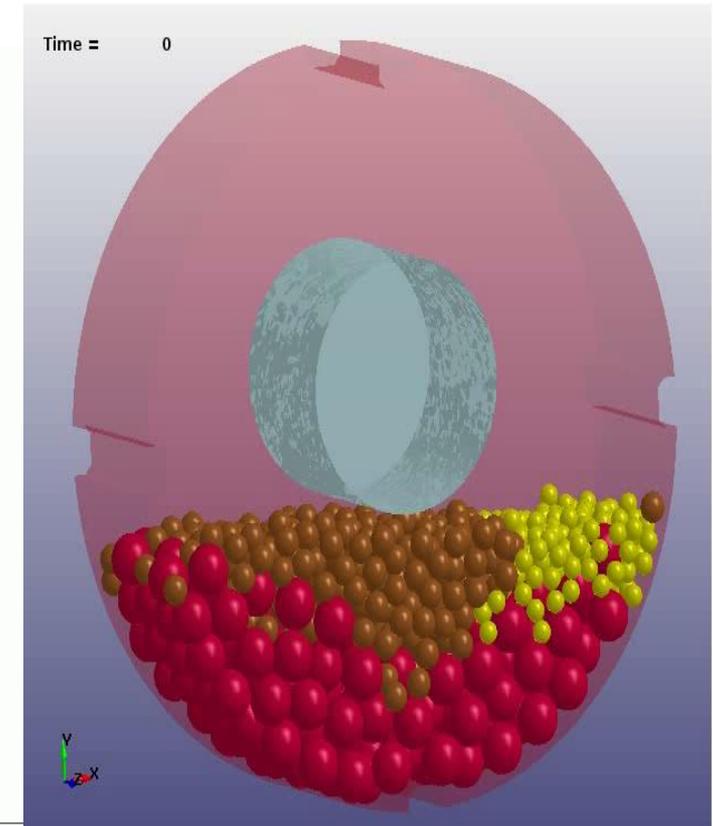


# ICFD – New Features for DEM Coupling

Two-way Coupling, Particles affect fluid volume

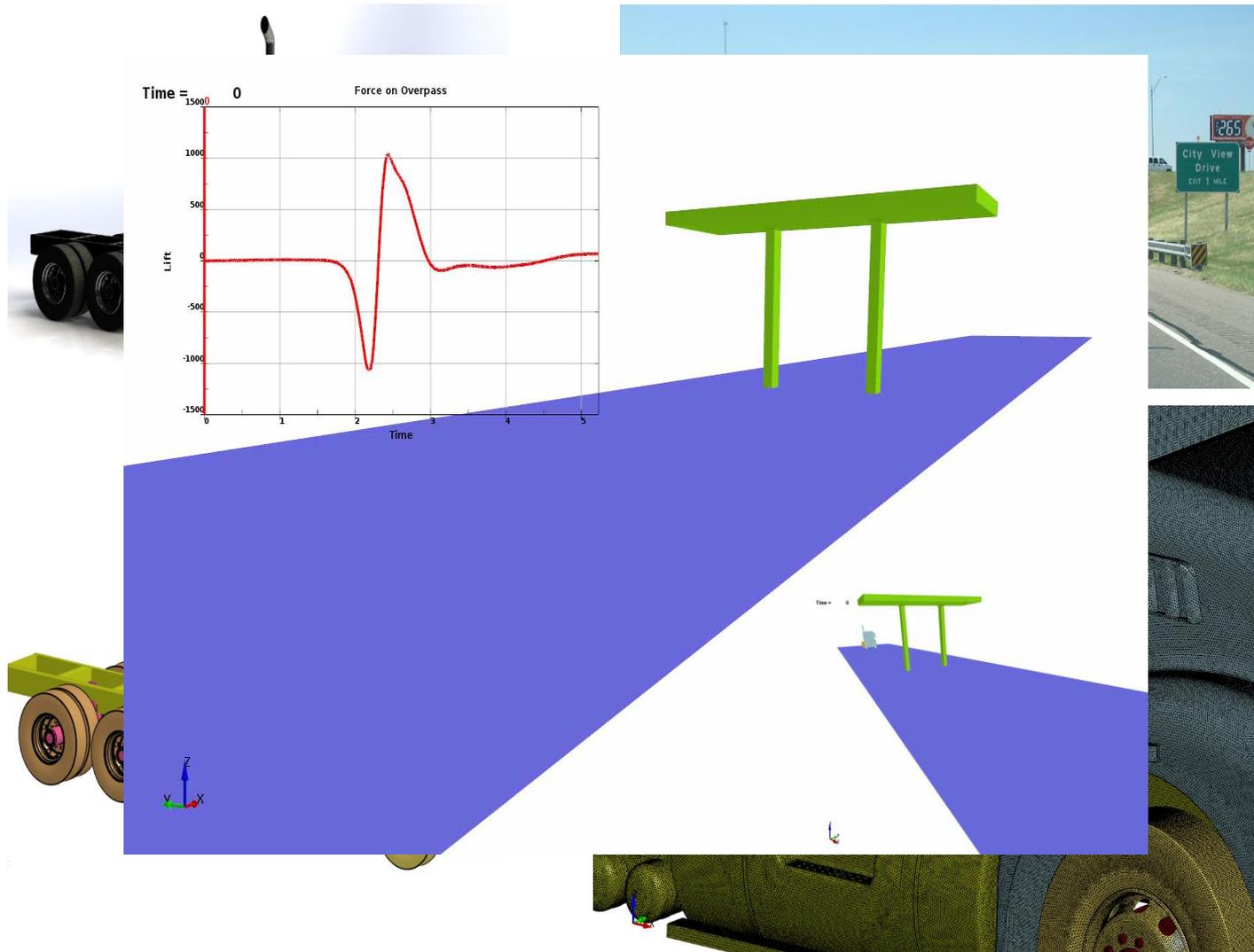


Water management: Rain Simulation



Courtesy of:  
Samuel Hammarberg,  
doktorand.  
Pär Jonsén, Professor.  
Göran Lindkvist, PhD.

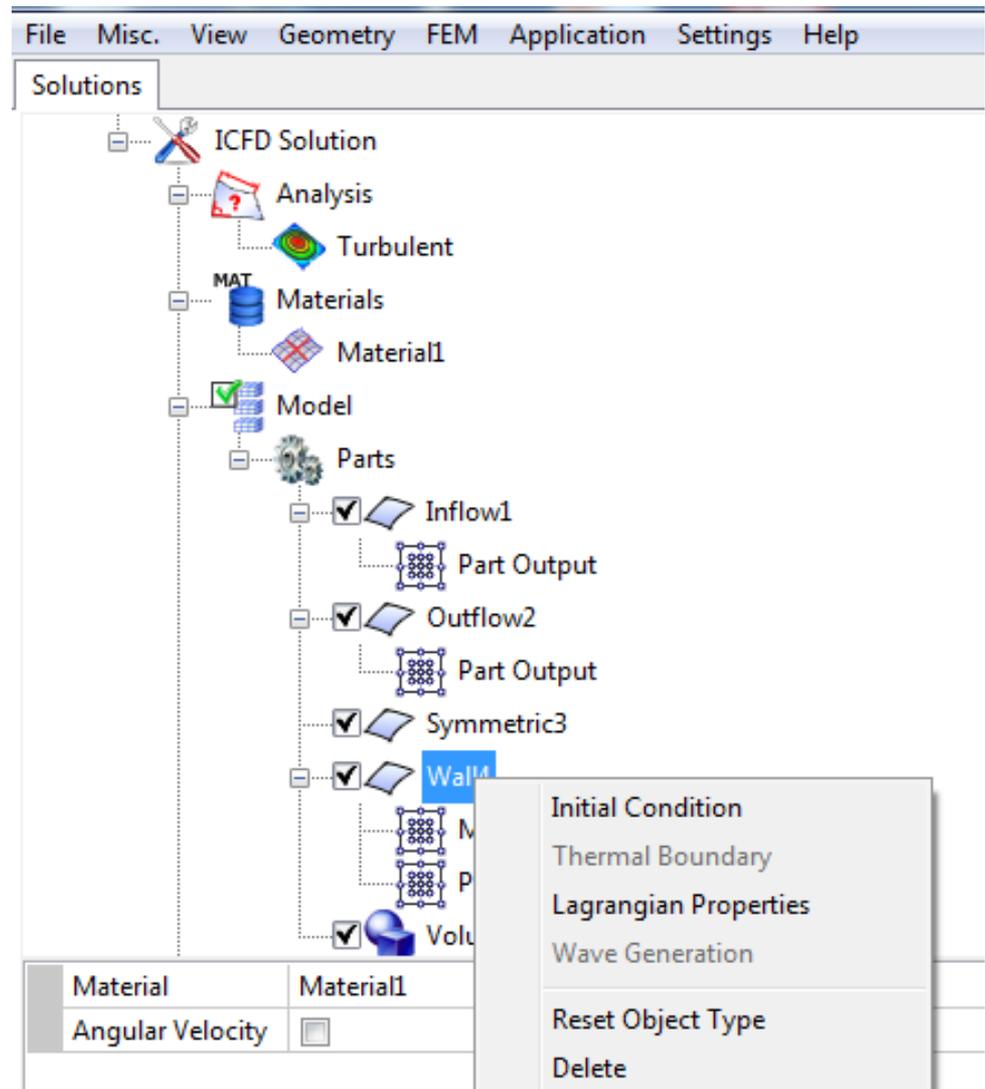
# ICFD – DEM for External Load Application



# ICFD

## LSPrePost 4.5: CFD pre-processing

- New GUI available in LSPP 4.5 for ICFD input deck set up.
- Tree Structure where user defines global analysis properties and part boundary conditions rather than keywords.
- More intuitive to use and offers more guidance to CFD analysts and engineers not familiar with LS-DYNA keyword format
- Could be extended to other LS-DYNA modules in the future (implicit, thermal, electromagnetics etc)



# Future

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- New features and algorithms will be continuously implemented to handle new challenges and applications
  - Electromagnetics,
  - Acoustics,
  - Compressible and incompressible fluids
  - Isogeometric shell & solid elements, isogeometric contact algorithms
  - Discrete elements
  - Peridynamics
  - Simulation based airbag folding and THUMS dummy positioning
  - Control systems and links to 3<sup>rd</sup> party control systems software
  - Composite material manufacturing
  - Battery response in crashworthiness simulations
  - Sparse solver developments for scalability to huge # of cores
  - Multi-scale capabilities are under development

# Summary

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Our ultimate goal is to deliver one highly scalable software to replace the multiplicity of software products currently used for analysis in the engineering design process. *Only one model is needed and created.*

## Capabilities

Multi-physics and Multi-stage  
Structure + Fluid + EM + Heat Transfer  
Implicit + Explicit ....

Multi-scale  
Accurate failure predictions

Multi-formulations  
linear + nonlinear + peridynamics + ...

Thank You !